ANNA UNIVERSITY, CHENNAI
NON-AUTONOMOUS AFFILIATED COLLEGES
REGULATIONS 2023
CHOICE BASED CREDIT SYSTEM

B.E. ELECTRICAL AND ELECTRONICS ENGINEERING - (TRAINING INTEGRATED)

1. PROGRAMME EDUCATIONAL OBJECTIVES (PEOs):

I. Find employment in Core Electrical and Electronics Engineering and service sectors.
II. Get elevated to technical lead position and lead the organization competitively.
III. Enter into higher studies leading to post-graduate and research degrees.
Become consultant and provide solutions to the practical problems of core organization.
IV. Become an entrepreneur and be part of electrical and electronics product and service industries.

2. PROGRAMME OUTCOMES (POs):

After going through the four years of study, our Electrical and Electronics Engineering Graduates will exhibit ability to:

PO#	Graduate Attribute	Programme Outcome
1	Engineering knowledge	Apply knowledge of mathematics, basic science and engineering science.
2	Problem analysis	Identify, formulate and solve engineering problems.
3	Design/development of solutions	Design an electrical system or process to improve its performance, satisfying its constraints.
4	Conduct investigations of complex problems	Conduct experiments in electrical and electronics systems and interpret the data.
5	Modern tool usage	Apply various tools and techniques to improve the efficiency of the system.
6	The Engineer and society	Conduct themselves to uphold the professional and social obligations.
7	Environment and sustainability	Design the system with environment consciousness and sustainable development.
8	Ethics	Interacting industry, business and society in a professional and ethical manner.
9	Individual and team work	Function in a multidisciplinary team.
10	Communication	Proficiency in oral and written Communication.
11	Project management and finance	Implement COst effective and improved system.
12	Life-long learning	Continue professional development and learning as a life-long activity.

3. PROGRAM SPECIFIC OUTCOMES (PSOs):

On completion of Electrical and Electronics Engineering program, the student will have the following Program Specific Outcomes.

1. **Foundation of Electrical Engineering:** Ability to understand the principles and working of electrical components, circuits, systems and control that are forming a part of power generation, transmission, distribution, utilization, conservation and energy saving. Students can assess the power management, auditing, crisis and energy saving aspects.

2. **Foundation of Mathematical Concepts**: Ability to apply mathematical methodologies to solve problems related with electrical engineering using appropriate engineering tools and algorithms.

3. **Computing and Research Ability:** Ability to use knowledge in various domains to identify research gaps and hence to provide solution which leads to new ideas and innovations.

	COURSE CODE	PROGRAM OUTCOMES												PROGRAM SPECIFIC OUTCOMES		
		PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
I	Matrices and Calculus	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
	Electric Circuit Analysis	3	3	3	2.8	2		2	1				3	3	3	3
	Digital Logic Circuits	3	3	3	1	3			1				1	3		1
	Problem Solving and Python Programming	2	3	3	3	2	-	-	-	-	-	2	2	3	3	
	Problem Solving and Python Programming Laboratory	2	3	3	3	2	-	-	-	-	-	2	2	3	3	
II	Statistics and Numerical Methods	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
	Electromagnetic Fields	3	2	1	2			1.4	1				1	3	2	1
	Electron Devices and Circuits	2	2	3	2	2			1				1	3		1
	Environmental Sciences and Sustainability	2.8	1.8	1	1	-	2.2	2.4	-	-	-	-	1.8	-	-	-
	Basic Electronics and Electrical Circuits Laboratory	-	3	2.7	3	3			1.5			3			3	
III	Electrical Machines - I	3	3	1	1	1			1				1	3	3	3
	Linear Integrated Circuits	2	2	3	2	2			1				1	3	2	1
	C Programming and Data Structures	3	2.33	2.5	2.2	2.25	2.33	-	1	1	1	-	1.5	-	-	-
	Linear and Digital Circuits Laboratory		3	1.6	3	3			1.5			3	3	2	1	2
	C Programming and Data Structures Laboratory	2	-	1.2	-	3	2	-	2	3	3	-	3	-	-	-
IV	Electrical Machines - II	3	3	1.6	2.3	2.6			1					3	3	2
	Transmission and Distribution	2.8	1.8	1	1		1	-	1.8					3	2.4	1
	Microprocessor and Microcontroller	2	1	2	3				1				3	3	1	3
	Electrical Machines Laboratory	3	3	1	1				1.5	1			2.8	3	3	1.6
	Microprocessor and Microcontroller laboratory	2	1	2	3				1.5				3	3	1	3
V	Power System Analysis	3	2.6	2.4	1.8	1.4				1			1	1	1	1.4
	Measurements and Instrumentation	3	2	3	2	3	2		2		3		3	3	3	3
	Control Systems	3	3	3	3	3			1				3	3	3	3

	Control and Instrumentation Laboratory	3	3	3	3	3			1.5				2	3	3	3
VI	Power Electronics	3	3	3	3			1.5	1			2.25	3	3	3	3
	Protection and Switchgear	3	1	1	2	1.2	2	1	1	1	1	2		3	1.4	1
	Power System Operation and Control	2	1.6	1	1		1		1.6		2		2	3	2.2	2.86
	Power Electronics Laboratory	3	3	3	3	3			1.5				3	3	3	3
VII	High Voltage Engineering	2	2	2.33	1		2		1	1		2	3	3	2	2
	Utilization and Conservation of Electrical Energy	2.2	2	2.6	1		1		1.5					3	3	2.5
	Electric Vehicle Architecture	3		2.2	3	3			1				2	3	3	3
VIII	Project Work	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3

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I TO VIII SEMESTERS CURRICULUM AND SYLLABUS

SEMESTER I

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIMA3101	Matrices and Calculus	BSC	3	1	0	4	4
2.	TIEE3101	Electric Circuit Analysis	PCC	3	1	0	4	4
3.	TIEE3102	Digital Logic Circuit	PCC	3	0	0	3	3
4.	TIEE3103	Problem Solving and Python Programming	ESC	3	0	0	3	3
PRACTICALS								
5.	TIEE3111	Problem Solving and Python Programming Laboratory	ESC	0	0	4	4	2
			TOTAL	**12**	**2**	**4**	**18**	**16**

SEMESTER II

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIMA3201	Statistics and Numerical Methods	BSC	3	1	0	4	4
2.	TIEE3201	Electromagnetic Fields	PCC	3	1	0	4	4
3.	TIEE3202	Electron Devices and Circuits	PCC	3	0	0	3	3
4.	TIEE3203	Environmental Science and Sustainability	BSC	2	0	0	2	2
PRACTICALS								
5.	TIEE3211	Basic Electronics and Electrical Circuits Laboratory	PCC	0	0	3	3	1.5
			TOTAL	**11**	**2**	**3**	**16**	**14.5**

SEMESTER III

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIEE3301	Electrical Machines I	PCC	3	0	0	3	3
2.	TIEE3302	Linear Integrated Circuits	PCC	3	0	0	3	3
3.	TIEE3303	C programming and Data Structures	PCC	3	0	0	3	3
PRACTICALS								
4.	TIEE3311	Linear and Digital Circuits Laboratory	PCC	0	0	3	3	1.5
5.	TIEE3312	C programming and Data Structures Laboratory	PCC	0	0	3	3	1.5
			TOTAL	**9**	**0**	**6**	**15**	**12**

SEMESTER IV

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIEE3401	Electrical Machines II	PCC	3	0	0	3	3
2.	TIEE3402	Transmission and Distribution	PCC	3	0	0	3	3
3.	TIEE3403	Microprocessor and Microcontroller	PCC	3	0	0	3	3
PRACTICALS								
4.	TIEE3411	Electrical Machines Laboratory	PCC	0	0	3	3	1.5
5.	TIEE3412	Microprocessor and Microcontroller Laboratory	PCC	0	0	3	3	1.5
			TOTAL	**9**	**0**	**6**	**15**	**12.0**

SEMESTER V

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIEE3501	Power System Analysis	PCC	3	0	0	3	3
2.	TIEE3502	Measurements and Instrumentation	PCC	3	0	0	3	3
3.	TIEE3503	Control Systems	PCC	3	0	0	3	3
4.		Professional Elective I	PEC	3	0	0	3	3
PRACTICALS								
5.	TIEE3511	Control and Instrumentation Laboratory	PCC	0	0	4	4	2
			TOTAL	**12**	**0**	**4**	**16**	**14**

SEMESTER VI

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIEE3601	Power Electronics	PCC	3	0	0	3	3
2.	TIEE3602	Protection and Switchgear	PCC	3	0	0	3	3
3.	TIEE3603	Power System Operation and Control	PCC	3	0	0	3	3
4.		Professional Elective II	PEC	3	0	0	3	3
PRACTICALS								
5.	TIEE3611	Power Electronics Laboratory	PCC	0	0	3	3	1.5
			TOTAL	**12**	**0**	**3**	**15**	**13.5**

SEMESTER VII

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	TIEE3701	High Voltage Engineering	PCC	3	0	0	3	3
2.	TIEE3702	Utilization and Conservation of Electrical Energy	PCC	3	0	0	3	3
3.	TIEE3703	Electric Vehicle Architecture	PCC	3	0	0	3	3
4.		Professional Elective III	PEC	3	0	0	3	3
5.		Professional Elective IV	PEC	3	0	0	3	3
			TOTAL	**15**	**0**	**0**	**15**	**15**

SEMESTER VIII

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.		Professional Elective V	PEC	3	0	0	3	3
2.		Professional Elective VI	PEC	3	0	0	3	3
3.		Elective- Management	HSMC	3	0	0	3	3
PRACTICALS								
4.	TIEE3811	Project Work	EEC	0	0	6	6	3
			TOTAL	**9**	**0**	**6**	**15**	**12**

TOTAL CREDITS RANGE: 109

ELECTIVE - MANAGEMENT COURSES

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIGE3801	Principles of Management		3	0	0	3	3
2.	TIGE3802	Total Quality Management		3	0	0	3	3
3.	TIGE3803	Engineering Economics and Financial Accounting		3	0	0	3	3
4.	TIGE3804	Human Resource Management		3	0	0	3	3
5.	TIGE3805	Knowledge Management		3	0	0	3	3
6.	TIGE3806	Industrial Management		3	0	0	3	3

PROFESSIONAL ELECTIVE COURSES :

Power Engineering	Converters and Drives	Embedded Systems	Electric Vehicle Technology	Advanced Control	Diversified Courses
Under Ground Cable Engineering	Special Electrical Machines	Embedded System Design	Design of Motor and Power Converters for Electric Vehicles	Process Modeling and Simulation	Energy Storage Systems
Substation Engineering and Substation Automation	Analysis of Electrical Machines	Embedded C-Programming	Electric Vehicle Design, Mechanics and Control	Computer Control of Processes	Hybrid Energy Technology
HVDC and FACTS	Multilevel Power Converters	Embedded Processors	Design of Electric Vehicle Charging System	System Identification	Design and Modelling of Renewable Energy Systems
Energy Management and Auditing	Electrical Drives	Embedded Control for Electric Drives	Testing of Electric Vehicles	Model Based Control	Grid integrating Techniques and Challenges
Power Quality	SMPS and UPS	Smart System Automation	Grid Integration of Electric Vehicles	Non Linear Control	Sustainable and Environmental Friendly HV Insulation System
Smart Grids	Power Electronics for Renewable Energy Systems	Embedded System for Automotive Applications.	Intelligent control of Electric Vehicles.	Optimal Control	Power System Transients
Restructured Power Market	Control of Power Electronics Circuits	VLSI Design		Adaptive Control	PLC Programming
	-	MEMS and NEMS	-	Machine Monitoring System	Big Data Analytics
-	-	Digital Signal Processing System Design	-	-	-

Registration of Professional Elective Courses:

Professional Elective Courses will be registered from Semester V onwards. These courses are listed in different groups that represent a particular area of specialisation / diversified group. Students are permitted to choose all the Professional Electives from a particular group or from different group. Further, only one Professional Elective course shall be chosen in a semester horizontally (row-wise). However, two courses are permitted from the same row, provided one course is enrolled in Semester V and another in semester VI.

Total number of professional elective courses per group may change in the each programme of study as 6 or 7 or 8. If there is shortage of courses in a group the same may be chosen from another group of the same programme.

PROFESSIONAL ELECTIVE COURSES

POWER ENGINEERING

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3001	Under Ground Cable Engineering	PEC	3	0	0	3	3
2.	TIEE3002	Substation Engineering and Automation	PEC	3	0	0	3	3
3.	TIEE3003	HVDC and FACTS	PEC	3	0	0	3	3
4.	TIEE3004	Energy Management and Auditing	PEC	3	0	0	3	3
5.	TIEE3005	Power Quality	PEC	3	0	0	3	3
6.	TIEE3006	Smart Grid	PEC	3	0	0	3	3
7.	TIEE3007	Restructured Power Market	PEC	3	0	0	3	3

CONVERTERS AND DRIVES

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3008	Special Electrical Machines	PEC	2	0	2	4	3
2.	TIEE3009	Analysis of Electrical Machines	PEC	2	0	2	4	3
3.	TIEE3010	Multilevel Power Converters	PEC	2	0	2	4	3
4.	TIEE3011	Electrical Drives	PEC	2	0	2	4	3
5.	TIEE3012	SMPS and UPS	PEC	2	0	2	4	3
6.	TIEE3013	Power Electronics for Renewable Energy Systems	PEC	2	0	2	4	3
7.	TIEE3014	Control of Power Electronics Circuits	PEC	2	0	2	4	3

EMBEDDED SYSTEMS

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3015	Embedded System Design	PEC	2	0	2	4	3
2.	TIEE3016	Embedded C-programming	PEC	2	0	2	4	3
3.	TIEE3017	Embedded Processors	PEC	2	0	2	4	3
4.	TIEE3018	Embedded Control for Electric Drives	PEC	2	0	2	4	3
5.	TIEE3019	Smart System Automation	PEC	2	0	2	4	3
6.	TIEE3020	Embedded System for Automotive Applications	PEC	2	0	2	4	3
7.	TIEE3021	VLSI Design	PEC	2	0	2	4	3
8.	TIEE3022	MEMS and NEMS	PEC	2	0	2	4	3
9.	TIEE3023	Digital Signal Processing System Design	PEC	2	0	2	4	3

ELECTRIC VEHICLE TECHNOLOGY

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3024	Design of Motor and Power Converters for Electric Vehicles	PEC	2	0	2	4	3
2.	TIEE3025	Electric Vehicle Design, Mechanics and Control	PEC	2	0	2	4	3
3.	TIEE3026	Design of Electric Vehicle Charging System	PEC	2	0	2	4	3
4.	TIEE3027	Testing of Electric Vehicles	PEC	2	0	2	4	3
5.	TIEE3028	Grid Integration of Electric Vehicles	PEC	3	0	0	3	3
6.	TIEE3029	Intelligent Control of Electric Vehicles	PEC	2	0	2	4	3

ADVANCED CONTROL

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3030	Process Modeling and Simulation	PEC	3	0	0	3	3
2.	TIEE3031	Computer Control of Processes	PEC	3	0	0	3	3
3.	TIEE3032	System Identification	PEC	3	0	0	3	3
4.	TIEE3033	Model Based Control	PEC	3	0	0	3	3
5.	TIEE3034	Non Linear Control	PEC	3	0	0	3	3
6.	TIEE3035	Optimal Control	PEC	3	0	0	3	3
7.	TIEE3036	Adaptive Control	PEC	3	0	0	3	3
8.	TIEE3037	Machine Monitoring System	PEC	3	0	0	3	3

DIVERSIFIED COURSES

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	TIEE3038	Energy Storage Systems	PEC	3	0	0	3	3
2.	TIEE3039	Hybrid Energy Technology	PEC	3	0	0	3	3
3.	TIEE3040	Design and Modeling of Renewable Energy Systems	PEC	3	0	0	3	3
4.	TIEE3041	Grid integrating Techniques and Challenges	PEC	2	0	2	4	3
5.	TIEE3042	Sustainable and Environmental Friendly HV Insulation System	PEC	3	0	0	3	3
6.	TIEE3043	Power System Transients	PEC	3	0	0	3	3
7.	TIEE3044	PLC Programming	PEC	3	0	0	3	3
8.	TIEE3045	Big Data Analytics	PEC	2	0	2	4	3

SUMMARY

SL. NO.	SUBJECT AREA	CREDITS PER SEMESTER								CREDITS TOTAL
		I	II	III	IV	V	VI	VII	VIII	
1.	HSMC								3	3
2.	BSC	4	6							10
3.	ESC	5								5
4.	PCC	7	8.5	12	12	11	10.5	9		70
5.	PEC					3	3	6	6	18
6.	OEC									0
7.	EEC								3	3
	Total	16	14.5	12	12	14	13.5	15	12	109

TIMA3101 **MATRICES AND CALCULUS** **L T P C**
3 1 0 4

OBJECTIVES :

- To develop the use of matrix algebra techniques that is needed by engineers for practical applications.
- To familiarize the students with differential calculus.
- To familiarize the student with functions of several variables. This is needed in many branches of engineering.
- To make the students understand various techniques of integration.
- To acquaint the student with mathematical tools needed in evaluating multiple integrals and their applications.

UNIT I MATRICES **9 + 3**

Eigenvalues and Eigenvectors of a real matrix – Characteristic equation – Properties of Eigenvalues and Eigenvectors – Cayley - Hamilton theorem – Diagonalization of matrices by orthogonal transformation – Reduction of a quadratic form to canonical form by orthogonal transformation – Nature of quadratic forms – Applications : Stretching of an elastic membrane.

UNIT II DIFFERENTIAL CALCULUS **9 + 3**

Representation of functions - Limit of a function - Continuity - Derivatives - Differentiation rules (sum, product, quotient, chain rules) - Implicit differentiation - Logarithmic differentiation - Applications : Maxima and Minima of functions of one variable.

UNIT III FUNCTIONS OF SEVERAL VARIABLES **9 + 3**

Partial differentiation – Homogeneous functions and Euler's theorem – Total derivative – Change of variables – Jacobians – Partial differentiation of implicit functions – Taylor's series for functions of two variables – Applications : Maxima and minima of functions of two variables and Lagrange's method of undetermined multipliers.

UNIT IV INTEGRAL CALCULUS **9 + 3**

Definite and Indefinite integrals - Substitution rule - Techniques of Integration : Integration by parts, Trigonometric integrals, Trigonometric substitutions, Integration of rational functions by partial fraction, Integration of irrational functions - Improper integrals - Applications : Hydrostatic force and pressure, moments and centres of mass.

UNIT V MULTIPLE INTEGRALS **9 + 3**

Double integrals – Change of order of integration – Double integrals in polar coordinates – Area enclosed by plane curves – Triple integrals – Volume of solids – Change of variables in double and triple integrals – Applications : Moments and centres of mass, moment of inertia.

TOTAL : 60 PERIODS

OUTCOMES :

At the end of the course the students will be able to

- Use the matrix algebra methods for solving practical problems.
- Apply differential calculus tools in solving various application problems.
- Able to use differential calculus ideas on several variable functions.
- Apply different methods of integration in solving practical problems.
- Apply multiple integral ideas in solving areas, volumes and other practical problems.

TEXT BOOKS :

1. Kreyszig.E, "Advanced Engineering Mathematics", John Wiley and Sons, 10th Edition, New Delhi, 2016.
2. Grewal.B.S., “Higher Engineering Mathematics”, Khanna Publishers, New Delhi, 44th Edition , 2018.
3. James Stewart, " Calculus : Early Transcendentals ", Cengage Learning, 8th Edition, New Delhi, 2015. [For Units II & IV - Sections 1.1, 2.2, 2.3, 2.5, 2.7 (Tangents problems only), 2.8, 3.1 to 3.6, 3.11, 4.1, 4.3, 5.1 (Area problems only), 5.2, 5.3, 5.4 (excluding net change theorem), 5.5, 7.1 - 7.4 and 7.8].

REFERENCES :

1. Anton. H, Bivens. I and Davis. S, " Calculus ", Wiley, 10th Edition, 2016
2. Bali. N., Goyal. M. and Watkins. C., “ Advanced Engineering Mathematics ”, Firewall Media (An imprint of Lakshmi Publications Pvt., Ltd.,), New Delhi, 7th Edition, 2009.
3. Jain . R.K. and Iyengar. S.R.K., “ Advanced Engineering Mathematics ”, Narosa Publications, New Delhi, 5th Edition, 2016.
4. Narayanan. S. and Manicavachagom Pillai. T. K., “ Calculus " Volume I and II, S. Viswanathan Publishers Pvt. Ltd., Chennai, 2009.
5. Ramana. B.V., " Higher Engineering Mathematics ", McGraw Hill Education Pvt. Ltd,New Delhi, 2016.
6. Srimantha Pal and Bhunia. S.C, " Engineering Mathematics " Oxford University Press, 2015.
7. Thomas. G. B., Hass. J, and Weir. M.D, " Thomas Calculus ", 14th Edition, Pearson India, 2018.

MAPPING OF COs WITH POs AND PSOs

	PO01	PO02	PO03	PO04	PO05	PO06	PO07	PO08	PO09	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
CO2	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
CO3	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
CO4	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
CO5	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-
Avg.	3	3	1	1	0	0	0	0	2	0	2	3	-	-	-

TIEE3101 **ELECTRIC CIRCUIT ANALYSIS** **L T P C**
3 1 0 4

OBJECTIVES:

- To introduce electric circuits and its analysis
- To provide key concepts to analyze and understand electrical circuits
- To impart knowledge on solving circuit equations using network theorems
- To educate on obtaining the transient response of circuits.
- To introduce the phenomenon of resonance in coupled circuits.
- To introduce Phasor diagrams and analysis of single &three phase circuits

UNIT I BASIC CIRCUITS ANALYSIS 9+3

Fundamentals concepts of R, L and C elements-Energy Sources- Ohm's Law -Kirchhoff 's Laws – DC Circuits – Resistors in series and parallel circuits - A.C Circuits – Average and RMS Value – Complex Impedance – Phasor diagram - Real and Reactive Power, Power Factor, Energy -Mesh current and node voltage methods of analysis D.C and A.C Circuits.

UNIT II NETWORK REDUCTION AND THEOREMS FOR DC AND AC CIRCUITS 9+3

Network reduction: voltage and current division, source transformation – star delta conversion. Theorems – Superposition, Thevenin's and Norton's Theorem – Maximum power transfer theorem – Reciprocity Theorem – Millman's theorem- Tellegen's Theorem-Statement, application to DC and AC Circuits.

UNIT III TRANSIENT RESPONSE ANALYSIS 9+3

Introduction – Laplace transforms and inverse Laplace transforms- standard test signals -Transient response of RL, RC and RLC circuits using Laplace transform for Source free, Step input and Sinusoidal input.

UNIT IV RESONANCE AND COUPLED CIRCUITS 9+3

Series and parallel resonance –frequency response – Quality factor and Bandwidth – Self and mutual inductance – Coefficient of coupling – Dot rule-Analysis of coupled circuits– Single Tuned circuits.

UNIT V THREE PHASE CIRCUITS 9+3

Analysis of three phase 3-wire and 4-wire circuits with star and delta connected loads, balanced and unbalanced – phasor diagram of voltages and currents – power measurement in three phase circuits– Power Factor Calculations.

TOTAL: 60 PERIODS

COURSE OUTCOMES:

After completing this course, the students will be able to:

CO1: Explain circuit's behavior using circuit laws.
CO2: Apply mesh analysis/ nodal analysis / network theorems to determine behavior of the given DC and AC circuit
CO3: Compute the transient response of first order and second order systems to step and sinusoidal input
CO4: Compute power, line/ phase voltage and currents of the given three phase circuit
CO5: Explain the frequency response of series and parallel RLC circuits
CO6: Explain the behavior of magnetically coupled circuits.

TEXT BOOKS:

1. William H. HaytJr, Jack E. Kemmerly and Steven M. Durbin, “Engineering Circuits Analysis”, McGraw Hill publishers, 9th edition, New Delhi, 2020.
2. Charles K. Alexander, Mathew N.O. Sadiku, “Fundamentals of Electric Circuits”, Second Edition, McGraw Hill, 2019.
3. Allan H. Robbins, Wilhelm C. Miller, “Circuit Analysis Theory and Practice”, Cengage Learning India, 2013.

REFERENCES

1. Chakrabarti A, “Circuits Theory (Analysis and synthesis), Dhanpat Rai& Sons, New Delhi, 2020.
2 Joseph A. Edminister, Mahmood Nahvi, “Electric circuits”, Schaum’s series, McGraw-Hill, First Edition, 2019.
4. M E Van Valkenburg, “Network Analysis”,Prentice-Hall of India Pvt Ltd, New Delhi, 2015.
5. Richard C. Dorf and James A. Svoboda, “Introduction to Electric Circuits”, 7th Edition, John Wiley Sons, Inc. 2018.
6. Sudhakar A and Shyam Mohan SP, “Circuits and Networks Analysis and Synthesis”, McGraHill, 2015.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	3	2	2		2	1				3	3	3	3
CO2	3	3	3	3	2		2	1				3	3	3	3
CO3	3	3	3	3	2		2	1				3	3	3	3
CO4	3	3	3	3	2		2	1				3	3	3	3
CO5	3	3	3	3	2		2	1				3	3	3	3
CO6	3	3	3	3	2		2	1				3	3	3	3
Avg.	3	3	3	2.8	2		2	1				3	3	3	3

TIEE3102 **DIGITAL LOGIC CIRCUITS** **L T P C**
3 0 0 3

COURSE OBJECTIVES:

- To introduce the fundamentals of combinational and sequential digital circuits.
- To study various number systems and to simplify the mathematical expressions using Boolean functions word problems
- To study implementation of combinational circuits using Gates` and MSI Devices.
- To study the design of various synchronous and asynchronous circuits
- To introduce digital simulation techniques for development of application oriented logic circuit

UNIT I NUMBER SYSTEMS AND DIGITAL LOGIC FAMILIES 9

Number system, error detection, corrections & codes conversions, Boolean algebra: De-Morgan's theorem, switching functions and minimization using K-maps & Quine McCluskey method - Digital Logic Families -comparison of RTL, DTL, TTL, ECL and MOS families - operation, characteristics of digital logic family.

UNIT II COMBINATIONAL CIRCUITS 9

Combinational logic - representation of logic functions-SOP and POS forms, K-map representations - minimization using K maps - simplification and implementation of combinational logic – multiplexers and de multiplexers - code converters, adders, subtractors, Encoders and Decoders.

UNIT III SYNCHRONOUS SEQUENTIAL CIRCUITS 9

Sequential logic- SR, JK, D and T flip flops - level triggering and edge triggering - counters - asynchronous and synchronous type - Modulo counters - Shift registers - design of synchronous sequential circuits – Moore and Mealy models- Counters, state diagram; state reduction; state assignment.

UNIT IV ASYNCHRONOUS SEQUENTIAL CIRCUITS AND PROGRAMMABILITY LOGIC DEVICES 9

Asynchronous sequential logic Circuits-Transition stability, flow stability-race conditions, hazards &errors in digital circuits; analysis of asynchronous sequential logic circuits-introduction to Programmability Logic Devices: PROM – PLA –PAL, CPLD-FPGA.

UNIT V VHDL 9

RTL Design – combinational logic – Sequential circuit – Operators – Introduction to Packages – Subprograms – Test bench. (Simulation /Tutorial Examples: adders, counters, flip flops, Multiplexers & De multiplexers).

TOTAL : 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Explain various number systems and characteristics of digital logic families

CO2: Apply K-maps and Quine McCluskey methods to simplify the given Boolean expressions

CO3: Explain the implementation of combinational circuit such as multiplexers and de multiplexers - code converters, adders, subtractors, Encoders and Decoders

CO4: Design various synchronous and asynchronous circuits using Flip Flops

CO5: Explain asynchronous sequential circuits and programmable logic devices

CO6: Use VHDL for simulating and testing RTL, combinatorial and sequential circuits

TEXTBOOKS:

1. Morris Mano.M, 'Digital Logic and Computer Design', Prentice Hall of India, 3rd Edition, 2005.
2. Donald D.Givone, 'Digital Principles and Design', Tata McGraw Hill,1st Edition, 2003
3. Thomas L Floyd, 'Digital fundamentals', Pearson Education Limited, 11th Edition, 2018

REFERENCES:

1. Tocci R.J., Neal S. Widmer, 'Digital Systems: Principles and Applications', Pearson Education Asia, 12th Edition, 2017.
2. Donald P Leach, Albert Paul Malvino, Goutam Sha, 'Digital Principles and Applications', Tata McGraw Hill, 7th Edition, 2010.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	3	1	3			1				1	3		1
CO2	3	3	3	1	3			1				1	3		1
CO3	3	3	3	1	3			1				1	3		1
CO4	3	3	3	1	3			1				1	3		1
CO5	3	3	3	1	3			1				1	3		1
Avg	3	3	3	1	3			1				1	3		1

TIEE3103 PROBLEM SOLVING AND PYTHON PROGRAMMING L T P C
3 0 0 3

COURSE OBJECTIVES:

- To understand the basics of algorithmic problem solving.
- To learn to solve problems using Python conditionals and loops.
- To define Python functions and use function calls to solve problems.
- To use Python data structures - lists, tuples, dictionaries to represent complex data.
- To do input/output with files in Python.

UNIT I COMPUTATIONAL THINKING AND PROBLEM SOLVING 9

Fundamentals of Computing – Identification of Computational Problems -Algorithms, building blocks of algorithms (statements, state, control flow, functions), notation (pseudo code, flow chart, programming language), algorithmic problem solving, simple strategies for developing algorithms (iteration, recursion). Illustrative problems: find minimum in a list, insert a card in a list of sorted cards, guess an integer number in a range, Towers of Hanoi.

UNIT II DATA TYPES, EXPRESSIONS, STATEMENTS 9

Python interpreter and interactive mode,debugging; values and types: int, float, boolean, string, a nd list; variables, expressions, statements, tuple assignment, precedence of operators, comments; Illustrative programs: exchange the values of two variables, circulate the values of n variables, distance between two points.

UNIT III CONTROL FLOW, FUNCTIONS, STRINGS 9

Conditionals:Boolean values and operators, conditional (if), alternative (if-else),chained conditional (if-elif-else);Iteration: state, while, for, break, continue, pass; Fruitful functions: return values,parameters, local and global scope, function composition, recursion; Strings: string slices,immutability, string functions and methods, string module; Lists as arrays. Illustrative programs: square root, gcd, exponentiation, sum an array of numbers, linear search, binary search.

UNIT IV LISTS, TUPLES, DICTIONARIES 9

Lists: list operations, list slices, list methods, list loop, mutability, aliasing, cloning lists, list parameters; Tuples: tuple assignment, tuple as return value; Dictionaries: operations and methods; advanced list processing - list comprehension; Illustrative programs: simple sorting, histogram, Students marks statement, Retail bill preparation.

UNIT V FILES, MODULES, PACKAGES 9

Files and exceptions: text files, reading and writing files, format operator; command line arguments, errors and exceptions, handling exceptions, modules, packages; Illustrative programs: word count, copy file, Voter's age validation, Marks range validation (0-100).

TOTAL : 45 PERIODS

COURSE OUTCOMES:

Upon completion of the course, students will be able to

CO1: Develop algorithmic solutions to simple computational problems.
CO2: Develop and execute simple Python programs.
CO3: Write simple Python programs using conditionals and loops for solving problems.
CO4: Decompose a Python program into functions.
CO5: Represent compound data using Python lists, tuples, dictionaries etc.
CO6: Read and write data from/to files in Python programs.

TEXT BOOKS:

1. Allen B. Downey, "Think Python: How to Think like a Computer Scientist", 2nd Edition, O'Reilly Publishers, 2016.
2. Karl Beecher, "Computational Thinking: A Beginner's Guide to Problem Solving and Programming", 1st Edition, BCS Learning & Development Limited, 2017.

REFERENCES:

1. Paul Deitel and Harvey Deitel, "Python for Programmers", Pearson Education, 1st Edition, 2021.
2. G Venkatesh and Madhavan Mukund, "Computational Thinking: A Primer for Programmers and Data Scientists", 1st Edition, Notion Press, 2021.
3. John V Guttag, "Introduction to Computation and Programming Using Python: With Applications to Computational Modeling and Understanding Data", Third Edition, MIT Press, 2021
4. Eric Matthes, "Python Crash Course, A Hands - on Project Based Introduction to Programming", 2nd Edition, No Starch Press, 2019.
5. https://www.python.org/
6. Martin C. Brown, "Python: The Complete Reference", 4th Edition, Mc-Graw Hill, 2018.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	3	3	2	-	-	-	-	-	2	2	3	3
2	3	3	3	3	2	-	-	-	-	-	2	2	3	-
3	3	3	3	3	2	-	-	-	-	-	2	-	3	-
4	2	2	-	2	2	-	-	-	-	-	1	-	3	-
5	1	2	-	-	1	-	-	-	-	-	1	-	2	-
6	2	2	-	-	2	-	-	-	-	-	1	-	2	-
AVg.	2	3	3	3	2	-	-	-	-	-	2	2	3	3

1 - low, 2 - medium, 3 - high, '-' - no correlation

TIEE3111 PROBLEM SOLVING AND PYTHON PROGRAMMING LABORATORY L T P C
0 0 4 2

OBJECTIVES:

- To understand the problem solving approaches.
- To learn the basic programming constructs in Python.
- To practice various computing strategies for Python-based solutions to real world problems.
- To use Python data structures - lists, tuples, dictionaries.
- To do input/output with files in Python.

EXPERIMENTS:

Note: The examples suggested in each experiment are only indicative. The lab instructor is expected to design other problems on similar lines. The Examination shall not be restricted to the sample experiments listed here.

1. Identification and solving of simple real life or scientific or technical problems, and developing flow charts for the same. (Electricity Billing, Retail shop billing, Sin series, weight of a motorbike, Weight of a steel bar, compute Electrical Current in Three Phase AC Circuit, etc.)
2. Python programming using simple statements and expressions (exchange the values of two variables, circulate the values of n variables, distance between two points).
3. Scientific problems using Conditionals and Iterative loops. (Number series, Number Patterns, pyramid pattern)
4. Implementing real-time/technical applications using Lists, Tuples. (Items present in a library/Components of a car/ Materials required for construction of a building –operations of list & tuples)
5. Implementing real-time/technical applications using Sets, Dictionaries. (Language, components of an automobile, Elements of a civil structure, etc.- operations of Sets & Dictionaries)
6. Implementing programs using Functions. (Factorial, largest number in a list, area of shape)
7. Implementing programs using Strings. (reverse, palindrome, character count, replacing characters)
8. Implementing programs using written modules and Python Standard Libraries (pandas, numpy. Matplotlib, scipy)
9. Implementing real-time/technical applications using File handling. (copy from one file to another, word count, longest word)
10. Implementing real-time/technical applications using Exception handling. (divide by zero error, voter's age validity, student mark range validation)

11. Exploring Pygame tool.
12. Developing a game activity using Pygame like bouncing ball, car race etc.

TOTAL: 60 PERIODS

OUTCOMES:

On completion of the course, students will be able to:

CO1: Develop algorithmic solutions to simple computational problems
CO2: Develop and execute simple Python programs.
CO3: Implement programs in Python using conditionals and loops for solving problems..
CO4: Deploy functions to decompose a Python program.
CO5: Process compound data using Python data structures.
CO6: Utilize Python packages in developing software applications.

TEXT BOOKS:

1. Allen B. Downey, “Think Python : How to Think like a Computer Scientist”, 2nd Edition, O’Reilly Publishers, 2016.
2. Karl Beecher, “Computational Thinking: A Beginner's Guide to Problem Solving and Programming”, 1st Edition, BCS Learning & Development Limited, 2017.

REFERENCES:

1. Paul Deitel and Harvey Deitel, “Python for Programmers”, Pearson Education, 1st Edition, 2021.
2. G Venkatesh and Madhavan Mukund, “Computational Thinking: A Primer for Programmers and Data Scientists”, 1st Edition, Notion Press, 2021.
3. John V Guttag, "Introduction to Computation and Programming Using Python: With Applications to Computational Modeling and Understanding Data‘‘, Third Edition, MIT Press , 2021
4. Eric Matthes, “Python Crash Course, A Hands - on Project Based Introduction to Programming”, 2nd Edition, No Starch Press, 2019.
5. https://www.python.org/
6. Martin C. Brown, “Python: The Complete Reference”, 4th Edition, Mc-Graw Hill, 2018.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
1	3	3	3	3	3	-	-	-	-	-	3	2	3	3
2	3	3	3	3	3	-	-	-	-	-	3	2	3	-
3	3	3	3	3	2	-	-	-	-	-	2	-	3	-
4	3	2	-	2	2	-	-	-	-	-	1	-	3	-
5	1	2	-	-	1	-	-	-	-	-	1	-	2	-
6	2	-	-	-	2	-	-	-	-	-	1	-	2	-
AVg.	2	3	3	3	2	-	-	-	-	-	2	2	3	3

1 - low, 2 - medium, 3 - high, ‘-' - no correlation

TIMA3201 STATISTICS AND NUMERICAL METHODS L T P C
3 1 0 4

OBJECTIVES:

- This course aims at providing the necessary basic concepts of a few statistical and numerical methods and give procedures for solving numerically different kinds of problems occurring in engineering and technology.
- To acquaint the knowledge of testing of hypothesis for small and large samples which plays an important role in real life problems.
- To introduce the basic concepts of solving algebraic and transcendental equations.
- To introduce the numerical techniques of interpolation in various intervals and numerical techniques of differentiation and integration which plays an important role in engineering and technology disciplines.
- To acquaint the knowledge of various techniques and methods of solving ordinary differential equations.

UNIT I TESTING OF HYPOTHESIS 9 + 3

Sampling distributions - Tests for single mean, proportion and difference of means (Large and small samples) – Tests for single variance and equality of variances – Chi square test for goodness of fit – Independence of attributes.

UNIT II DESIGN OF EXPERIMENTS 9 + 3

One way and two way classifications - Completely randomized design – Randomized block design – Latin square design - 2^2 factorial design.

UNIT III SOLUTION OF EQUATIONS AND EIGENVALUE PROBLEMS 9 + 3

Solution of algebraic and transcendental equations - Fixed point iteration method – Newton Raphson method- Solution of linear system of equations - Gauss elimination method – Pivoting - Gauss Jordan method – Iterative methods of Gauss Jacobi and Gauss Seidel - Eigenvalues of a matrix by Power method and Jacobi's method for symmetric matrices.

UNIT IV INTERPOLATION, NUMERICAL DIFFERENTIATION AND NUMERICAL INTEGRATION 9 +3

Lagrange's and Newton's divided difference interpolations – Newton's forward and backward difference interpolation – Approximation of derivates using interpolation polynomials – Numerical single and double integrations using Trapezoidal and Simpson's 1/3 rules.

UNIT V NUMERICAL SOLUTION OF ORDINARY DIFFERENTIAL EQUATIONS 9 +3

Single step methods: Taylor's series method - Euler's method - Modified Euler's method - Fourth order Runge-Kutta method for solving first order differential equations - Multi step methods: Milne's and Adams - Bash forth predictor corrector methods for solving first order differential equations.

TOTAL: 60 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Apply the concept of testing of hypothesis for small and large samples in real life problems.
- Apply the basic concepts of classifications of design of experiments in the field of agriculture.
- Appreciate the numerical techniques of interpolation in various intervals and apply the numerical techniques of differentiation and integration for engineering problems.
- Understand the knowledge of various techniques and methods for solving first and second order ordinary differential equations.
- Solve the partial and ordinary differential equations with initial and boundary conditions by using certain techniques with engineering applications.

TEXT BOOKS:

1. Grewal, B.S., and Grewal, J.S., "Numerical Methods in Engineering and Science", Khanna Publishers, 10th Edition, New Delhi, 2015.
2. Johnson, R.A., Miller, I and Freund J., “Miller and Freund’s Probability and Statistics for Engineers", Pearson Education, Asia, 8th Edition, 2015.

REFERENCES:

1. Burden, R.L and Faires, J.D, "Numerical Analysis”, 9th Edition, Cengage Learning, 2016.
2. Devore. J.L., "Probability and Statistics for Engineering and the Sciences”, Cengage Learning, New Delhi, 8th Edition, 2014.
3. Gerald. C.F. and Wheatley. P.O. "Applied Numerical Analysis” Pearson Education, Asia, New Delhi, 7th Edition, 2007.
4. Gupta S.C. and Kapoor V. K., “ Fundamentals of Mathematical Statistics”, Sultan Chand & Sons, New Delhi, 12th Edition, 2020.
5. Spiegel. M.R., Schiller. J. and Srinivasan. R.A., "Schaum’s Outlines on Probability and Statistics ", Tata McGraw Hill Edition, 4th Edition, 2012.
6. Walpole. R.E., Myers. R.H., Myers. S.L. and Ye. K., “Probability and Statistics for Engineers and Scientists", 9th Edition, Pearson Education, Asia, 2010.

MAPPING OF COs WITH POs AND PSOs

	PO01	PO02	PO03	PO04	PO05	PO06	PO07	PO08	PO09	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
CO2	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
CO3	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
CO4	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
CO5	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-
Avg.	3	3	1	1	1	0	0	0	2	0	2	3	-	-	-

TIEE3201 **ELECTROMAGNETIC FIELDS** **L T P C**
3 1 0 4

COURSE OBJECTIVES:

- To introduce the basic mathematical concepts related to electromagnetic vector fields
- To impart knowledge on the concepts of
  - ✓ Electrostatic fields, electric potential, energy density and their applications.
  - ✓ Magneto static fields, magnetic flux density, vector potential and its applications.
  - ✓ Different methods of emf generation and Maxwell's equations
  - ✓ Electromagnetic waves and characterizing parameters

UNIT I ELECTROSTATICS – I **12**

Sources and effects of electromagnetic fields – Coordinate Systems – Vector fields –Gradient, Divergence, Curl – theorems and applications - Coulomb's Law – Electric field intensity – Field due to discrete and continuous charges – Gauss's law and applications.

UNIT II ELECTROSTATICS – II **12**

Electric potential – Electric field and equipotential plots, Uniform and Non-Uniform field, Utilization factor – Electric field in free space, conductors, dielectrics - Dielectric polarization –Dielectric strength - Electric field in multiple dielectrics – Boundary conditions, Poisson's and Laplace's equations, Capacitance, Energy density, Applications.

UNIT III MAGNETOSTATICS **12**

Lorentz force, magnetic field intensity (H) – Biot–Savart's Law - Ampere's Circuit Law – H due to straight conductors, circular loop, infinite sheet of current, Magnetic flux density (B) – B in free space, conductor, magnetic materials – Magnetization, Magnetic field in multiple media –Boundary conditions, scalar and vector potential, Poisson's Equation, Magnetic force, Torque, Inductance, Energy density, Applications.

UNIT IV ELECTRODYNAMIC FIELDS **12**

Magnetic Circuits - Faraday's law – Transformer and motional EMF – Displacement current -Maxwell's equations (differential and integral form) – Relation between field theory and circuit theory – Applications.

UNIT V ELECTROMAGNETIC WAVES **12**

Electromagnetic wave generation and equations – Wave parameters; velocity, intrinsic impedance, propagation constant – Waves in free space, lossy and lossless dielectrics, conductors- skin depth - Poynting vector – Plane wave reflection and refraction.

TOTAL: 60 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Visualize and explain Gradient, Divergence, and Curl operations on electromagnetic vector fieldsand identify the electromagnetic sources and their effects.

CO2: Compute and analyse electrostatic fields, electric potential, energy density along with their applications.

CO3: Compute and analyse magneto static fields, magnetic flux density, vector potential along with their applications.

CO4: Explain different methods of emf generation and Maxwell's equations
CO5: Explain the concept of electromagnetic waves and characterizing parameters

TEXT BOOKS:

1. Mathew N. O. Sadiku, S.V. Kulkarni 'Principles of Electromagnetics', 6th Edition, Oxford University Press Inc. Asian edition, 2015.
2. William H. Hayt and John A. Buck, 'Engineering Electromagnetics', McGraw Hill Special Indian edition, 2014.
3. Kraus and Fleish, 'Electromagnetics with Applications', McGraw Hill International Editions, Fifth Edition, 2010.

REFERENCES

1. V.V.Sarwate, 'Electromagnetic fields and waves', Second Edition, Newage Publishers, 2018.
2. J.P.Tewari, 'Engineering Electromagnetics - Theory, Problems and Applications', Second Edition, Khanna Publishers 2013.
3. Joseph. A.Edminister, 'Schaum's Outline of Electromagnetics, Fifth Edition (Schaum's Outline Series), McGraw Hill, 2018.
4. S.P.Ghosh, Lipika Datta, 'Electromagnetic Field Theory', First Edition, McGraw Hill Education(India) Private Limited, 2017.
5. K A Gangadhar, 'Electromagnetic Field Theory', Khanna Publishers; Sixteenth Edition Eighth Reprint :2015

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	2	-	-			3	1				1	3	2	1
CO2	3	2	1	2			1	1				1	3	2	1
CO3	3	2	1	2			1	1				1	3	2	1
CO4	3	2	1	2			1	1				1	3	2	1
CO5	3	2	1	2			1	1				1	3	2	1
Avg	3	2	1	2			1.4	1				1	3	2	1

TIEE3202	ELECTRON DEVICES AND CIRCUITS	L T P C 3 0 0 3

COURSE OBJECTIVES:

- To understand the structure of basic electronic devices.
- To be exposed to active and passive circuit elements.
- To familiarize the operation and applications of transistor like BJT and FET.
- To explore the characteristics of amplifier gain and frequency response.
- To learn the required functionality of positive and negative feedback systems.

UNIT I PN JUNCTION DEVICES 9

PN junction diode –structure, operation and V-I characteristics, diffusion and transition capacitance – Clipping & Clamping circuits - Rectifiers – Half Wave and Full Wave Rectifier– Display devices- LED, Laser diodes, Zener diode characteristics- Zener diode Reverse characteristics – Zener diode as regulator.

UNIT II TRANSISTORS AND THYRISTORS 9

BJT, JFET, MOSFET- structure, operation, characteristics and Biasing UJT, Thyristors and IGBT - Structure and characteristics.

UNIT III AMPLIFIERS 9

BJT small signal model – Analysis of CE, CB, CC amplifiers- Gain and frequency response –MOSFET small signal model– Analysis of CS and Source follower – Gain and frequency response- High frequency analysis.

UNIT IV MULTISTAGE AMPLIFIERS AND DIFFERENTIAL AMPLIFIER 9

BIMOS cascade amplifier, Differential amplifier – Common mode and Difference mode analysis – FET input stages – Single tuned amplifiers – Gain and frequency response – Neutralization methods, power amplifiers –Types (Qualitative analysis).

UNIT V FEEDBACK AMPLIFIERS AND OSCILLATORS 9

Advantages of negative feedback – voltage / current, series, Shunt feedback –positive feedback – Condition for oscillations, phase shift – Wien bridge, Hartley, Colpitts and Crystal oscillators.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon successful completion of the course, the students will be able to:

CO1: Explain the structure and operation of PN junction devices (diode, Zener diode, LED and Laser diode)

CO2: Design clipper, clamper, half wave and full wave rectifier, regulator circuits using PN junction diodes

CO3: Analyze the structure and characteristics BJT, FET, MOSFET, UJT, Thyristor and IGBT

CO4: Analyze the performance of various configurations of BJT and MOSFET based amplifier

CO5: Explain the characteristics of MOS based cascade and differential amplifier

CO6: Explain the operation of various feedback amplifiers and oscillators

TEXT BOOKS:

1. David A. Bell , ”Electronic devices and circuits”, Oxford University higher education, 5th edition 2008.
2. Sedra and smith, “Microelectronic circuits”,7th Edition., Oxford University Press, 2017

REFERENCES:

1. Balbir Kumar, Shail.B.Jain, “Electronic devices and circuits” PHI learning private limited, 2nd edition 2014.
2. Thomas L.Floyd, “Electronic devices” Conventional current version, Pearson prentice hall, 10th Edition, 2017.
3. Donald A Neamen, “Electronic Circuit Analysis and Design” Tata McGraw Hill, 3rd Edition, 2003.
4. Robert L.Boylestad, “Electronic devices and circuit theory”, 11th edition, Pearson prentice Hall 2013.
5. Robert B. Northrop, “Analysis and Application of Analog Electronic Circuits to Biomedical Instrumentation”, CRC Press, Second edition, 2012.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	2	3	2	2			1				1	3		1
CO2	2	2	3	2	2			1				1	3		1
CO3	2	2	3	2	2			1				1	3		1
CO4	2	2	3	2	2			1				1	3		1
CO5	2	2	3	2	2			1				1	3		1
Avg	2	2	3	2	2			1				1	3		1

TIEE3203 ENVIRONMENTAL SCIENCES AND SUSTAINABILITY

L	T	P	C
2	0	0	2

OBJECTIVES:

- To introduce the basic concepts of environment, eCOsystems and biodiversity and emphasize on the biodiversity of India and its conservation.
- To impart knowledge on the causes, effects and control or prevention measures of environmental pollution and natural disasters.
- To facilitate the understanding of global and Indian scenario of renewable and nonrenewable resources, causes of their degradation and measures to preserve them.
- To familiarize the concept of sustainable development goals and appreciate the interdependence of economic and social aspects of sustainability, recognize and analyze climate changes, concept of carbon credit and the challenges of environmental management.
- To inculcate and embrace sustainability practices and develop a broader understanding on green materials, energy cycles and analyze the role of sustainable urbanization.

UNIT I ENVIRONMENT AND BIODIVERSITY **6**

Definition, scope and importance of environment – need for public awareness. Eco-system and Energy flow– ecological succession. Types of biodiversity: genetic, species and eCOsystem diversity– values of biodiversity, India as a mega-diversity nation – hot-spots of biodiversity – threats to

biodiversity: habitat loss, poaching of wildlife, man-wildlife conflicts – endangered and endemic species of India – conservation of biodiversity: In-situ and ex-situ.

UNIT II ENVIRONMENTAL POLLUTION 6

Causes, Effects and Preventive measures of Water, Soil, Air and Noise Pollutions. Solid, Hazardous and E-Waste management. Case studies on Occupational Health and Safety Management system (OHASMS). Environmental protection, Environmental protection acts .

UNIT III RENEWABLE SOURCES OF ENERGY 6

Energy management and conservation, New Energy Sources: Need of new sources. Different types new energy sources. Applications of- Hydrogen energy, Ocean energy resources, Tidal energy conversion. Concept, origin and power plants of geothermal energy.

UNIT IV SUSTAINABILITY AND MANAGEMENT 6

Development, GDP, Sustainability- concept, needs and challenges-economic, social and aspects of sustainability-from unsustainability to sustainability-millennium development goals, and protocols - Sustainable Development Goals-targets, indicators and intervention areas Climate change- Global, Regional and local environmental issues and possible solutions-case studies. Concept of Carbon Credit, Carbon Footprint. Environmental management in industry-A case study.

UNIT V SUSTAINABILITY PRACTICES 6

Zero waste and R concept, Circular economy, ISO 14000 Series, Material Life cycle assessment, Environmental Impact Assessment. Sustainable habitat: Green buildings, Green materials, Energy efficiency, Sustainable transports. Sustainable energy: Non-conventional Sources, Energy Cycles-carbon cycle, emission and sequestration, Green Engineering: Sustainable urbanization- Socio-economical and technological change.

TOTAL: 30 PERIODS

OUTCOMES:

- To recognize and understand the functions of environment, eCOsystems and biodiversity and their conservation.
- To identify the causes, effects of environmental pollution and natural disasters and contribute to the preventive measures in the society.
- To identify and apply the understanding of renewable and non-renewable resources and contribute to the sustainable measures to preserve them for future generations.
- To recognize the different goals of sustainable development and apply them for suitable technological advancement and societal development.
- To demonstrate the knowledge of sustainability practices and identify green materials, energy cycles and the role of sustainable urbanization.

TEXT BOOKS:

1. Anubha Kaushik and C. P. Kaushik's "Perspectives in Environmental Studies", 6th Edition, New Age International Publishers ,2018.
2. Benny Joseph, 'Environmental Science and Engineering', Tata McGraw-Hill, New Delhi, 2016.
3. Gilbert M.Masters, 'Introduction to Environmental Engineering and Science', 2nd edition, Pearson Education, 2004.
4. Allen, D. T. and Shonnard, D. R., Sustainability Engineering: Concepts, Design and Case Studies, Prentice Hall.
5. Bradley. A.S; Adebayo, A.O., Maria, P. Engineering applications in sustainable design and development, Cengage learning.
6. Environment Impact Assessment Guidelines, Notification of Government of India, 2006.

7. Mackenthun, K.M., Basic Concepts in Environmental Management, Lewis Publication, London, 1998.

REFERENCES

1. R.K. Trivedi, 'Handbook of Environmental Laws, Rules, Guidelines, Compliances and Standards', Vol. I and II, Enviro Media. 38.
2. Cunningham, W.P. Cooper, T.H. Gorhani, 'Environmental Encyclopedia', Jaico Publ., House, Mumbai, 2001.
3. Dharmendra S. Sengar, 'Environmental law', Prentice hall of India PVT. LTD, New Delhi, 2007.
4. Rajagopalan, R, 'Environmental Studies-From Crisis to Cure', Oxford University Press, 2005.
5. Erach Bharucha "Textbook of Environmental Studies for Undergraduate Courses" Orient Blackswan Pvt. Ltd. 2013.

MAPPING OF COs WITH POs AND PSOs

CO	PO												PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	2	1	-	-	-	2	3	-	-	-	-	2	-	-	-
2	3	2	-	-	-	3	3	-	-	-	-	2	-	-	-
3	3	-	1	-	-	2	2	-	-	-	-	2	-	-	-
4	3	2	1	1	-	2	2	-	-	-	-	2	-	-	-
5	3	2	1	-	-	2	2	-	-	-	-	1	-	-	-
Avg.	2.8	1.8	1	1	-	2.2	2.4	-	-	-	-	1.8	-	-	-

- 1-low, 2-medium, 3-high, '-"- no correlation

TIEE3211 BASIC ELECTRONICS AND ELECTRICAL CIRCUITS LABORATORY L T P C
0 0 3 1.5

COURSE OBJECTIVES:

- To enable the students to understand the behavior of semiconductor device based on experimentation.
- Be exposed to active and passive circuit elements.
- Familiarize the operation and characteristics of transistor like BJT and FET.
- Explore the characteristics of amplifier gain and frequency response.
- Learn the required functionality of positive and negative feedback systems.

Electrical Experiments:

1. Verification of series and parallel electrical circuit using fundamental laws.
2. Simulation and experimental verification of electrical circuit problems using Thevenin's theorem.
3. Verification of electrical circuit problems using Superposition theorem.
4. Validation of R-C,R-L and RLC electric circuit transients
5. Simulation and Experimental validation of Frequency response of RLC electric circuit.

6. Verification of three phase balanced and unbalanced star, delta networks circuit (Power and Power factor calculations).

Electronics experiments:

1. V-I Characteristics of Semiconductor diode, Zener diode, photodiode, and phototransistor
2. V-I Characteristics of MOSFET
3. V-I Characteristics of UJT and generation of sawtooth waveforms
4. Design and frequency response characteristics of a Common Emitter amplifier
5. Design and testing of RC phase shift and LC oscillators
6. Single-Phase half-wave and full-wave rectifiers with capacitive filters

COURSE OUTCOMES:

Upon successful completion of the course, the students will be able to:

CO1: Verify the fundamental laws pof electric circuits.
CO2: Verify the thorems (Thevenin's superposition) via simulation and experimental studies.
CO3: Verify and validate the responses in PLC, RL and RLC transients and resononant circuit.
CO4: Compute power and power factor for a balanced unbalanced three phase circuits.
CO5: Analyze the characteristics of PN, Zener diode, photodiode, photo transistor and BJT in CE, configurations experimentally
CO6: Analyze the characteristics of JFET and UJT experimentally.
CO7: Analyze the characteristics of RC phase shift and LC oscillators experimentally
CO8: Analyze the characteristics of half-wave and full-wave rectifier with and without filters experimentally

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	3	1	1			1.5	2			3	3	3	3
CO2	3	3	3	1	3			1.5	2			3	3	3	3
CO3	3	3	3	1	1			1.5	2			3	3	3	3
CO4	3	3	2	1	1			1.5	2			3	3	3	3
CO5	3	3	2	1	-			1.5	2			3	3	1	3
CO6	3	3	2	1	-			1.5	2			3	3	2	3
CO7	3	3	2	1	-			1.5	2			3	3	2	3
CO8	3	3	2	1	1			1.5	2			3	3	2	3
Avg	3	3	2.3	1	0.8			1.5	2			3	3	2.3	3

TIEE3301	ELECTRICAL MACHINES - I	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To understand the concept of electromechanical energy conversion system.
- To identify the appropriate machine for a given application based on its characteristics.
- To identify the appropriate test to determine the performance parameters of a given machine.
- To familiarize with the procedure for parallel operation of generators and transformers.
- To deliberate the working of auto transformer and three phase transformers.

UNIT I ELECTROMECHANICAL ENERGY CONVERSION 9

Fundamentals of Magnetic circuits- Statically and dynamically induced EMF - Principle of electromechanical energy conversion forces and torque in magnetic field systems- energy balance in magnetic circuits- magnetic force- co-energy in singly excited and multi excited magnetic field system mmf of distributed windings – Winding Inductances-, magnetic fields in rotating machines- magnetic saturation and leakage fluxes. Introduction to Indian Standard Specifications (ISS) - Role and significance in testing.

UNIT II DC GENERATORS 9

Principle of operation, constructional details, armature windings and its types, EMF equation, wave shape of induced emf, armature reaction, demagnetizing and cross magnetizing Ampere turns, compensating winding, commutation, methods of improving commutation, interpoles, OCC and load characteristics of different types of DC Generators. Parallel operation of DC Generators, equalizing connections- applications of DC Generators.

UNIT III DC MOTORS 9

Principle of operation, significance of back emf, torque equations and power developed by armature, speed control of DC motors, starting methods of DC motors, load characteristics of DC motors, losses and efficiency in DC machine, condition for maximum efficiency. Testing of DC Machines: Brake test, Swinburne's test, Hopkinson's test, Field test, Retardation test, Separation of core losses-applications of DC motors.

UNIT IV SINGLE PHASE TRANSFORMER 9

Construction and principle of operation, equivalent circuit, phasor diagrams, testing - polarity test, open circuit and short circuit tests, voltage regulation, losses and efficiency, all day efficiency, back-to-back test, separation of core losses, parallel operation of single-phase transformers, applications of single-phase transformer.

UNIT V AUTOTRANSFORMER AND THREE PHASE TRANSFORMER 9

Construction and working of auto transformer, comparison with two winding transformers, applications of autotransformer. Three Phase Transformer- Construction, types of connections and their comparative features, Scott connection, applications of Scott connection.

TOTAL : 45 PERIODS

TEXT BOOKS

1. I. J. Nagrath and D. P. Kothari, “Electric Machines”, McGraw Hill Education, 5th Edition, 2017.
2. P. S. Bimbhra, “Electric Machinery”, Khanna Publishers, 2nd Edition, 2021.

REFERENCES

1. A. E. Fitzgerald and C. Kingsley, "Electric Machinery”, New York, McGraw Hill Education, 6th Edition 2017.
2. A. E. Clayton and N. N. Hancock, “Performance and design of DC machines”, CBS Publishers, 2018.
3. M. G. Say, “Performance and design of AC machines”, CBS Publishers, First Edition 2008.
4. Sahdev S. K. “Electrical Machines”, Cambridge University Press, 2018.

COURSE OUTCOMES:

At the end of the course students will be able to:

CO1: Apply the laws governing the electromechanical energy conversion for singly and multiple excited systems.

CO2: Explain the construction and working principle of DC machines.

CO3: Interpret various characteristics of DC machines.

CO4: Compute various performance parameters of the machine, by conducting suitable tests.

CO5: Draw the equivalent circuit of transformer and predetermine the efficiency and regulation.

CO6: Describe the working principle of auto transformer, three phase transformer with different types of connections.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	1	1	1			1				1	3	2	2
CO2	3	3	1	1	1			1				1	3	1	1
CO3	3	3	1	1	1			1				1	3	1	1
CO4	3	3	1	1	1			1				1	3	3	2
CO5	3	3	1	1	1			1				1	3	3	2
CO6	3	3	1	1	1			1				1	3	3	2
Avg	3	3	1	1	1			1				1	3	3	3

TIEE3302	LINEAR INTEGRATED CIRCUITS	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

To impart knowledge on the following topics

- Signal analysis using Op-amp based circuits.
- Applications of Op-amp.
- Functional blocks and the applications of special ICs like Timers, PLL circuits, regulator Circuits.
- IC fabrication procedure.

UNIT I IC FABRICATION 9

IC classification, fundamental of monolithic IC technology, epitaxial growth, masking and etching, diffusion of impurities. Realisation of monolithic ICs and packaging. Fabrication of diodes, capacitance, resistance, FETs and PV Cell.

UNIT II CHARACTERISTICS OF OPAMP 9

Ideal OP-AMP characteristics, DC characteristics, AC characteristics, differential amplifier; frequency response of OP-AMP; Voltage-shunt feedback and inverting amplifier - Voltage series feedback: and Non-Inverting Amplifier - Basic applications of op-amp –, summer, differentiator and Integrator-V/I & I/V converters.

UNIT III APPLICATIONS OF OPAMP 9

Instrumentation amplifier and its applications for transducer Bridge, Log and Antilog Amplifiers- Analog multiplier & Divider, first and second order active filters, comparators, multi vibrators, waveform generators, clippers, clampers, peak detector, S/H circuit, D/A converter (R- 2R ladder and weighted resistor types), A/D converters using OP-AMPs.

UNIT IV SPECIAL ICs 9

Functional block, characteristics of 555 Timer and its PWM application - IC-566 voltage controlled oscillator IC; 565-phase locked loop IC, AD633 Analog multiplier ICs.

UNIT V APPLICATION ICs 9

AD623 Instrumentation Amplifier and its application as load cell weight measurement - IC voltage regulators –LM78XX, LM79XX; Fixed voltage regulators its application as Linear power supply - LM317, 723 Variability voltage regulators, switching regulator- SMPS - ICL 8038 function generator IC.

TOTAL :45 PERIODS

COURSE OUTCOMES:

Upon successful completion of the course, the students will be able to:

CO1 Explain monolithic IC fabrication process

CO2 Explain the fabrication of diodes, capacitance, resistance, FETs and PV Cell.

CO3 Analyze the characteristics and basic applications (inverting/non-inverting amplifier, summer, differentiator, integrator, V/I and I/V converter) of Op-Amp

CO4 Explain circuit and applications of op-amp based instrumentation amplifier, log/antilog amplifier, analog multiplier /divider, active filters, comparators, waveform generators, A/D and D/A converters

CO5 Explain Functional blocks, characteristics and applications of Timer, PLL, analog multiplier ICs.

CO6 Explain the applications of ICs in Instrumentation amplifier, fixed and variable voltage regulator, SMPS and function generator

TEXT BOOKS:

1. David A. Bell, 'Op-amp & Linear ICs', Oxford, Third Edition, 2011
2. D. Roy Choudhary, Sheil B. Jani, 'Linear Integrated Circuits', , New Age, Fourth Edition, 2018.
3. Ramakant A.Gayakward, 'Op-amps and Linear Integrated Circuits', IV edition, Pearson Education, PHI 2021.

REFERENCES

1. Fiore,"Opamps& Linear Integrated Circuits Concepts & applications", Cengage, 2010.
2. Floyd ,Buchla,"Fundamentals of Analog Circuits, Pearson, 2013.
3. Jacob Millman, Christos C.Halkias, 'Integrated Electronics - Analog and Digital circuits system', McGraw Hill, 2nd Edition, 2017.
4. Robert F.Coughlin, Fredrick F. Driscoll, 'Op-amp and Linear ICs', Pearson, 6th edition,2012.
5. Sergio Franco, 'Design with Operational Amplifiers and Analog Integrated Circuits', McGraw Hill, 2016 – Fourth Edition.
6. Muhammad H. Rashid,' Microelectronic Circuits Analysis and Design' Cengage Learning, 2nd Edition, 2012.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	2	3	2	2			1				1	3	2	1
CO2	2	2	3	2	2			1				1	3	2	1
CO3	2	2	3	2	2			1				1	3	2	1
CO4	2	2	3	2	2			1				1	3	2	1
CO5	2	2	3	2	2			1				1	3	2	1
Avg	2	2	3	2	2			1				1	3	2	1

TIEE3303	C PROGRAMMING AND DATA STRUCTURES	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To introduce the basics of C programming language.
- To learn the concepts of advanced features of C.
- To understand the concepts of ADTs and linear data structures.
- To know the concepts of non-linear data structure and hashing.
- To familiarize the concepts of sorting and searching techniques.

UNIT I C PROGRAMMING FUNDAMENTALS (8+1 SKILL) 9

Data Types – Variables – Operations – Expressions and Statements – Conditional Statements – Functions – Recursive Functions – Arrays – Single and Multi-Dimensional Arrays.

UNIT II C PROGRAMMING - ADVANCED FEATURES (8+1 SKILL) 9

Structures – Union – Enumerated Data Types – Pointers: Pointers to Variables, Arrays and Functions – File Handling – Preprocessor Directives.

UNIT III LINEAR DATA STRUCTURES (8+1 SKILL) 9

Abstract Data Types (ADTs) – List ADT – Array-Based Implementation – Linked List – Doubly- Linked Lists – Circular Linked List – Stack ADT – Implementation of Stack – Applications – Queue ADT – Priority Queues – Queue Implementation – Applications.

UNIT IV NON-LINEAR DATA STRUCTURES (8+1 SKILL) 9

Trees – Binary Trees – Tree Traversals – Expression Trees – Binary Search Tree – Hashing - Hash Functions – Separate Chaining – Open Addressing – Linear Probing– Quadratic Probing – Double Hashing – Rehashing.

UNIT V SORTING AND SEARCHING TECHNIQUES (8+1 SKILL) 9

Insertion Sort – Quick Sort – Heap Sort – Merge Sort –Linear Search – Binary Search.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 5

COURSE OUTCOMES:

CO1 Develop C programs for any real world/technical application.
CO2 Apply advanced features of C in solving problems.
CO3 Write functions to implement linear and non–linear data structure operations.
CO4 Suggest and use appropriate linear/non–linear data structure operations for solving a given problem.
CO5 Appropriately use sort and search algorithms for a given application.
CO6 Apply appropriate hash functions that result in a collision free scenario for data storage and retrieval.

TEXT BOOKS:

1. Mark Allen Weiss, “Data Structures and Algorithm Analysis in C”, Second Edition, Pearson Education, 1997.
2. ReemaThareja, “Programming in C”, Second Edition, Oxford University Press, 2016.

REFERENCES:

1. Brian W. Kernighan, Rob Pike, “The Practice of Programming”, Pearson Education, 1999.
2. Paul J. Deitel, Harvey Deitel, “C How to Program”, Seventh Edition, Pearson Education, 2013.
3. Alfred V. Aho, John E. Hopcroft, Jeffrey D. Ullman, “Data Structures and Algorithms”, Pearson Education,1983.
4. Ellis Horowitz, SartajSahni and Susan Anderson, “Fundamentals of Data Structures”, Galgotia, 2008.

List of Open Source Software/ Learning website:

https://www.coursera.org/specializations/data-structures-algorithms
https://nptel.ac.in/courses/112107243
https://nptel.ac.in/courses/112105598

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3		2		3	3		1		1		2	-	-	-
CO2	3	3	3	2	2	2		1	1	1			-	-	-
CO3	3	1	2	2	2			1	1	1			-	-	-
CO4	3	3	3	3	2			1		1			-	-	-
CO5	3			2		2		1		1		1	-	-	-
CO6	3			2				1		1			-	-	-
AVg.	3	2.33	2.5	2.2	2.25	2.33		1	1	1		1.5	-	-	-

1-low, 2-medium, 3-high, ‘-“- no correlation

TIEE3311 LINEAR AND DIGITAL CIRCUITS LABORATORY L T P C
0 0 3 1.5

COURSE OBJECTIVES:

- To learn design, testing and characterizing of circuit behavior with combinational logic gate ICs.
- To learn design, testing and characterizing of circuit behavior with register/ counter and sequential logic ICs.
- To learn design, testing and characterizing of circuit behavior with OPAMP ICs.
- To learn design, testing and characterizing of circuit behavior with analog Ics like 555 timer VCO and regulators.
- To learn design, testing and characterizing of circuit behavior with digital Ics like decoders, multiplexers.

LIST OF EXPERIMENTS

1. Implementation of Boolean Functions, Adder and Subtractor circuits.
2. Code converters: Excess-3 to BCD and Binary to Gray code converter and vice-versa.
3. Parity generator and parity checking.

4. Encoders and Decoders.
5. Counters: Design and implementation of 3-bit modulo counters as synchronous and Asynchronous types using FF IC's and specific counter IC.
6. Shift Registers: Design and implementation of 4-bit shift registers in SISO, SIPO, PISO, PIPO modes using suitability IC's.
7. Study of multiplexer and de multiplexer
8. Timer IC application: Study of NE/SE 555 timer in Astability, Monostability operation.
9. Application of Op-Amp: inverting and non-inverting amplifier, Adder, comparator, Integrator and Differentiator.
10. Voltage to frequency characteristics of NE/ SE 566 IC.
11. Variability Voltage Regulator using IC LM317.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

At the end of the course, the student should have the:

CO1: Ability to understand and implement Boolean Functions.
CO2: Ability to understand the importance of code conversion
CO3: Ability to Design and implement circuits with digital ICs like decoders, multiplexers, register.
CO4: Ability to acquire knowledge on Application of Op-Amp
CO5: Ability to Design and implement counters using analog ICs like timers, VCOs and digital ICs like Flip-flops and counters.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1				3				1.5			3	3	2	1	2
CO2			3	3				1.5			3	3	2	1	2
CO3		3	2	3	3			1.5			3	3	2	1	2
CO4		3	3	3	3			1.5			3	3	2	1	2
CO5								1.5				3			
Avg		3	1.6	3	3			1.5			3	3	2	1	2

TIEE3312 C PROGRAMMING AND DATA STRUCTURES LABORATORY L T P C

0 0 3 1.5

COURSE OBJECTIVES:

- To develop applications in C
- To implement linear and non-linear data structures
- To understand the different operations of search trees
- To get familiarized to sorting and searching algorithms

LIST OF EXPERIMENTS

1. Practice of C programming using statements, expressions, decision making and iterative statements
2. Practice of C programming using Functions and Arrays
3. Implement C programs using Pointers and Structures
4. Implement C programs using Files
5. Development of real time C applications
6. Array implementation of List ADT
7. Array implementation of Stack and Queue ADTs
8. Linked list implementation of List, Stack and Queue ADTs
9. Applications of List, Stack and Queue ADTs
10. Implementation of Binary Trees and operations of Binary Trees
11. Implementation of Binary Search Trees
12. Implementation of searching techniques
13. Implementation of Sorting algorithms : Insertion Sort, Quick Sort, Merge Sort
14. Implementation of Hashing – any two collision techniques

TOTAL: 45 PERIODS

COURSE OUTCOMES:

At the end of the course, the students will be able to:

CO1 Use different constructs of C and develop applications

CO2 Write functions to implement linear and non-linear data structure operations

CO3 Suggest and use the appropriate linear / non-linear data structure operations for a given problem

CO4 Apply appropriate hash functions that result in a collision free scenario for data storage and Retrieval

CO5 Implement Sorting and searching algorithms for a given application

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	2		2		3	2		2	3	3					
2	2		1		3	2		2	3	3		3			
3	2		1		3	2		2	3	3		3			
4	2		1		3	2		2	3	3					
5	2		1		3	2		2	3	3					
AVg.	2		1.2		3	2		2	3	3		3			

1-low, 2-medium, 3-high, '-"- no correlation

TIEE3401 ELECTRICAL MACHINES - II LT P C
3 0 0 3

COURSE OBJECTIVES:

To impart knowledge on the following Topics

- Construction and performance of salient and non – salient type synchronous generators.
- Principle of operation and performance of synchronous motor.
- Construction, principle of operation and performance of induction machines.
- Starting and speed control of three-phase induction motors.
- Construction, principle of operation and performance of single phase induction motors and special machines.

UNIT I SYNCHRONOUS GENERATOR 9

Constructional details – Types of rotors –winding factors- EMF equation – Synchronous reactance – Armature reaction – Phasor diagrams of non-salient pole synchronous generator connected to infinite bus--Synchronizing and parallel operation – Synchronizing torque -Change of excitation and mechanical input- Voltage regulation – EMF, MMF, ZPF and A.S.A method – steady state power-angle characteristics– Two reaction theory –slip test -short circuit transients - Capability Curves.

UNIT II SYNCHRONOUS MOTOR 9

Principle of operation – Torque equation – Operation on infinite bus bars - V and Inverted V curves – Power input and power developed equations – Starting methods – Current loci for constant power input, constant excitation and constant power Developed-Hunting – natural frequency of oscillations – damper windings- synchronous condenser.

UNIT III THREE PHASE INDUCTION MOTOR 9

Constructional details – Types of rotors –- Principle of operation – Slip –cogging and crawling- Equivalent circuit – Torque-Slip characteristics - Condition for maximum torque – Losses and efficiency – Load test - No load and blocked rotor tests - Circle diagram – Separation of losses – Double cage induction motors –Induction generators – Synchronous induction motor.

UNIT IV STARTING AND SPEED CONTROL OF THREE PHASE INDUCTION MOTOR 9

Need for starting – Types of starters – DOL, Rotor resistance, Autotransformer and Star delta starters – Speed control – Voltage control, Frequency control and pole changing – Cascaded Connection-V/f control – Slip power recovery Scheme-Braking of three phase induction motor: Plugging, dynamic braking and regenerative braking.

UNIT V SINGLE PHASE INDUCTION MOTORS AND SPECIAL MACHINES 9

Constructional details of single phase induction motor – Double field revolving theory and operation – Equivalent circuit – No load and blocked rotor test – Performance analysis – Starting methods of single-phase induction motors – Capacitor-start capacitor run Induction motor- Shaded pole induction motor - Linear induction motor – Repulsion motor - Hysteresis motor - AC series motor- Servo motors- Stepper motors - introduction to magnetic levitation systems.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will have the:

CO1: Ability to understand the construction and working principle of Synchronous generator
CO2: Ability to understand the construction and working principle of Synchronous Motor
CO3: Ability to understand the construction and working principle of Three Phase Induction Motor
CO4: Acquire knowledge about the starting and speed control of induction motors.
CO5: To gain knowledge about the basic principles and working of Single phase induction motors and Special Electrical Machines.

TEXT BOOKS:

1. A.E. Fitzgerald, Charles Kingsley, Stephen. D. Umans, 'Electric Machinery', Mc Graw Hill publishing Company Ltd, 6th Education 2017.
2. Stephen J. Chapman, 'Electric Machinery Fundamentals'4th edition, McGraw Hill Education Pvt. Ltd, 4th Edition 2017.
3. D.P. Kothari and I.J. Nagrath, 'Electric Machines', McGraw Hill Publishing Company Ltd, 5th Edition 2017
4. P.S. Bhimbhra, 'Electrical Machinery', Khanna Publishers, edition 2, 2021.

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1. Vincent Del Toro, 'Basic Electric Machines' Pearson India Education, 2016.
2. M.N. Bandyo padhyay, Electrical Machines Theory and Practice, PHI Learning PVT LTD., New Delhi, 2011.
3. B.R.Gupta, 'Fundamental of Electric Machines' New age International Publishers,3rd Edition, Reprint 2015.
4. Murugesh Kumar, 'Electric Machines', Vikas Publishing House Pvt. Ltd, First edition 2010.
5. Alexander S. Langsdorf, 'Theory of Alternating-Current Machinery', McGraw Hill Publications, 2001.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	2	3	3			1					3	3	2
CO2	3	3	2	3	3			1					3	3	2
CO3	3	3	2	3	3			1					3	3	2
CO4	3	3	2	3	3			1					3	3	2
CO5	3	3	1	1	2			1					3	3	2
CO6	3	3	1	1	2			1					3	3	2
Avg	3	3	1.6	2.3	2.6			1					3	3	2

TIEE3402	TRANSMISSION AND DISTRIBUTION	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To impart knowledge about the configuration of the electrical power systems.
- To study the line parameters and interference with neighboring circuits.
- To understand the mechanical design and performance analysis of transmission lines.
- To learn about different insulators and underground cables.
- To understand and analyze the distribution system.

UNIT I TRANSMISSION LINE PARAMETERS 9

Structure of electric power system - Parameters of single and three phase transmission lines with single and double circuits -Resistance, inductance, and capacitance of solid, stranded, and bundled conductors - Typical configuration, conductor types - Symmetrical and unsymmetrical spacing and transposition – application of self and mutual GMD; skin and proximity effects - Effects of earth on the capacitance of the transmission line - interference with neighboring communication circuits.

UNIT II MODELLING AND PERFORMANCE OF TRANSMISSION LINES 9

Performance of Transmission lines – short line, medium line and long line – equivalent circuits, phasor diagram, attenuation constant, phase constant, surge impedance – transmission efficiency and voltage regulation, real and reactive power flow in lines – Power Circle diagrams – Ferranti effect – Formation of Corona – Critical Voltages – Effect on line Performance.

UNIT III SAG CALCULATION AND LINE SUPPORTS 9

Mechanical design of overhead lines – Line Supports –Types of towers – Tension and Sag Calculation for different weather conditions – Methods of grounding - Insulators: Types, voltage distribution in insulator string, improvement of string efficiency, testing of insulators.

UNIT IV UNDERGROUND CABLES 9

Underground cables – Types of cables – Construction of single-core and 3-core belted cables – Insulation Resistance – Potential Gradient – Capacitance of single-core and 3-core belted cables – Grading of cables – Power factor and heating of cables– DC cables.

UNIT V DISTRIBUTION SYSTEMS 9

Distribution Systems – General Aspects – Kelvin's Law – AC and DC distributions –Concentrated and Distributed loading- Techniques of Voltage Control and Power factor improvement – Distribution Loss – Types of Substations – Trends in Transmission and Distribution: EHVAC, HVDC and FACTS (Qualitative treatment only).

TOTAL: 45 PERIODS

TEXT BOOKS:

1. D.P.Kothari, I.J. Nagarath, 'Power System Engineering', Mc Graw-Hill Publishing Company limited, New Delhi, Third Edition, 2019.
2. C.L.Wadhwa, 'Electrical Power Systems', New Age International Ltd, seventh edition 2022.
3. S.N. Singh, 'Electric Power Generation, Transmission and Distribution', Prentice Hall of India Pvt. Ltd, New Delhi, Second Edition, 2008.

REFERENCE BOOKS:

1. B.R.Gupta, 'Power System Analysis and Design' S. Chand, New Delhi, Sixth Edition, 2011.
2. Luces M.Fualken berry, Walter Coffer, 'Electrical Power Distribution and Transmission', Pearson Education, 2007.
3. Arun Ingole, "Power transmission and distribution" Pearson Education, first edition, 2018
4. J.Brian Hardy and Colin R.Bayliss 'Transmission and Distribution in Electrical Engineering', Newnes; Fourth Edition, 2011.
5. G.Ramamurthy, "Handbook of Electrical power Distribution," Universities Press, 2013.
6. V.K.Mehta, Rohit Mehta, 'Principles of power system', S. Chand & Company Ltd, New Delhi, 2013
7. Hadi Saadat, 'Power System Analysis', McGraw Hill Education Pvt. Ltd., New Delhi, 3rd Edition, 23rd reprint, 2015.
8. R.K.Rajput, 'A Text Book of Power System Engineering' 2nd edition, Laxmi Publications (P) Ltd, New Delhi, 2016.

COURSE OUTCOMES

On the successful completion of the course, students will be able to:

CO1 : Understand the structure of power system, computation of transmission line parameters for different configurations.

CO2 : Model the transmission lines to determine the line performance and to understand the impact of Ferranti effect and corona on line performance.

CO3 : Do Mechanical design of transmission lines, grounding and to understand about the insulators in transmission system.

CO4 : Design the underground cables and understand the performance analysis of underground cable.

CO5 : Understand the modelling, performance analysis and modern trends in distribution system.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	1	-	-	-	-	-	1	-	-	-	-	3	1	1
CO2	3	2	1	1	-	1	-	2	-	-	-	-	3	2	1
CO3	3	2	1	1	-	1	-	2	-	-	-	-	3	3	1
CO4	3	2	1	1	-	1	-	2	-	-	-	-	3	3	1
CO5	3	2	1	1	-	1	-	2	-	-	-	-	3	3	1
Avg	2.8	1.8	1	1		1	-	1.8					3	2.4	1

TIEE3403 MICROPROCESSOR AND MICROCONTROLLER LT P C
3 0 0 3

COURSE OBJECTIVES:

- To study the addressing modes & instruction set of 8085 &8051
- To develop skills in simple program writing in assembly languages
- To introduce commonly used peripheral/interfacing ICs.
- To study and understand typical applications of micro-processors.
- To study and understand the typical applications of micro-controllers

UNIT I INTRODUCTION TO 8085 ARCHITECTURE 9

Functional block diagram – Memory interfacing–I/O ports and data transfer concepts – Timing Diagram — Interrupt structure.

UNIT II 8085 INSTRUCTION SET AND PROGRAMMING 9

Instruction format and addressing modes — Assembly language format — Data transfer, data manipulation & control instructions – Programming: Loop structure with counting & Indexing - Look up table - Subroutine instructions, stack.

UNIT III INTERFACING BASICS AND ICS 9

Study of Architecture and programming of ICs: 8255 PPI, 8259PIC, 8251USART, 8279 Keyboard display controller and 8254 Timer/Counter – Interfacing with 8085 -A/D and D/A converter interfacing.

.

UNIT IV INTRODUCTION TO 8051 MICROCONTROLLER 9

Functional block diagram - Instruction format and addressing modes – Interrupt structure – Timer – I/O ports – Serial communication, Simple programming –keyboard and display interface – Temperature control system –stepper motor control - Usage of IDE for assembly language programming.

UNIT V INTRODUCTION TO RISC BASED ARCHITECTURE 9

PIC16 /18 architecture, Memory organization – Addressing modes – Instruction set - Programming techniques – Timers – I/O ports – Interrupt programming.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon successful completion of the course, the students should have the:

CO1: Ability to write assembly language program for microprocessor and microcontroller
CO2: Ability to design and implement interfacing of peripheral with microprocessor and microcontroller
CO3: Ability to analyze, comprehend, design and simulate microprocessor based systems used for control and monitoring.
CO4: Ability to analyze, comprehend, design and simulate microcontroller based systems used for control and monitoring.
CO5: Ability to understand and appreciate advanced architecture evolving microprocessor field

TEXTBOOKS:

1. Ramesh S. Gaonkar, 'Microprocessor Architecture Programming and Application', Pen ram International (P)ltd., Mumbai, 6th Education, 2013.
2. Muhammad Ali Mazidi & Janice Gilli Mazidi, 'The 8051 Micro Controller and Embedded Systems', Pearson Education, Second Edition 2011.

3. Muhammad Ali Mazidi & Janice Gilli Mazidi, 'The PIC Micro Controller and Embedded Systems', 2010

REFERENCES:

1. Douglas V. Hall, "Micro-processors & Interfacing", Tata McGraw Hill 3rd Edition, 2017.
2. Krishna Kant, "Micro-processors & Micro-controllers", Prentice Hall of India, 2007.
3. Mike Predko, "8051 Micro-controllers", McGraw Hill, 2009
4. Kenneth Ayala, 'The 8051 Microcontroller', Thomson, 3rd Edition 2004.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	1	2	3				1				3	3	1	3
CO2	2	1	2	3				1				3	3	1	3
CO3	2	1	2	3				1				3	3	1	3
CO4	2	1	2	3				1				3	3	1	3
CO5	2	1	2	3				1				3	3	1	3
Avg	2	1	2	3				1				3	3	1	3

TIEE3411 ELECTRICAL MACHINES LABORATORY L T P C
0 0 3 1.5

COURSE OBJECTIVES:

- To expose the students to determine the characteristics of DC machines and transformers by performing experiments on these machines.
- To provide hands on experience to evaluate the performance parameters of DC machines and transformer by conducting suitable tests.

LIST OF EXPERIMENTS:

1. Open circuit and load characteristics of DC shunt generator- calculation of critical resistance and critical speed.
2. Load test on DC series motor.
3. Swinburne's test and speed control of DC shunt motor.
4. Load test on single-phase transformer and three phase transformers.
5. Open circuit and short circuit tests on single phase transformer.
6. Regulation of three phase alternator by EMF and MMF methods.
7. V and Inverted V curves of Three Phase Synchronous Motor.
8. Load test on three-phase induction motor.
9. No load and blocked rotor tests on three-phase induction motor (Determination of equivalent circuit parameters).
10. Load test on single-phase induction motor.
11. No load and blocked rotor test on single-phase induction motor.
12. Study of Induction Motor Starters and DC Motor starter.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

At the end of the course students will be able to:

CO1: Ability to understand and analyse predetermination methods of calculating regulation for synchronous generations.

CO2: Acquire hands on experience of conducting various tests on transformers, three phase induction motor and single phase induction motor.

CO3: Ability to acquire knowledge on separation of losses for static and induction motors.

CO4: Ability to understand the concepts related with encitating current, armature current and power factor for a synchronous motor.

CO5: Ability to understand the performance characterizes of AC and DC machines.

CO6: Capability to understand the parameters that control the speed of DC motor.

MAPPING OF CO'S WITH PO'S AND PSO'S

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	3	3	2	1		1				2	3	3	2
CO2	3	3	3	3	2	1		1				2	3	3	2
CO3	3	3	3	3	2	1		1				2	3	3	2
CO4	3	3	3	3	2	1		1				2	3	3	2
CO5	3	2	2	3	2	1		1				2	3	3	2
CO6	2	1	1	-	-	1		1				2	3	3	1
Avg.	3	3	1	1				1.5	1			2.8	3	3	1.6

TIEE3412 MICROPROCESSOR AND MICROCONTROLLER LABORATORY L T P C
0 0 3 1.5

COURSE OBJECTIVES:

- To perform simple arithmetic operations using assembly language program and study the addressing modes & instruction set of 8085 & 8051
- To develop skills in simple program writing in assembly languages
- To write an assembly language program to convert Analog input to Digital output and Digital input to Analog output.
- To perform interfacing experiments with µP8085
- To perform interfacing experiments with µC8051.

PROGRAMMING EXERCISES / EXPERIMENTS WITH µP8085:

1. Simple arithmetic operations: Multi precision addition / subtraction /multiplication / division.
2. Programming with control instructions: Increment / Decrement, Ascending / Descending order, Maximum / Minimum of numbers, Rotate instructions, Hex / ASCII / BCD code conversions.
3. Interface Experiments: A/D Interfacing. D/A Interfacing. Traffic light controller
4. Stepper motor controller interface.
5. Displaying a moving/ rolling message in the student trainer kit's output device.

PROGRAMMING EXERCISES / EXPERIMENTS WITH µC8051:

6. Simple arithmetic operations with 8051: Multi precision addition / subtraction / multiplication/ division.
7. Programming with control instructions: Increment / Decrement, Ascending / Descending. order, Maximum / Minimum of numbers, Rotate instructions, Hex / ASCII / BCD code conversions.
8. Interface Experiments: A/D Interfacing. D/A Interfacing. Traffic light controller
9. Stepper motor controller interface.
10. Displaying a moving/ rolling message in the student trainer kit's output device.
11. Programming PIC architecture with software tools.

TOTAL :45 PERIODS

COURSE OUTCOMES:

After studying the above subject, students should have the:

CO1: Ability to write assembly language program for microprocessor.
CO2: Ability to write assembly language program for microcontroller
CO3: Ability to design and implement interfacing of peripheral with microprocessor and microcontroller
CO4: Ability to analyze, comprehend, design and simulate microprocessor based systems used for control and monitoring..
CO5: Ability to analyze, comprehend, design and simulate microcontroller based systems used for control and monitoring.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	1	2	3				1.5				3	3	1	3
CO2	2	1	2	3				1.5				3	3	1	3
CO3	2	1	2	3				1.5				3	3	1	3
CO4	2	1	2	3				1.5				3	3	1	3
CO5	2	1	2	3				1.5				3	3	1	3
Avg	2	1	2	3				1.5				3	3	1	3

TIEE3501 POWER SYSTEM ANALYSIS L T P C
3 0 0 3

COURSE OBJECTIVES:

- Impact knowledge on need for operational studies, andTo model the power system under steady state operating condition.
- To understand and apply iterative techniques for power flow analysis.
- To model of carry out short circuit studies for power system during symmetrical fault.
- To model of carry out short circuit – studies during
- To study about the various methods for analyzing power system stability

UNIT I POWER SYSTEM 9

Need for system planning and operational studies - Power scenario in India - Power system components, Representation - Single line diagram - per unit quantities - p.u. impedance diagram - p.u. reactance diagram, Network graph Theory - Bus incidence matrices, Primitive parameters, Formation of bus admittance matrix – Direct inspection method – Singular Transformation method.

UNIT II POWER FLOW ANALYSIS 9

Bus classification - Formulation of Power Flow problem in polar coordinates - Power flow solution using Gauss Seidel method - Handling of Voltage controlled buses - Power Flow Solution by Newton Raphson method **–** Flow charts – Comparison of methods.

UNIT III SYMMETRICAL FAULT ANALYSIS 9

Assumptions in short circuit analysis - Symmetrical short circuit analysis using Thevenin's theorem - Bus Impedance matrix building algorithm (without mutual coupling) - Symmetrical fault analysis through bus impedance matrix - Post fault bus voltages - Fault level - Current limiting reactors.

UNIT IV UNSYMMETRICAL FAULT ANALYSIS 9

Symmetrical components - Sequence impedances - Sequence networks - Analysis of unsymmetrical faults at generator terminals: LG, LL and LLG - unsymmetrical fault occurring at any point in a power system.

UNIT V STABILITY ANALYSIS 9

Classification of power system stability – Rotor angle stability - Power-Angle equation – Steady state stability - Swing equation – Solution of swing equation by step by step method - Swing curve, Equal area criterion - Critical clearing angle and time, Multi-machine stability analysis – modified Euler method.

TOTAL : 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students should have the:

CO1: Ability to model the power system under steady state operating condition.
CO2: Ability to carry out power flow analysis using.
CO3: Ability to infer the significance of short circuit studies in designing circuit breakers.
CO4: Ability to analyze the state of the power system for various unsymmetrical faults.
CO5: Ability to analyze the stability of power system using different methods.

TEXT BOOKS:

1. John J. Grainger, William D. Stevenson, Jr, 'Power System Analysis', Mc Graw Hill Education (India) Private Limited, New Delhi, 2017.
2. Kothari D.P. and Nagrath I.J., 'Power System Engineering', Tata McGraw-Hill Education, 3rd edition 2019.
3. Hadi Saadat, 'Power System Analysis', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 21st reprint, 2010.

REFERENCES

1. Pai M A, 'Computer Techniques in Power System Analysis', Tata Mc Graw-Hill Publishing Company Ltd., New Delhi, Second Edition, 2007.
2. J. Duncan Glover, Mulukutla S.Sarma, Thomas J. Overbye, 'Power System Analysis & Design', Cengage Learning, Fifth Edition, 2012.
3. P. Venkatesh, B. V. Manikandan, A. Srinivasan, S. Charles Raja, "Electrical Power Systems: Analysis, Security and Deregulation" Prentice Hall India (PHI), second edition - 2017
4. Gupta B.R., 'Power System - Analysis and Design', S. Chand Publishing, Reissue edition 2005.
5. Kundur P., 'Power System Stability and Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 2013

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03	PS04
CO1	3	2	2	1	1				1				1		2	
CO2	3	3	3	2	1				1				1	1	1	
CO3	3	3	3	2	1				1			1	1	1	1	1
CO4	3	2	2	2	2				1			1	1	1	2	
CO5	3	3	2	2	2				1			1	1	1	1	1
Avg	3	2.6	2.4	1.8	1.4				1			1	1	1	1.4	2

TIEE3502 MEASUREMENTS AND INSTRUMENTATION LT P C
3 0 0 3

COURSE OBJECTIVES

- To educate the fundamental concepts and characteristics of measurement and errors
- To impart the knowledge on the functional aspects of measuring instruments
- To infer the importance of various bridge circuits used with measuring instruments.
- To educate the fundamental working of sensors and transducers and their applications
- To summarize the overall measurement and instrumentation with the knowledge on digital instrumentation principles.

UNIT I CONCEPTS OF MEASUREMENTS 9

Instruments: classification, applications – Elements of a generalized measurement system - Static and dynamic characteristics - Errors in measurement -Statistical evaluation of measurement data.

UNIT II MEASUREMENT OF PARAMETERS IN ELECTRICAL SYSTEMS 9

Classification of instruments – moving coil and moving iron meters – Induction type, dynamometer type watt meters – Energy meter – Megger – Instrument transformers (CT & PT).

UNIT III AC/DC BRIDGES AND INSTRUMENTATION AMPLIFIERS 9

Wheatstone bridge, Kelvin double bridge - Maxwell, Hay, Wien and Schering bridges – Errors and compensation in A.C. bridges - Instrumentation Amplifiers.

UNIT IV TRANSDUCERS FOR MEASUREMENT OF NON- ELECTRICAL PARAMETERS 9

Classification of transducers – Measurement of pressure, temperature, displacement, flow, angular velocity – Digital transducers – Smart Sensors.

UNIT V DIGITAL INSTRUMENTATION 9

A/D converters: types and characteristics – Sampling, Errors- Measurement of voltage, Current, frequency and phase - D/A converters: types and characteristics- DSO- Data Loggers – Basics of PLC programming and Introduction to Virtual Instrumentation - Instrument standards.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon successful completion of the course, the students should have the:
CO1: Ability to understand the fundamental art of measurement in engineering.
CO2: Ability to understand the structural elements of various instruments.

CO3: Ability to understand the importance of bridge circuits.
CO4: Ability to understand about various transducers and their characteristics by experiments.
CO5: Ability to understand the concept of digital instrumentation and virtual instrumentation by experiments.

TEXT BOOKS:

1. A.K. Sawhney, Puneet Sawhney 'A Course in Electrical & Electronic Measurements & Instrumentation', Dhanpat Rai and Co, New Delhi, Edition 2011.
2. H.S. Kalsi, 'Electronic Instrumentation', Tata McGraw-Hill, New Delhi, 2010

REFERENCES:

1. M.M.S. Anand, 'Electronics Instruments and Instrumentation Technology', Prentice Hall India, New Delhi, 2009
2. J.J. Carr, 'Elements of Electronic Instrumentation and Measurement', Pearson Education India, New Delhi, 2011
3. W.Bolton, Programmable Logic Controllers, 6th Edition, Elseiver, 2015.
4. R.B. Northrop, 'Introduction to Instrumentation and Measurements', Taylor & Francis, New Delhi, 3rd Edition 2014.
5. E. O. Doebelin and D. N. Manik, "Measurement Systems – Application and Design", Tata McGraw-Hill, New Delhi, 6th Edition 2017.
6. R. K. Rajput, "Electrical and Electronics Measurements and Instrumentation", Chand Pub, 2016

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	2	3		3	2		2				3	3	3	3
CO2	3	2	3	2						3		3	3	3	3
CO3	3	2	3		3	2						3	3	3	3
CO4	3	2	3					2					3	3	3
CO5	3	2	3	2	3					3		3	3	3	3
Avg	3	2	3	2	3	2		2		3		3	3	3	3

TIEE3503 **CONTROL SYSTEMS** **LT P C**
3 0 0 3

COURSE OBJECTIVES:

- To make the students to familiarize with various representations of systems.
- To make the students to analyze the stability of linear systems in the time domain and frequency domain.
- To make the students to analyze the stability of linear systems in the frequency domain.
- To make the students to design compensator based on the time and frequency domain specifications.
- To develop linear models: mainly state variable model and Transfer function model

UNIT I MODELING OF LINEAR TIME INVARIANT SYSTEM (LTIV) 9

Control system: Open loop and Closed loop – Feedback control system characteristics – First principle modeling: Mechanical, Electrical and Electromechanical systems – Transfer function representations: Block diagram and Signal flow graph.

UNIT II TIME DOMAIN ANALYSIS 9

Standard test inputs – Time response – Time domain specifications – Stability analysis: Concept of stability – Routh Hurwitz stability criterion – Root locus: Construction and Interpretation. Effect of adding poles and zeros

UNIT III FREQUENCY DOMAIN ANALYSIS 9

Bode plot, Polar plot and Nyquist plot: – Frequency domain specifications Introduction to closed loop Frequency Response. Effect of adding lag and lead compensators.

UNIT IV STATE VARIABLE ANALYSIS 9

State variable formulation – Non uniqueness of state space model – State transition matrix –Eigen values – Eigen vectors - Free and forced responses for Time Invariant and Time Varying Systems – Controllability – Observability

UNIT V DESIGN OF FEED BACK CONTROL SYSTEM 9

Design specifications – Lead, Lag and Lag-lead compensators using Root locus and Bode plot techniques –PID controller - Design using reaction curve and Ziegler-Nichols technique- PID control in State Feedback form.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Represent simple systems in transfer function and state variable forms.
CO2: Analyze simple systems in time domain.
CO3: Analyze simple systems in frequency domain.
CO4: Infer the stability of systems in time and frequency domain.
CO5: Interpret characteristics of the system and find out solution for simple control problems.

TEXT BOOKS:

1. Benjamin C. Kuo, “Automatic Control Systems”, 7th edition PHI Learning Private Ltd, 2010.
2. Nagarath, I.J. and Gopal, M., “Control Systems Engineering”, New Age International Publishers 2010.

REFERENCES:

1. Richard C.Dorf and Bishop, R.H., “Modern Control Systems”, Education Pearson, 3 Impression 2009.
2. John J.D., Azzo Constantine, H. and Houpis Sttuart, N Sheldon, “Linear Control System Analysis and Design with MATLAB”, CRC Taylor& Francis Reprint 2009.
3. Katsuhiko Ogata, “Modern Control Engineering”, PHI Learning Private Ltd, 5thEdition, 2010
4. NPTEL Video Lecture Notes on “Control Engineering” by Prof.S.D.Agashe, IIT Bombay.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3			1				3	3	3	3
CO2	3	3	3	3	3			1				3	3	3	3
CO3	3	3	3	3	3			1				3	3	3	3
CO4	3	3	3	3	3			1				3	3	3	3
CO5	3	3	3	3	3			1				3	3	3	3
Avg.	3	3	3	3	3			1				3	3	3	3

TIEE3511 CONTROL AND INSTRUMENTATION LABORATORY LT P C
0 0 4 2

COURSE OBJECTIVES:

- To make the students familiarize with various representations of systems.
- To make the students analyze the stability of linear systems in the time domain and frequency domain.
- To make the students design compensator based on the time and frequency domain Specifications.
- To develop linear models mainly state variable model and transfer function model
- To make the students to design a complete closed loop control system for the physical systems.

LIST OF EXPERIMENTS:

1. Analog (op amp based) simulation of linear differential equations.
2. Numerical Simulation of given nonlinear differential equations.
3. Real time simulation of differential equations.
4. Mathematical modeling and simulation of physical systems in at least two fields.
   - Mechanical
   - Electrical
   - Chemical process
5. System Identification through process reaction curve.
6. Stability analysis using Pole zero maps and Routh Hurwitz Criterion in simulation platform.
7. Root Locus based analysis in simulation platform.
8. Determination of transfer function of a physical system using frequency response and Bode's asymptotes.
9. Design of Lag, lead compensators and evaluation of closed loop performance.
10. Design of PID controllers and evaluation of closed loop performance.
11. Discretization of continuous system and effect of sampling.
12. Test of controllability and observability in continuous and discrete domain in simulation platform.
13. State feedback and state observer design and evaluation of closed loop performance.
14. Mini Project 1: Simulation of complete closed loop control systems including sensor and actuator dynamics.
15. Mini Project 2: Demonstration of a closed loop system in hardware.

TOTAL :60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will demonstrate the ability

CO1: To model and analyze simple physical systems and simulate the performance in analog and digital platform.

CO2: To design and implement simple controllers in standard forms.

CO3: To design compensators based on time and frequency domain specifications.

CO4: To design a complete closed control loop and evaluate its performance for simple physical systems.

CO5: To analyze the stability of a physical system in both continuous and discrete domains.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3			1.5				2	3	3	3
CO2	3	3	3	3	3			1.5				2	3	3	3
CO3	3	3	3	3	3			1.5				2	3	3	3
CO4	3	3	3	3	3			1.5				2	3	3	3
CO5	3	3	3	3	3			1.5				2	3	3	3
Avg	3	3	3	3	3			1.5				2	3	3	3

TIEE3601 **POWER ELECTRONICS** **LT P C**
3 0 0 3

COURSE OBJECTIVES:

- To understand the various applications of power electronic devices for conversion, control and conditioning of the electrical power and to get an overview of different types of power semiconductor devices and their dynamic characteristics.
- To understand the operation, characteristics and performance parameters of controlled rectifiers
- To study the operation, switching techniques and basic topologies of DC-DC switching regulators.
- To learn the different modulation techniques of pulse width modulated inverters and to understand harmonic reduction methods.
- To study the operation of AC voltage controller and various configurations of AC voltage controller.

UNIT I SWITCHING POWER SUPPLIES **9**

MOSFET dynamic behavior - driver and snubber circuits - low power high switching frequency switching Power supplies, buck, boost, buck-boost converters – Isolated topologies – resonant converters - switching loss calculations and thermal design.

UNIT II INVERTERS **9**

IGBT: Static and dynamic behavior - single phase half bridge and full bridge inverters - VSI :(1phase and three phase inverters square wave operation) - Voltage control of inverters single, multi pulse, sinusoidal, space vector modulation techniques– various harmonic elimination techniques-CSI

UNIT III UNCONTROLLED RECTIFIERS **9**

Power Diode – half wave rectifier – mid-point secondary transformer based full wave rectifier – bridge rectifier – voltage doubler circuit – distortion factor – capacitor filter for low power rectifiers – LC filters – Concern for power quality – three phase diode bridge.

UNIT IV CONTROLLED RECTIFIERS **9**

SCR-Two transistor analogy based turn- ON – turn ON losses – thermal protection – controlled converters (1 pulse, 2 pulse, 3 pulse, 6 pulse) - displacement factor – ripple and harmonic factor - power factor mitigation, performance parameters – effect of source inductance - inverter angle limit.

UNIT V AC PHASE CONTROLLERS **9**

TRIAC triggering concept with positive and negative gate pulse triggering, TRIAC based phase controllers - various configurations for SCR based single and three phase controllers.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Understand the operation of semiconductor devices and dynamic characteristics and to design &analyze the low power SMPS

CO2: Analyze the various uncontrolled rectifiers and design suitable filter circuits

CO3: Analyze the operation of the n-pulse converters and evaluate the performance parameters

CO4: Understand various PWM techniques and apply voltage control and harmonic elimination methods to inverter circuits.

CO5: Understand the operation of AC voltage controllers and its applications.

TEXT BOOKS:

1. Ned Mohan, T.M.Undeland, W.P.Robbins, "Power Electronics: Converters, applications and design", John Wiley and Sons, 3rd Edition (reprint), 2009
2. Rashid M.H., Power Electronics Circuits, Devices and Applications, Prentice Hall India, 3rd Edition, New Delhi, 2004.

REFERENCES:

1. Cyril. W.Lander, Power Electronics, McGraw Hill International, Third Edition, 1993.
2. P.S.Bimbhra, Power Electronics, Khanna Publishers, Third Edition 2003
3. Philip T.Krein, Elements of Power Electronics, Oxford University Press, 2013.
4. P.C.Sen, Power Electronics, Tata McGraw-Hill, 30th reprint, 2008.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3			2	1			3	3	3	3	3
CO2	3	3	3	3				1					3	3	3
CO3	3	3	3	3			2	1			2		3	3	3
CO4	3	3	3	3			1	1			2	3	3	3	3
CO5	3	3	3	3			1	1			2	3	3	3	3
Avg.	3	3	3	3			1.5	1			2.25	3	3	3	3

TIEE3602	PROTECTION AND SWITCHGEAR	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To understand the significance of protection, protection schemes and role of earthing.
- To study the characteristics, functions and application areas of various relays.
- To acquire practical knowledge about common faults in power system apparatus and applying suitable protective schemes.
- To understand the functioning of static relays and Numerical protection concepts.
- To understand the problems associated with circuit breaking and to discuss about various circuit breakers.

UNIT I PROTECTION SCHEMES 9

Significance and need for protective schemes – nature and causes of faults – types of faults Effects of faults - Zones of protection and essential qualities of protection – Types of Protection schemes - Power system Grounding and Methods of Grounding.

UNIT II BASICS OF RELAYS 9

Operating principles of relays –Universal torque equation - R-X diagram –Electromagnetic Relays – Over current, Directional and non-directional, Distance, Differential, Negative sequence and Under frequency relays.

UNIT III OVERVIEW OF EQUIPMENT PROTECTION 9

Current transformers and Potential transformers and their applications in protection schemes - Protection of transformer, generator, motor, bus bars and transmission line.

UNIT IV STATIC RELAYS AND NUMERICAL PROTECTION 9

Static relays – Phase, Amplitude Comparators – Synthesis of various relays using Static comparators – Block diagram of Numerical relays – Over current protection, transformer differential protection, and distantce protection of transmission lines.

UNIT V CIRCUIT BREAKERS 9

Physics of arcing phenomenon and arc interruption – DC and AC circuit breaking – re-striking voltage and recovery voltage - rate of rise of recovery voltage - current chopping - interruption of capacitive current - resistance switching - Types of circuit breakers – air blast, oil, SF6 and vacuum circuit breakers – comparison of different circuit breakers – HVDC Breaker.

TOTAL : 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will have theability to:

CO1: Understand and select proper protective scheme and type of earthing.
CO2: Explain the operating principles of various relays.
CO3: Suggest suitable protective scheme for the protection of various power system apparatus.
CO4: Analyze the importance of static relays and numerical relays in power system protection.
CO5: Summarize the merits and demerits and application areas of various circuit breakers.

TEXT BOOKS:

1. Sunil S.Rao, 'Switchgear and Protection', Khanna Publishers, New Delhi, Four Edition, 2010.
2. Badri Ram ,B.H. Vishwakarma, 'Power System Protection and Switchgear', New Age International Pvt Ltd Publishers, Second Edition 2011.
3. B.Rabindranath and N.Chander, 'Power System Protection and Switchgear', New Age International (P) Ltd., Second Edition, 2018.
4. Arun Ingole, 'Switch Gear and Protection' Pearson Education, 2018.

REFERENCES

1. Y.G.Paithankar and S.R.Bhide, 'Fundamentals of power system protection', Second Edition,Prentice Hall of India Pvt. Ltd., New Delhi, 2013.
2. C.L.Wadhwa, 'Electrical Power Systems', 6th Edition, New Age International (P) Ltd., 2018
3. VK Metha," Principles of Power Systems", S. Chand, Reprint, 2013
4. Bhavesh Bhalja, R.P. Maheshwari, Nilesh G. Chotani,'Protection and Switchgear' Oxford University Press, 2nd Edition 2018.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	2	1	2	1	1	1	1	2		3	1	
CO2	3	1	1	2	1	2	1	1	1	1	2		3	1	
CO3	3	1	1	2	1	2	1	1	1	1	2		3	2	
CO4	3	1	1	2	1	2	1	1	1	1	2		3	2	1
CO5	3	1	1	2	2	2	1	1	1	1	2		3	1	1
Avg.	3	1	1	2	1.2	2	1	1	1	1	2		3	1.4	1

TIEE3603 POWER SYSTEM OPERATION AND CONTROL L T P C
3 0 0 3

COURSE OBJECTIVES:

To impart knowledge on,

- The significance of power system operation and control.
- Real power– frequency interaction and design of power– frequency controller.
- Reactive power– voltage interaction and the compensators for maintaining the voltage profile.
- The generation scheduling and economic operation of power system.
- SCADA and its application for real time operation and control of power systems.

UNIT I INTRODUCTION 9

Power scenario in Indian grid – National and Regional load dispatching centres – Requirements of good power system – Necessity of voltage and frequency regulation – real power vs frequency and reactive power vs voltage control loops - System load variation, load curves – Load forecasting – Computational methods in load forecasting – Load shedding and Islanding – deregulation - Basics of electrical energy tariff.

UNIT II REAL POWER FREQUENCY CONTROL 9

Basics of speed governing mechanisms and modelling – Speed regulation of two generators in parallel Load Frequency Control (LFC) of single area system – Static and dynamic analysis – LFC of two area system –Tie line modelling – Block diagram representation of two area system – Static and dynamic analysis – Tie line with frequency bias control – State variable model – Integration of economic dispatch control with LFC.

UNIT III REACTIVE POWER – VOLTAGE CONTROL 9

Generation and absorption of reactive power – Basics of reactive power control – Automatic Voltage Regulator (AVR) – Brushless AC excitation system – Block diagram representation of AVR loop static and dynamic analysis – Stability compensation – Voltage drop in transmission line – Methods of reactive power injection – Tap changing transformer, SVC and STATCOM for voltage control.

UNIT IV ECONOMIC OPERATION OF POWER SYSTEM 9

Statement of economic dispatch problem – Input and output characteristics of thermal plant incremental COst curve – Optimal operation of thermal units without and with transmission losses (no derivation of transmission loss coefficients) – Lambda–iteration method – Base point and participation factors method. Statement of Unit Commitment (UC) problem – Constraints on UC problem – Solution of UC problem using priority list – Special aspects of short term and long-term hydrothermal scheduling problems.

UNIT V COMPUTER AIDED CONTROL OF POWER SYSTEM 9

Need of computer control of power system – Concept of energy control centers and functions – PMU system monitoring, Data acquisition and controls – System hardware configurations – SCADA and EMS functions – State estimation – Measurements and errors – Weighted least square estimation – Various operating states – State transition diagram.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

On the successful completion of the course, students will be able to:

CO1: Understand the day – to – day operation of power system.
CO2: Model and analyse the control actions that are implemented to meet the minute-to-minute variation of system real power demand.
CO3: Model and analyze the compensators for reactive power control and various devices used for voltage control.
CO4: Prepare day ahead and real time economic generation scheduling.
CO5: Understand the necessity of computer control of power systems.

TEXTBOOKS:

1. Olle. I. Elgerd, 'Electric Energy Systems theory – An introduction', McGraw Hill Education Pvt. Ltd., New Delhi, 2nd edition, 2017.
2. Allen. J. Wood and Bruce F. Wollen berg, 'Power Generation, Operation and Control', John Wiley & Sons, Inc., 3rd edition, 2013.
3. Abhijit Chakrabarti and Sunita Halder, 'Power System Analysis Operation and Control', PHI learning Pvt. Ltd., New Delhi, Fourth Edition, 2018.

REFERENCE BOOKS:

1. Kothari D.P. and Nagrath I.J., 'Power System Engineering', Tata McGraw– Hill Education, Second Edition, Reprint 2018.
2. Hadi Saadat, 'Power System Analysis', McGraw Hill Education Pvt. Ltd., New Delhi, 23rd reprint, 2015.
3. Kundur P., 'Power System Stability and Control, McGraw Hill Education Pvt. Ltd., New Delhi, 12th reprint, 2015.
4. B.M. Weedy, B.J. Cory et al, 'Electric Power systems', Wiley, Fifth Edition, 2012.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	-	-		-		1		-		2	3	3	3
CO2	3	2	1	1		1		2		2		2	3	3	3
CO3	3	2	1	1		1		2		2		2	3	3	3
CO4	3	2	1	1		1		2		2		2	3	1	2.33
CO5	2	1	-	-		-		1		2		2	3	3	3
Avg.	2	1.6	1	1		1		1.6		2		2	3	2.2	2.86

TIEE3611 **POWER ELECTRONICS LABORATORY** **L T P C**
0 0 3 1.5

COURSE OBJECTIVES:

- To study the VI characteristics of SCR, TRIAC, MOSFET and IGBT.
- To analyze the performance of semi converter, full converter, step up, step down choppers by simulation and experimentation.
- To study the behavior of voltage waveforms of PWM inverter applying various modulation techniques.
- To design and analyze the performance of SMPS.
- To study the performance of AC voltage controller by simulation and Experimentation.

LIST OF EXPERIMENTS:

1. Characteristics of SCR and TRIAC.
2. Characteristics of MOSFET and IGBT.
3. AC to DC half controlled converter.
4. AC to DC fully controlled converter.
5. Step down and step up MOSFET based choppers.
6. IGBT based single phase PWM inverter.
7. IGBT based three phase PWM inverter.
8. AC Voltage controller.
9. Switched mode power converter.
10. Simulation of PE circuits (1Φ & 3Φ semi converter, 1Φ & 3Φ full converter, dc-dc converters, ac voltage controllers).

TOTAL :45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Determine the characteristics of SCR, IGBT, TRIAC, MOSFET and IGBT

CO2: Find the transfer characteristics of full converter, semi converter, step up and step down choppers by simulation experimentation.

CO3: Analyze the voltage waveforms for PWM inverter using various modulation techniques.

CO4: Design and experimentally verify the performance of basic DC/DC converter topologies used for SMPS.

CO5: Understand the performance of AC voltage controllers by simulation and experimentation

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3			1.5				3	3	3	3
CO2	3	3	3	3	3			1.5				3	3	3	3
CO3	3	3	3	3	3			1.5				3	3	3	3
CO4	3	3	3	3	3			1.5				3	3	3	3
CO5	3	3	3	3	3			1.5				3	3	3	3
Avg	3	3	3	3	3			1.5				3	3	3	3

TIEE3701 **HIGH VOLTAGE ENGINEERING** **L T P C**
3 0 0 3

COURSE OBJECTIVES:

- Various types of over voltages in power system and protection methods.
- Generation of over voltages in laboratories.
- Measurement of over voltages.
- Nature of Breakdown mechanism in solid, liquid and gaseous dielectrics.
- Testing of power apparatus and insulation coordination.

UNIT I OVER VOLTAGES IN ELECTRICAL POWER SYSTEMS 9

Causes of over voltages and its effects on power system – Lightning, switching surges and temporary over voltages – Reflection and Refraction of Travelling waves- protection against over voltages_ Insulation Coordination.

UNIT II DIELECTRIC BREAKDOWN 9

Properties of Dielectric materials - Gaseous breakdown in uniform and non-uniform fields –Corona discharges – Vacuum breakdown – Conduction and breakdown in pure and commercial liquids, Maintenance of oil Quality – Breakdown mechanisms in solid and composite dielectrics- Applications of insulating materials in electrical equipment.

UNIT III GENERATION AND MEASUREMENTS OF HIGH VOLTAGES AND HIGH CURRENTS 9

Generation of High DC, AC, impulse voltages and currents - Analysis of DC/AC and Impulse generator circuits - Tripping and control of impulse generators**,** Measurement of High voltages and High currents – High Resistance with series ammeter – Dividers - Resistance, Capacitance and Mixed dividers - Peak Voltmeter, Generating Voltmeters, Electrostatic Voltmeters – Sphere Gaps, High current shunts- Digital techniques in high voltage measurement.

UNIT IV HIGH VOLTAGE TESTING & INSULATION COORDINATION 9

High voltage testing of electrical power apparatus- International and Indian standards – Power frequency, impulse voltage and DC testing of Insulators, circuit breakers, bushing, isolators and transformers - Insulation Coordination.

UNIT V APPLICATION IN INDUSTRY 9

Introduction – electrostatic applications- electrostatic precipitation, separation, painting / coating, spraying, imaging, printing, Transport of materials – manufacturing of sand paper – Smoke particle detector – Electrostatic spinning, pumping, propulsion – Ozone generation – Biomedical applications.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Explain various overvoltage's and its effects on power systems.

CO2: Understand the breakdown phenomena in different medium under uniform and non-uniform fields.

CO3: Explain the methodsof generating and measuring High DC, AC, Impulse voltage and currents.
CO4: Suggest and Conduct suitable HV testing of Electrical power apparatus as per Standards
CO5: Explain the Industrial Applications of Electrostatic Fields.

TEXT BOOKS

1. M.S.Naidu and V. Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth Edition, 2013.
2. E. Kuffel and W.S. Zaengl, J.Kuffel, 'High voltage Engineering fundamentals', Newnes Second Edition, Elsevier , New Delhi, 2005.
3. C.L. Wadhwa, 'High voltage Engineering', New Age International Publishers, Fourth Edition, 2020.

REFERENCES

1. L.L.Alston, High Voltage Technology, Oxford University Press, First Indian Edition 2006.
2. C.L.Wadhwa, High voltage Engineering, New Age International Publishers, Fourth Edition, 2020
3. Mazen Abdel – Salam, Hussein Anis, Ahdab A-Morshedy, RoshdayRadwan, High Voltage Engineering – Theory &Practice,Second Edition, Taylor & Francis Gourp, 2019
4. Subir Ray." An Introduction to High Voltage Engineering "PHI Learning Private Limited, New Delhi, Second Edition-2011

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2		-									3	2	
CO2	3	2		1									3		
CO3	2	2	3	1							2	3	3	2	
CO4	1	2	3	1				1	1			3	3	2	
CO5	2	2	1	-		2					2		3		2
Avg	2	2	2.33	1		2		1	1		2	3	3	2	2

TIEE3702 UTILIZATION AND CONSERVATION OF ELECTRICAL ENERGY **LT P C**
3 0 0 3

COURSE OBJECTIVES:

- To know various electric drives and traction motors with applications
- To introduce the energy saving concept by different ways of illumination.
- To understand the different methods of electric heating and electric welding.
- To know the conversion of solar and wind energies into electrical energy for different applications.
- To study the domestic utilization of electrical energy.

UNIT I ELECTRIC DRIVES AND TRACTION (7+2 Skill) 9

Fundamentals of electric drive - choice of an electric motor - application of motors for particular services traction generator set, traction motors, power transformers - characteristic features of traction motor - systems of railway electrification - electric braking - train movement and energy consumption - traction motor control - track equipment and collection gear.

UNIT II ILLUMINATION (7+2 Skill) 9

Introduction - definition and meaning of terms used in illumination engineering - classification of light sources - incandescent lamps, sodium vapour lamps, mercury vapour lamps, fluorescent lamps – design of illumination systems - indoor lighting schemes - factory lighting halls - outdoor lighting schemes - flood lighting - street lighting - energy saving lamps, LED

UNIT III HEATING AND WELDING (7+2 Skill) 9

Introduction - advantages of electric heating – modes of heat transfer - methods of electric heating - resistance heating - arc furnaces - induction heating - dielectric heating - electric welding – types - resistance welding - arc welding - power supply for arc welding - radiation welding.

Unit IV ENERGY CONSERVATION AND ITS IMPORTANCE (7+2 Skill) 9

Energy conservation act 2001 and its Features-Review of Industrial Energy Conservation-Energy conservation in electrical Industries-Simulation study of energy conservation using power factor controller. (Three phase circuit simulation with and without capacitor)

UNIT V DOMESTIC UTILIZATION OF ELECTRICAL ENERGY (7+2 Skill) 9

House wiring - working principle of air conditioning system, Induction based appliances, Online an OFF line UPS, Batteries - Power quality aspects – nonlinear and domestic loads – Earthing syste for Domestic, Industrial and Substation.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Conter Preparation/Quiz/Surprise Test/Solving Problems) 10

1. Choosing electrical motors for drives and traction applications.
2. A general design procedure for lighting schemes.
3. Design of heating element and study of welding methods.
4. Practical case studies of energy conservation.
5. Power requirement for different domestic appliances.

COURSE OUTCOMES:

At the end of the course, students should have the:

CO1 Ability to choose suitable electric drives for different applications
CO2 Ability to design the illumination systems for energy saving
CO3 Ability to demonstrate the utilization of electrical energy for heating and welding purposes
CO4 Ability to know the effective usage of solar and wind energies for electrical applications
CO5 Ability to do electric connection for any domestic appliance like refrigerator, batter charging circuit for a specific household application.
CO6 To illustrate the need for energy conservation and to simulate three phase powe control.

TEXT BOOKS:

1. N.V. Suryanarayana, "Utilisation of Electric Power", Wiley Eastern Limited, New Ag International Limited, 1994 & Second Edition 2017 Feb.
2. J.B.Gupta, "Utilisation Electric power and Electric Traction", S.K.Kataria and sons, 200(2012th Edition, 2013, January.
3. G.D.Rai,"Non-Conventional Energy sources",Khanna publications Ltd.,New Delhi 1998
4. D.P.Kothari, K.C.Singal, Rakesh Ranjan, "Renewable Energy Sources and Emergin Technologies", PHI Learing Private Limited, 3rd Edition 2022.
5. Industrial Energy Conservation, Volume I-II, S C Bhatia, Sarvesh Devraj, Energy conservation and Managment by Akshay A pujara1st edition, June 2018.

REFERENCES:

1. R.K.Rajput, Utilisation of Electric Power, Laxmi publications 2nd Edition 2016.
2. H.Partab, Art and Science of Utilisation of Electrical Energy", Edition, Dhanpat Rai and Co New Delhi-2004.
3. C.L.Wadhwa, "Generation, Distribution and Utilisation of Electrical Energy", New Ag international Pvt.Ltd., 3rd Edition, 2015 January.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	2	1		1		1.5					3		
CO2	2	1	3					1.5					3		
CO3	3	2	2			1		1.5					3		
CO4	1	2	3					1.5					3		
CO5	1	1	3			1		1.5					3	3	2
CO6	3	3	3					1.5					3	3	3
Avg	2.2	2	2.6	1		1		1.5					3	3	2.5

TIEE3703	ELECTRIC VEHICLE ARCHITECTURE	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To learn the structure of Electric Vehicle, Hybrid Electric Vehicle
- To study about the EV conversion components
- To know about the details and specifications for Electric Vehicles
- To understand the concepts of Plug-in Hybrid Electric Vehicle
- To model and simulate all types of DC motors

UNIT I VEHICLE MECHANICS (7+2 Skill) 9

Vehicle mechanics- Roadway fundamentals, Laws of motion, Vehicle Kinetics, Dynamics of vehicle motion, propulsion power, velocity and acceleration, Tire –Road mechanics, Propulsion System Design.

UNIT II VEHICLE ARCHITECTURE and SIZING (7+2 Skill) 9

Electric Vehicle History, and Evolution of Electric Vehicles. Series, Parallel and Series parallel Architecture, Micro and Mild architectures. Mountain Bike - Motorcycle- Electric Cars and Heavy Duty EVs. -Details and Specifications

UNIT III POWER COMPONENTS AND BRAKES (7+2 Skill) 9

Power train Component sizing- Gears, Clutches, Differential, Transmission and Vehicle Brakes. EV power train sizing, HEV Powertrain sizing, Example.

UNIT IV HYBRID VEHICLE CONTROL STRATEGY (7+2 Skill) 9

Vehicle supervisory controller, Mode selection strategy, Modal Control strategies.

UNIT V PLUG-IN HYBRID ELECTRIC VEHICLE (7+2 Skill) 9

Introduction-History-Comparison with electrical and hybrid electrical vehicle-Construction and working of PHEV-Block diagram and components-Charging mechanisms-Advantages of PHEVs.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / etc) Basics of MATLAB simulation 10

1. Variables and Expressions Formats, Vectors and Matrices,
2. Arrays, Vectors,
3. Matrices, Built-in functions, Trigonometric functions,
4. Data types and Plotting.
5. Simulation of drive cycles.

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: Summarize the History and Evolution of EVs, Hybrid and Plug-In Hybrid EVs
CO2: Describe the various EV components
CO3: Describe the concepts related in the Plug-In Hybrid Electric Vehicles
CO4: Analyse the details and Specifications for the various EVs developed.
CO5: Describe the hybrid vehicle control strategy.

REFERENCES:

1. Mehrdad Ehsani, YiminGao, Sebastian E. Gay, Ali Emadi, 'Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design', CRC Press, 2004.
2. Build Your Own Electric Vehicle,Seth Leitman , Bob Brant, McGraw Hill, Third Edition 2013.
3. Advanced Electric Drive Vehicles, Ali Emadi, CRC Press, First edition 2017.
4. The Electric Vehicle Conversion Handbook: How to Convert Cars, Trucks, Motorcycles, and Bicycles -- Includes EV Components, Kits, and Project Vehicles Mark Warner, HP Books, 2011.
5. Heavy-duty Electric Vehicles from Concept to Reality, Shashank Arora, Alireza Tashakori Abkenar, Shantha Gamini Jayasinghe, Kari Tammi, Elsevier Science, 2021
6. Electric Vehicles Modern Technologies and Trends, Nil Patel, Akash Kumar Bhoi, Sanjeevikumar Padmanaban, Jens Bo Holm-Nielsen Springer, 2020
7. Hybrid Electric Vehicles: A Review of Existing Configurations and Thermodynamic Cycles, Rogelio León , Christian Montaleza , José Luis Maldonado , MarCOs Tostado-Véliz and Francisco Jurado, Thermo, **2021**, 1, 134–150. https://doi.org/10.3390/thermo1020010.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		2					1				2	3		
CO2	3		2					1				2	3	3	3
CO3	3		2					1				2	3		
CO4	3		2					1				2	3		
CO5	3		3	3	3			1				2	3	3	3
Avg	3		2.2	3	3			1				2	3	3	3

TIEE3811	PROJECT WORK / INTERNSHIP	L	T	P	C
		0	0	6	3

COURSE OBJECTIVES:

The student should be made to learn methodology to select a good project and able to work in a team leading to development of hardware/software product.prepare a good technical report. Gain Motivation to present the ideas behind the project with clarity.

A Project topic must be selected either from research literature or the students themselves may propose suitable topics in consultation with their guides. The aim of the project work is to deepen Comprehension of principles by applying them to a new problem which may be the design /fabrication of any power component / circuit / sensor / Activator / Controller, a research investigation, a computer or management project or a design problem. The progress of the project is evaluated based on a minimum of two reviews. The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated jointly by external and internal examiners constituted by the Head of the Department based on oral presentation and the project report.

TOTAL : 90 PERIODS

COURSE OUTCOMES:

CO1 Ability to identify, formulate, design, interprete,analyze and provide solutions to complex engineering and societal issues by applying knowledge gained on basics of science and Enginnering.

CO2 Ability to choose, conduct and demonstrate a sound technical knowledge of their selected project topics in the field of power components, protection, highvoltage, electronics, process automation, power electronics and drives instrumentation and control by exploring suitable engineering and IT tools.

CO3 Ability to understand, formulate and propose new learning algorithms to solve engineering and societal problems of moderate complexity through multidisciplinary projectsunderstanding commitment towards sustainable development.

CO4 Ability to demonstrate, prepare reports, communicate and work in a team as a member/leader by adhering to ethical responsibilities.

CO5 Ability to acknowledge the value of continuing education for oneself and to stay up with technology advancements.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	-	-	-	-	-	-	-	-	3	3	3
CO2	-	-	-	-	3	3	-	-	-	-	-	-	3	-	-
CO3	-	-	-	-	-	-	3	-	3	-	-	-	-	-	3
CO4	-	-	-	-	-	-	-	3	3	3	3	-	-	-	3
CO5	-	-	-	-	-	-	-	-	-	-	-	3	3	3	3
AVg.	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3

1-low, 2-medium, 3-high, '-"- no correlation

POWER ENGINEERING

TIEE3001	UNDERGROUND CABLE ENGINEERING	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

To impart knowledge on the following topics

- Understanding Power Cable Characteristics and Applications.
- Cable Manufacturing.
- Installation of underground power cables
- Underground cable System Fault Locating.
- Testing and maintenance of Underground cable system.
- Cable Performance and Field Assessment of Power Cables

UNIT I INTRODUCTION TO ELECTRICAL POWER CABLES (7+2 SKILL) 9

Development of Underground Cables - Electric Lighting- Distribution of Energy for Lighting- - Paper Insulated Cables - Underground Residential Distribution Systems- Underground Residential Distribution Systems- Medium Voltage Cable Development.

UNIT II CABLE ARCHITECHTURE, DIELECTRIC THEORY AND CABLE CHARACTERISTICS (7+2 SKILL) 9

Architecture of Underground Cabling System - Basic Dielectric Theory of Cable – Conductors -Armour and Protective Finishes - Cable Characteristics: Electrical- Fundamentals of Electrical Insulation Materials - Electrical Properties of Cable Insulating Materials - Cable Standards and Quality Assurance - Cable design parameters- Current Carrying Capacity - Short-circuit Ratings.

UNIT III SUPPLY DISTRIBUTION SYSTEMS AND CABLES(7+2 SKILL) 9

Supply Distribution Systems - Distribution Cable Types, Design and Applications - Paper Insulated Distribution Cables - PVC Insulated Cables - Polymeric Insulated Distribution Cables for 6-30 kV - Manufacture of Distribution Cables - Joints and Terminations for Distribution Cables - Testing of Distribution Cables.

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UNIT IV TRANSMISSION SYSTEMS AND CABLES(7+2 SKILL) 9

Basic Cable Types for A.C. Transmission - Self-contained Fluid-filled Cables - Gas Pressure Cables - High Pressure Fluid-filled Pipe Cables - Polymeric Insulated Cables for Transmission Voltages - Techniques for Increasing Current Carrying Capacity - Transmission Cable Accessories and Jointing for Pressure-assisted and Polymeric Cables.

UNIT V CABLE INSTALLATION, TESTING, MAINTENANCE(7+2 SKILL) 9

Installation of Transmission Cables -Splicing, Terminating, and Accessories - Sheath Bonding and Grounding-Testing of Transmission Cable Systems - Underground System Fault Locating - Field Assessment of Power Cable Systems- Condition monitoring tests – PD measurements.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (GROUP SEMINAR/ MINI PROJECT/ ASSIGNMENT/ CONTENT PREPARATION/ QUIZ/ SURPRISE TEST /SOLVING GATE QUESTIONS /ETC. 10

1. Demonstration of cable architecture with cable samples of all types.
2. Understanding the cable manufacturing process through factory visit.
3. Familiarization of the cable laying procedure through field visits.
4. Familiarization of cable jointing / end termination techniques.
5. Understanding and familiarization of cable fault locating techniques through field visit to local distribution company or inhouse laboratory.
6. Understanding testing procedures and condition monitoring tests.

COURSE OUTCOMES:

CO1 Ability to understand the fundamental of underground cable system.

CO2 Ability to gain knowledge on the architecture of UG cable and physical and electrical characteristics of the UG cable.

CO3 Ability to understand different types of cable used in distribution system.

CO4 Ability to acquire knowledge on Underground cables used in transmission system

CO5 Ability to understand the cable installations procedures and practices.

CO6 Ability to understand the theory / methodology of cable fault detection and rectification, testing and maintenance.

TEXT BOOKS:

1. William Thue, 'Electrical Power Cable Engineering', CRC Press Taylor & Francis Group., 6000 Broken Sound Parkway NW, Suite 300Boca Raton, FL 33487-2742, 3rd Edition 2017.

2. G. F. Moore, 'Electric Cables Handbook' -Third edition, Blackwell Science Ltd, 9600 Garsington Road, Oxford OX4 2DQ, UK., January 2017.

REFERENCES:

1. Leonard L. Grigsby, 'Electrical Power Cable Engineering' - CRC Press, Marcel Dekker, 3rd Edition 2012.
2. Christian Flytkjaer Jensen, Online Location of Faults on AC Cables in Underground Transmission Systems (Springer Theses), 2014, March.
3. https://kafactor.com/content/technical-resources/kerite-underground-cable-engineering-handbook.pdf
4. Handbook on Cable Fault Localization (April 2020) https://rdso.indianrailways.gov.in/works/uploads/File/Handbook%20on%20Cable%20Fault%20Localization(2).pdf
5. K. H. Ali et al.: Industry Practice Guide for Underground Cable Fault-Finding in the LVDN: https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9807279, June 2022.
6. R. W. Deltenre, J. J. Schwarz, and H. J. Wagnon, ''Underground cable fault location: A handbook to TD-153,'' BDM Corp., Albuquerque, NM, USA, Final Rep. EPRI EL-363, 1977. [Online]. Available: https://www.osti.gov/servlets/purl/7233049, doi: 10.2172/7233049, January 1997.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2					2	1		3	2		3		3
CO2	3	2					2	1		3	2		3		3
CO3	3	2					2	1		3	2		3		3
CO4	3	2					2	1		3	2		3		3
CO5	3	2	3				2	1		3	2		3	3	3
CO6	3	3		3			2	1		3	2		3	3	3
Avg	3	2.1	3	3			2	1		3	2		3	3	3

TIEE3002 **SUBSTATION ENGINEERING AND AUTOMATION** **L T P C 3 0 0 3**

COURSE OBJECTIVES:

- To help engineering students to have a holistic understanding of the concepts behind substation engineering and design.
- The course aims to give an exposure to the students to the requirements of practical aspects including an overview of civil and mechanical aspects.
- Course aims to enhance the knowledge, and give the practical guidelines for site selection,construction, protection along with maintenance, safety in a substation.
- It also aims at providing knowledge about state-of-the-art technology in substation automation system

UNIT I SUBSTATION DESIGN DEVELOPMENT (7+2 SKILL) 9

Substation Introduction and Classifications, Different bus bar switching schemes for Substation. Standards and Practices, Factors Influencing Substation Design - Altitude, Ambient Temperature, Earthquake and seismic zones, pollution and corrosion etc., Testing of Electrical Equipment, Concept and development of Single Line Diagram. Requirement of substation calculation.

UNIT II SUBSTATION EQUIPMENT (7+2 SKILL) 9

Selection and sizing of main substation equipment: Transformer, Isolator, Circuit Breaker, surge arrestor, Instrument transformers, classification of equipment with a practical overview, and the performance parameters. Classifications of MV Switchgear and Key Design Parameters, MV/LV Switchgear construction and design of control scheme. Station Auxiliary equipment: Diesel Generator System, Basics of AC/DC Auxiliary Power System & Sizing of Aux. Transformer, DC System Components, Battery Sizing & charger Sizing, DG Set Classification, and sizing. Introduction to gas insulated substation: Operating principle of GIS, Advantage over AIS, construction of GIS.

UNIT III PROTECTION AND SUBSTATION AUTOMATION (7+2 SKILL) 9

Power System protection, Overcurrent and Earth Fault protection and coordination. Distribution Feeder Protection, Transformer – Unit/Main Protection, Familiarization of NUMERICAL Relays, distance/differential protection for transmission line. Substation Automation: Evolution of Substation Automation, Communication System Fundamentals-Protocol fundamental and choosing the right

protocol. Substation integration and automation functional architecture, Substation signal list - DI, DO, AI, AO– Bay Control Unit (BCU), Remote Terminal Unit RTU.

UNIT IV SUBSTATION DESIGN & LAYOUT ENGINEERING (7+2 SKILL) 9

Layout aspects of Outdoor Air Insulated Substation and GIS: Statutory Clearances, Equipment Layout engineering aspects for Outdoor Substation/GIS and related calculations, and guide lines, Cable routing layout, Erection Key Diagram (EKD), switchyard earthing design as per IEEE80, Importance and Types of Earthing, Earthing Design, Types of Earthing Material, Direct stroke Lightning Protection for switchyard with IS/ IEC 62305. LV Cables - Power & Control, MV Cables, Methods for Cable Installation, Practical aspects of Cable Sizing, Cable accessories, Illumination System Design.

UNIT V INTERFACE ENGINEERING (7+2 SKILL) 9

Civil & Structural Engineering - Familiarization of site development plan, equipment supports structures, foundation for equipment, familiarization of control building and substation building, infrastructure development, Mechanical System- Fire Detection, Alarm System and Fire Suppression System for transformer, Heating, Ventilation and Air-conditioning (HVAC) for Substation.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (GROUP SEMINAR/ MINI PROJECT/ ASSIGNMENT/ CONTENT PREPARATION/ QUIZ/ SURPRISE TEST /SOLVING GATE QUESTIONS /ETC. 10

1.Battery sizing for a substation with a load cycle based on IEEE 1115 Ni-cd - A case study
OR
2.DG and auxiliary transformer sizing for a substation auxiliary power supply- A case study
3.Overcurrent Relay coordination in a substation- A case study
4.Earthmat sizing calculation for an outdoor substation based on IEEE80- A case study
OR
5.Direct stroke lightning protection calculation for outdoor switchyard based on IEC 62305- A case study

COURSE OUTCOMES:

On successful completion of the course student will be able to:
CO 1: Understand the key deciding factors involved in substation design and operation
CO 2: Know about the sizing and selection of equipment which forms part of substation
CO 3: Know about composite layout design aspects of the substation with different services and the challenges including statutory clearances.
CO 4: Understand about Interdisciplinary aspects involved in substation design
CO 5: Understand different protection and control scheme involved in substation design
CO 6: Know about substation automation system and different communication protocol involved for efficient operation of a substation

REFERENCES:

1. McDonald John D, “Electric Power Substations Engineering”, CRC Press, 3rd Edition, 2012
2. Partap Singh Satnam, P.V. Gupta, “Sub-station Design and Equipment”, Dhanpat Rai Publications, 1st Edition, 2013
3. Sunil S. Rao, “Switchgear Protection and Power Systems (Theory, Practice & Solved Problems)”, Khanna Publications, 14th Edition, 2019 .
4. Electrical substation and engineering & practice by S.Rao, 3rd Edition, Khanna Publishers 2015
6. Manual on Substation by Central Board of irrigation and Power (CBIP) Publication No 342., 2006.
7. Substation automation system Design and implementation by Evelio Padilla by Wiley Publications, 1st Edition, 2015 November.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	-	2	1	3	2	-	-	-	3	3		1
CO2	3	3	3	3	2	3	-	1	2	-	-	2	3		1
CO3	3	2	3	3	1	3	-	2	2	-	-	3	3		1
CO4	3	1	2	-	-	3	2	1	2	-	-	2	3		1
CO5	3	3	3	3	-	3	2	1	1	-	-	3	3		1
CO6	-	2	3	3	-	3	-	1	-	-	-	3	3		1
Avg	2.6	2.3	2.6	3	1.6	2.6	2.3	1.3	1.75			2.6	3		1

TIEE3003 **HVDC AND FACTS** **L T P C**
3 0 0 3

COURSE OBJECTIVES:

To understand:

- The problems in AC transmission systems and DC transmission systems
- The operation and control of SVC and TCSC
- The concepts of IGBT based FACTS controllers
- The basic operation Line Commutated Converter(LCC) based HVDC links
- The features of voltage source converter based HVDC link..

UNIT I INTRODUCTION (7+2 Skill) 9

Reactive power control in electrical power transmission lines–load & system compensation, Uncompensated transmission line–shunt and series compensation. Need for HVDC Transmission, Comparison between AC & DC Transmission, , Types of HVDC transmission System.

UNIT II STATIC VAR COMPENSATOR (SVC) AND THYRISTOR CONTROLLED SERIES COMPENSATOR (TCSC) (7+2 Skill) 9

VI characteristics of FC+TSR, TSC+TSR, Voltage control by SVC–Advantages of slope in dynamic characteristics–Influence of SVC on system voltage–Design of SVC voltage regulator, Thyristor Controlled Series Compensator (TCSC), Concept of TCSC, Operation of the TCSC–Different modes of operation, Applications:

UNIT III VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS (7+2 Skill) 9

Static Synchronous Compensator (STATCOM)–Principle of operation–V-I Characteristics. Applications: Steady state power transfer-enhancement of transient stability-prevention of voltage instability. SSSC-operation of SSSC VI characteristics, Enhancement in Power transfer capability –, UPSC – Operation Principle Applications.

UNIT IV LINE COMMUTATED HVDC TRASMISSION (7+2 Skill) 9

Operation of Gratz bridge - Effect of delay in Firing Angle – Effect of commutation overlap - Equivalent circuit,. Basic concept of HVDC transmission. Model of operations and control of power flow CC and CIA mode of operation

UNIT V VSC BASED HVDC TRANSMISSION (7+2 Skill) 9

Basic 2 level IGBT inverter operation- 4 Quadrant operation- phase angle control- dq control- Control of power flow in VSC based HVDC Transmission, Topologies of MTDC system.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Simulation of FC+TSR connected to IEEE 5 bus system
2. Realization of reactive power, support by SVC in open loop and closed loop control in simulation.
3. Regulation of line flows employing TCSC and TSSC in closed loop control in simulation
4. Simulation of two terminal HVDC Link, closed loop control in CC and CIA mode in simulation
5. Realization of four quadrant operation of VSC in open loop mode in simulation

COURSE OUTCOMES:

After completion the above subject, students will be able to understand

CO1: To Identify and understand the problems in AC transmission systems and understand the need for Flexible AC transmission systems and HVDC Transmission

CO2: To understand the operation and control of SVC and TCSC and its applications to enhance the stability and damping.

CO3: To Analyze basic operation and control of voltage source converter based FACTS controllers

CO4: To demonstrate basic operation and control of Line Commutated HVDC Transmission

CO5: To explain the d-q control based operation of VSC based HVDC Transmission

TEXT BOOKS:

1. R.Mohan Mathur, Rajiv K.Varma ,“Thyristor–Based Facts Controllers for Electrical Transmission Systems”, IEEE press andJohnWiley&Sons,Inc,2002.
2. Narain G.Hingorani, “Understanding FACTS-Concepts and Technology of Flexible AC Transmission Systems”, Standard Publishers Distributors,Delhi-110006,2011.

REFERENCES:

1. K.R.Padiyar,”FACTS Controllersin Power Transmission and Distribution”, New Age International (P) Limited, Publishers, New Delhi, 2008
2. A.T.John,“FlexibleA.C.TransmissionSystems”,InstitutionofElectricalandElectronic Engineers(IEEE), 1999.
3. V.K.Sood, HVDC and FACTS controllers–Applications of Static Converters in Power System, APRIL2004,KluwerAcademic Publishers,2004.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03	PS04
CO1	3	3	1	3	1								2	3	3	
CO2	2	3	1	2	3								2	3	3	
CO3	2	3	1	3	1								2	3	3	
CO4	3	3	1	2	3								2	3	3	
CO5	3	3	1	3	1								2	3	3	
Avg	2.6	3	1	2.6	1.8								2	3	3	

TIEE3004 ENERGY MANAGEMENT AND AUDITING L T P C
3 0 0 3

COURSE OBJECTIVES:

- To study the concepts behind economic analysis and Load management.
- To understand the basics of materials and energy balance.
- To analyze the energy efficiency in thermal utilities.
- To know the concept of compressed air system.
- To illustrate the concept of lighting systems and cogeneration.

UNIT I GENERAL ASPECTS OF ENERGY MANAGEMENT AND ENERGY AUDIT (7+2 Skill) 9

Commercial and Non-commercial energy - final energy consumption - energy needs of growing economy - energy pricing - energy conservation and its importance - Re-structuring of the energy supply sector - Energy Conservation Act 2001, Energy Conservation (Amendment) Act, 2010, and its features - electricity tariff - Thermal Basics - need and types of energy audit - Energy management/audit approach- understanding energy COsts - maximizing system efficiencies - optimizing the input energy requirements - energy audit instruments - Case study.

UNIT II MATERIAL AND ENERGY BALANCE (7+2 Skill) 9

Methods for preparing process flow - material and energy balance diagrams - Energy policy purpose - location of energy management - roles and responsibilities of energy manager – employees training and planning- Financial Management: financial analysis techniques, simple payback period, return on investment, net present value, internal rate of return – Case Study.

UNIT III ENERGY EFFICIENCY IN THERMAL UTILITIES (7+2 Skill) 9

Introduction to fuels - properties of fuel oil, coal and gas - principles of combustion - combustion of oil, coal and gas - Boilers: Types, combustion in boilers, performances evaluation, analysis of losses - energy conservation opportunities - FBC boilers - Steam System: Properties of steam, assessment of steam distribution losses, steam leakages, steam trapping, condensate and flash

steam recovery system, identifying opportunities for energy savings - Furnaces: Classification, general fuel economy measures in furnaces, excess air, heat distribution, temperature control, draft control, waste heat recovery – Refractory : types, selection and application of refractories, heat loss - Cogeneration: classification and saving potentials - Case Study.

UNIT IV ENERGY EFFICIENCY IN COMPRESSED AIR SYSTEM (7+2 Skill) 9

Compressed Air System: Types of air compressors - efficient compressor operation - Compressed air system components - leakage test - savings opportunities - Refrigeration System: Vapour compression refrigeration cycle – refrigerants - coefficient of performance - factors affecting Refrigeration and Air conditioning system - savings opportunities - Vapour absorption refrigeration system: working principle - types and comparison with vapour compression system - saving potential - Cooling Tower: Types and performance evaluation, efficient system operation - flow control strategies and energy saving - Diesel Generating system: Factors affecting selection - energy performance assessment of diesel conservation avenues - Case Study.

UNIT V ENERGY EFFICIENCY IN ELECTRICAL UTILITIES (7+2 Skill) 9

Electrical load management and maximum demand control - power factor improvement and its benefit - selection and location of capacitors - performance assessment of PF capacitors - automatic power factor controllers - transformer losses - Electric motors: Types - losses in induction motors - motor efficiency - factors affecting motor performance - rewinding and motor replacement issues - energy saving opportunities with energy efficient motors - soft starters with energy saver - variable speed drives – Fans and blowers: Types - efficient system operation - flow control strategies -Pumps and Pumping System: Types - system operation - flow control methods - Lighting System: Light source, choice of lighting, luminance requirements – ballast - occupancy sensors - energy efficient lighting controls - energy conservation avenues - Case Study.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Study of energy conservation and audit
2. Performance study of Electric Motors.
3. Analysis on fan characteristic curves at different operating points
4. Case study of illumination system
5. Performance analysis of Compressors

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1 Students able to acquire knowledge in the field of energy management and auditing process.

CO2 Learned the about basic concepts of economic analysis and load management.

CO3 Able to design the effective thermal utility system.

CO4 Able to improve the efficiency in compressed air system.

CO5 Acquired the design concepts in the field of lighting systems, light sources and various forms of cogeneration.

TEXTBOOKS:

1. Mehmet Kanoglu, Yunus A Cengel, "Energy Efficiency and Management for Engineers", McGraw-Hill Education, First Edition, 2020.

REFERENCES:

1. Moncef Krati, 'Energy Audit of Building Systems: An Engineering Approach', Third Edition, CRC Press, Dec.2020.
2. Sonal Desai, 'Handbook of Energy Audit', McGraw Hill Education (India) Private Limited, 2015.
3. Michael P.Deru, Jim Kelsey, 'Procedures for Commercial Building Energy Audits', American Society of Heating, Refrigerating and Air conditioning Engineers, 2011.
4. Thomas D.Eastop, 'Energy Efficiency: For Engineers and Technologists', Longman Scientific & Technical, 1990, 1st Edition.
5. 'Energy Managers and Energy Auditors Guide book', Bureau of Energy Efficiency, 2006.
6. Larry C. Witte, Philip S.Schmidt, David R.Brown, 'Industrial Energy Management and Utilization', Springer Berlin Heidelberg, 1988.

List of Open Source Software/ Learning website:

1. http://lab.fs.uni-lj.si/kes/erasmus/Energy%20Management%20Handbook.pdf
2. https://www.sciencedirect.com/science/article/pii/S2212827114004491
3. https://mppolytechnic.ac.in/mp-staff/notes_upload_photo/ CS595EnergyEfficiencyinElectricalUtilities-5391.pdf
4. http://knowledgeplatform.in/wp-content/uploads/2017/03/1.3-Energy-management-Audit.pdf

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2		2				1				2	3	2	3
CO2	3						2	1	3		1	2	3	2	3
CO3	3		1	2	3			1				2	3	2	3
CO4	3	3						1	3			2	3	2	3
CO5	3		1	2				1			2	2	3	2	3
Avg	3	2.5	1	2	3		2	1	3		1.5	2	3	2	3

TIEE3005 **POWER QUALITY** **L T P C**
3 0 0 3

COURSE OBJECTIVES:

- To learn the basic definitions in Power Quality.
- To study the power quality issues in Single Phase and Three Phase Systems.
- To understand the principles of Power System Harmonics.
- To know the way to use DSTATCOM for Harmonic Mitigation.
- To learn the concepts related with Series Compensation.

UNIT I INTRODUCTION (7+2 Skill) 9

Introduction – Characterization of Electric Power Quality: Transients, short duration and long duration voltage variations, Voltage imbalance, waveform distortion, Voltage fluctuations, Power frequency variation, Power acceptability curves – power quality problems: poor load power factor, Non-linear and unbalanced loads, DC offset in loads, Notching in load voltage, Disturbance in supply voltage – Power quality standards.

UNIT II ANALYSIS OF SINGLE PHASE AND THREE PHASE SYSTEM (7+2 Skill) 9

Single phase linear and non-linear loads – single phase sinusoidal, non-sinusoidal source – supplying linear and nonlinear loads – three phase balanced system – three phase unbalanced system – three phase unbalanced and distorted source supplying non-linear loads – concept of power factor – three phase- three wire – three phase - four wire system.

UNIT III MITIGATION OF POWER SYSTEM HARMONICS (7+2 Skill) 9

Introduction - Principle of Harmonic Filters – Series-Tuned Filters – Double Band-Pass Filters – damped Filters – Detuned Filters – Active Filters – Power Converters – Harmonic Filter Design – Tuned Filter – Second-Order Damped Filter – Impedance Plots for Filter Banks – Impedance Plots for a Three-Branch 33 kV Filter.

UNIT IV LOAD COMPENSATION USING DSTATCOM (7+2 Skill) 9

Compensating single – phase loads – Ideal three phase shunt compensator structure – generating reference currents using instantaneous PQ theory – Instantaneous symmetrical components theory – Generating reference currents when the source is unbalanced –Realization and control of DSTATCOM – DSTATCOM in Voltage control mode.

UNIT V SERIES COMPENSATION OF POWER DISTRIBUTION SYSTEM (7+2 Skill) 9

Rectifier supported DVR – DC Capacitor supported DVR – DVR Structure – Voltage Restoration – Series Active Filter – Unified Power Quality Conditioner.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Harmonic analysis of single phase power converters (Semi converters and Full Converters) with R and RL load via simulation
2. Harmonic analysis of three phase power converters (Semi converters and Full Converters) with R and RL load via simulation
3. Harmonic analysis of single phase inverters with R and RL load via simulation
4. Harmonic analysis of three phase inverters with R and RL load via simulation
5. Mitigation of Harmonics using Tuned Filter

List of Open Source Software/ Learning website:

1. http://nptel.iitm.ac.in/courses.php
2. https://old.amu.ac.in/emp/studym/2442.pdf
3. https://electricalacademia.com/electric-power
4. https://www.intechopen.com/books/6214
5. https://www.cde.com/resources/technical-papers/Mitigation-of-Harmonics.pdf

6. https://www.academia.edu/43237017/Use_Series_Compensation_in_Distribution_Networks_33_KV

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1 Use various definitions of power quality for power quality issues

CO2 Describe the concepts related with single phase / three phase, linear / nonlinear loads and single phase / three phase sinusoidal, non-sinusoidal source

CO3 Solve problems related with mitigation of Power System Harmonics

CO4 Use DSTATCOM for load compensation

CO5 Demonstrate the role of DVR, SAFs UPQC in power distribution systems

TEXTBOOKS:

1. Arindam Ghosh and Gerad Ledwich "Power Quality Enhancement Using Custom Power Devices", Kluwer Academic Publishers, First Edition,2002
2. G.T.Heydt, "Electric Power Quality", Stars in a Circle Publications, Second Edition, 2011.
3. George J. Wakileh, "Power System Harmonics – Fundamentals, Analysis and Filter Design", Springer – Verlag Berlin Heidelberg, New York, 2019.

REFERENCES:

1. R.C.Duggan "Electric Power Systems Quality", Tata MC Graw Hill Publishers, Third Edition, 2012.
2. Arrillga "Power System Harmonics", John Wiely and Sons, 2003 2nd Edition.
3. Derek A.Paice "Power Electronic Converter Harmonics" IEEE Press, 1995, Wiley – IEE Press 1999, 18th Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3			3	3		3		3	3	3	3
CO2	3	3	3	3			3	3		3		3	3	3	3
CO3	3	3	3	3			3	3		3		3	3	3	3
CO4	3	3	3	3			3	3		3		3	3	3	3
CO5	3	3	3	3			3	3		3		3	3	3	3
Avg	3	3	3	3			3	3		3		3	3	3	3

TIEE3006	SMART GRID	LT P C
		3 0 0 3

COURSE OBJECTIVES:

- To understand the evolution of Smart and Interconnected energy systems.
- To understand the various challenges and benefits of smart grid and the national and international initiatives taken
- To understand the concepts related with transmission and distribution in smart grid technologies.
- To get an insight of the various smart measurement technologies.
- To understand the various computing technologies for Smart Operation of the Grid.

UNIT I INTRODUCTION (7+2 SKILL) 9

Evolution of Energy Systems, Concept, Definitions and Need, Difference between Conventional & Smart Grid, Drivers, structures, functions, opportunities, challenges and benefits of Smart Grid, Basics of Micro grid, National and International Initiatives in Smart Grid.

UNIT II SMART METERING (7+2 SKILL) 9

Introduction to Advanced Metering infrastructure (AMI) - drivers and benefits, AMI protocols, standards and initiatives, AMI needs in the smart grid, Real time management and control, Phasor Measurement Unit (PMU).

UNIT III SMART GRID TECHNOLOGIES (Transmission) (7+2 SKILL) 9

Technology Drivers, Smart energy resources, Smart substations, Substation Automation, Feeder Automation, Transmission systems: EMS, Wide area Monitoring, Protection and control.

UNIT IV SMART GRID TECHNOLOGIES (Distribution) (7+2 SKILL) 9

DMS, Volt/VAr control, Fault Detection, Isolation and service restoration, Outage management, High-Efficiency Distribution Transformers, Phase Shifting Transformers, Electric Vehicles.

UNIT V HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS (7+2 SKILL) 9

Local Area Network (LAN), House Area Network (HAN), Wide Area Network (WAN), Broadband over Power line (BPL), IP based Protocols, Computing technologies for Smart Grid applications (Web Service to CLOUD Computing), Role of big data and IoT, Cyber Security for Smart Grid.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Assignment-Familiarization of National and International Initiatives in Smart Grid
2. Simulation of smart meter using (MATLAB/ ETAP/SCILAB/ LABVIEW/ Proteus/Equivalent open source software).
3. Visit to a substation for analysing the Automation Technologies like Monitoring, Protection and control.
4. Awareness about High- Efficiency Distribution Transformers, Phase Shifting Transformers in a substation.
5. Introduction to recent technologies in electric vehicles and understanding the operation of EV,HEV and PHEV.
6. Simulation of IoT based digital communication system for smart grid applications.

COURSE OUTCOMES:

After completion the above subject, students will be able to understand

CO1: To be able to understand the importance and objectives of Power System Grid.

CO2: To be able to know and understand the concept of a smart grid;
CO3: To identify and discuss smart metering devices and associated technologies.
CO4: To be able to get an overview of Microgrid and Electric Vehicle Technology.
CO5:To be able to have an up to date knowledge on the various computing technologies; to understand the role of Big Data and IoT for effective and efficient operation of Smart Grid.

TEXT BOOKS:

1. Smart Grids Advanced Technologies and Solutions, Second Edition, Edited by Stuart Borlase,CRC, 2018.
2. Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, “Smart Grid: Technology and Applications”, John Wiley,2012
3. James Momoh ,Smart Grid Fundamentals of Design and Analysis, IEEE press 2012.

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1. Ahmed F. Zobaa, Trevor J. Bihl, Big data analytics in future power systems, 1st Edition, CRC press 2018.
2. C. Gungor et al., "Smart Grid Technologies: Communication Technologies and Standards," in IEEE Transactions on Industrial Informatics, vol. 7, no. 4, pp. 529-539, Nov. 2011.doi: 10.1109/TII.2011.2166794.
3. X. Fang, S. Misra, G. Xue and D. Yang, "Smart Grid — The New and Improved Power Grid: A Survey," in IEEE Communications Surveys & Tutorials, vol. 14, no. 4, pp. 944-980, Fourth Quarter 2012. doi: 10.1109/SURV.2011.101911.00087.
4. Stuart Borlase “Smart Grid : Infrastructure, Technology and Solutions”, CRC Press 2012.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03	PS04
CO1	3	3	2	3	3			1				2	3	3		2
CO2	3	3	2	3	3			1				2	3	3		2
CO3	3	3	2	3	3			1				2	3	3		2
CO4	3	3	2	3	3			1				2	3	3		2
CO5	3	3	2	3	3			1				2	3	3		2
Avg	3	3	2	3	3			1				2	3	3		2

TIEE3007	RESTRUCTURED POWER MARKET	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

Students will be able to:

- Describe various types of deregulated markets in power system.
- Describe the technical and non-technical issues in deregulated power industry.
- Classify different market mechanisms and summarize the role of various entities in the market.
- Analyze the energy and ancillary services management in deregulated power industry.
- Understand the restructuring framework US and Indian power sector

UNIT I INTRODUCTION (7+2 SKILL) 9

Reasons for restructuring - Understanding the restructuring process - objectives of deregulation of various power systems across the world - Consumer behavior - Supplier behavior - Market equilibrium - Short-run and Long-run COsts - Various COsts of production. The Philosophy of Market Models**:** Market models based on contractual arrangements - Market architecture .

UNIT II TRANSMISSION CONGESTION MANAGEMENT (7+2 SKILL) 9

Importance of congestion management in deregulated environment - Classification of congestion management methods - Calculation of ATC - Non-market methods - Market based methods - Nodal pricing - Inter-zonal Intra-zonal congestion management - Price area congestion management - Capacity alleviation method.

UNIT III LOCATIONAL MARGINAL PRICES(LMP) AND FINANCIAL TRANSMISSION RIGHTS (7+2 SKILL) 9

Fundamentals of locational marginal pricing - Lossless DCOPF model for LMP calculation - Loss compensated DCOPF model for LMP calculation - ACOPF model for LMP calculation - Risk Hedging Functionality Of financial Transmission Rights - FTR issuance process - Treatment of revenue shortfall - Secondary trading of FTRs **-** Flow Gate rights - FTR and market power.

UNIT IV ANCILLARY SERVICE MANAGEMENT AND PRICING OF TRANSMISSION NETWORK (7+2 SKILL) 9

Types of ancillary services - Load-generation balancing related services - Voltage control and reactive power support services - Black start capability service - Mandatory provision of ancillary services - Markets for ancillary services - Co-optimization of energy and reserve services - International comparison. Pricing of transmission network**:** wheeling - principles of transmission pricing - transmission pricing methods - Marginal transmission pricing paradigm - Composite pricing paradigm - loss allocation methods.

UNIT V MARKET EVOLUTION (7+2 SKILL) 9

US markets: PJM market - The Nordic power market **-** Reforms in Indian power sector**:** Framework of Indian power sector - Reform initiatives - availability based tariff (ABT) - The Electricity Act 2012 - Open Access issues - Power exchange.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / etc) 10

1. Analysis of ATC calculations using any one of the relevant software tool.
2. DCOPF based LMP calculations using any one of the relevant software tool.
3. ACOPF based LMP calculations using any one of the relevant software tool.
4. Analysis of social welfare maximization with different objectives.

5. Analysis of ABT components.

COURSE OUTCOMES:

Students will be able to:

CO1: describe the requirement for deregulation of the electricity market and the philosophy of various market models
CO2: analyze the various methods of congestion management in deregulated power system
CO3: analyze the locational marginal pricing and financial transmission rights
CO4: analyze the ancillary service management
CO5: analyze transmission pricing paradigm
CO6: understand the evolution of deregulation in Indian power sector

TEXT BOOKS:

1. Mohammad Shahidehpour, Muwaffaq Alomoush, "Restructured electrical power systems: operation, trading and volatility" Marcel Dekker Pub., 2001, 1st Edition.
2. Kankar Bhattacharya, MathH.J.Boolen, and Jaap E.Daadler, "Operation of restructured power systems", Kluwer Academic Pub.,2001, 1st Edition.

REFERENCES:

1. Sally Hunt, "Making competition work in electricity", JohnWilley and Sons Inc. 2002.
2. Steven Stoft, Power System Economics: Designing Markets for Electricity", Wiley-IEEE Press, 2002.
3. Allen. J. Wood and Bruce F. Wollen berg, 'Power Generation, Operation and Control', John Wiley & Sons, Inc., 2016, 3rd Edition.

List of Open Source Software/ Learning website:

1. S.A. Khaparde, A.R. Abhyankar, "Restructured Power Systems", NPTEL Course, https://nptel.ac.in/courses/108101005/.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3					3	2						2		2
CO2	3	2	1			3					2		2		2
CO3	3	2	1			3					2		2		2
CO4	3	2	1			3					2		2		2
CO5	3	2	1			3					2		2		2
CO6	3					3	2	1			2	1			
Avg	3	2	1			3	2	1			2	1	2		2

CONVERTERS AND DRIVES

TIEE3008 SPECIAL ELECTRICAL MACHINES L T P C
2 0 2 3

COURSE OBJECTIVES:

- To understand the working of special machines like stepper motor, switched reluctance motor, BLDC motor & PMSM
- To derive torque equation and study the characteristics of special machines
- To design the controller for special machines
- To study the working principle of synchronous reluctance motor
- To simulate closed loop operation of BLDC motor

UNIT I STEPPER MOTORS 6

Constructional features –Principle of operation –Types – Torque predictions – Linear and Non-linear analysis – Characteristics – Drive circuits – Closed loop control –Applications

UNIT II SWITCHED RELUCTANCE MOTORS 6

Constructional features –Principle of operation- Torque prediction–Characteristics-Power controllers – Control of SRM drive- Speed control-current control-design procedures- Sensor less operation of SRM – Current sensing-rotor position measurement and estimation methods- sensor less rotor position estimation-inductance based estimation –applications.

UNIT III PERMANENT MAGNET BRUSHLESS DC MOTORS 6

Fundamentals of Permanent Magnets- Types- Principle of operation- Magnetic circuit analysis EMF and Torque equations- Characteristics- Controller design-Transfer function –Machine, Load and Inverter-Current and Speed Controller.

UNIT IV PERMANENT MAGNET SYNCHROUNOUS MOTORS 6

Permanent Magnet ac Machines, Machine Configurations, PMSM - Principle of operation – EMF and Torque equations - Phasor diagram - Torque speed characteristics –evaluation of control characteristics- design of current and speed controllers- Constructional features, operating principle and characteristics of synchronous reluctance motor.

UNIT V STUDY OF OTHER SPECIAL ELECTRICAL MACHINES 6

Principle of operation and characteristics of Hysteresis motor – AC series motors – Linear motor – Applications.

30 PERIODS

LAB COMPONENT: 30 PERIODS

Using electromagnetic software

1) Simulation of BLDC motor
2) Simulation of SRM motor
3) Simulation of stepper motor
4) Simulation of PMSM motor
5) Simulation of any other special machines

TOTAL: 30+30 = 60 PERIODS

OURSE OUTCOMES:

CO1 Ability to model and analyze power electronic systems and equipment using computational software.

CO2 Ability to optimally design magnetics required in special machines based drive systems using FEM based software tools.

CO3 Ability to analyse the dynamic performance of special electrical machines

CO4 Ability to understand the operation and characteristics of other special electrical machines.

CO5 Ability to design and conduct experiments towards research.

REFERENCES:

1.Jacek F. Gieras, Dr. Rong-Jie Wang, Professor Maarten J. Kamper - Axial Flux Permanent Magnet Brushless Machines-Springer Netherlands 2008.

2.Bilgin, Berker Emadi, Ali Jiang, James Weisheng - Switched reluctance motor drives: fundamentals to applications-CRC 2019.

3.Ramu Krishnan - Permanent Magnet Synchronous and Brushless DC Motor Drives -CRC Press, Marcel Applications -CRC Press 2009

6.T.Kenjo, ' Stepping motors and their microprocessor controls', Oxford University press, New Delhi, 2000 Dekker 2009

4.T.J.E. Miller, 'Brushless magnet and Reluctance motor drives', Clarendon press, London, 1989

5.R. Krishnan - Switched Reluctance Motor Drives Modeling, Simulation, Analysis, Design, and Applications -CRC Press 2017.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3							1		1		1	3	2	1
CO2	3	3	3	3			2	1		2		3	3	3	3
CO3	3							1		1		1	3	3	3
CO4	3	3	3	3				1		3		3	3	3	3
CO5	3	3	3	3			3	1		3		3	3	3	3
CO6	3	3	3	3	3			1		3		3	3	3	3
Avg	3	3	3	3	3		2.5	1		2.2		2.3	3	2.8	2.6

TIEE3009 ANALYSIS OF ELECTRICAL MACHINES LT P C
2 0 2 3

COURSE OBJECTIVES:

- To model & simulate all types of DC machines
- To develop reference frame equations for various elements like R, L and C
- To model an induction (three phase and 'n' phase) and synchronous machine
- To drive reference frame equations for induction and synchronous machine
- To study the need and working of multiphase induction and synchronous machine

UNIT I MODELING OF BRUSHED-DC ELECTRIC MACHINERY **6**

Fundamentals of Operation – Introduction – Governing equations and modeling of Brushed DC-Motor – Shunt, Series and Compound – State model derivation – Construction of Model of a DC Machine using state equations- Shunt, Series and Compound..

UNIT II REFERENCE FRAME THEORY **6**

Historical background – phase transformation and commutator transformation – transformation of variables from stationary to arbitrary reference frame .

UNIT III INDUCTION MACHINES **6**

Three phase induction machine - equivalent circuit– free acceleration characteristics – voltage and torque equations in machine variables and arbitrary reference frame variables – Simulation under no-load and load conditions- Machine variable form, arbitrary reference variable form.

UNIT IV SYNCHRONOUS MACHINES **6**

Three phase synchronous machine - voltage and torque equations in machine variables and rotor reference frame variables (Park's equations).

UNIT V MULTIPHASE (MORE THAN THREE-PHASE) MACHINES CONCEPTS **6**

Preliminary Remarks - Necessity of Multiphase Machines - Evolution of Multiphase Machines- Advantages of Multiphase Machines - Working Principle - Multiphase Induction Machine, Multiphase Synchronous Machine -Modeling of 'n' phase machine. Applications of Multiphase Machines

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Modeling of DC machines.
2. Simulation under no-load and loaded conditions for a PMDC motor
3. Simulation of smooth starting for DC motor.
4. Simulation under no-load and load conditions of a three phase induction machine in machine variable form and arbitrary reference variable form.
5. Simulation under no-load and load conditions of a three phase synchronous machine in machine variable form and arbitrary reference variable form.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students should be able to:

CO1: Find the modeling for a brushed DC-Motor (Shunt, Series, Compound and separately excised motor) and to simulate DC motors using state models

CO2: Apply reference frame theory for, resistive and reactive elements (three phase)
CO3: Compute the equivalent circuit and torque of three phase induction motor and synchronous motor in machine variable arbitrary reference frame variable
CO4: Find the need and advantages of multiphase machines
CO5: Demonstrate the working of multiphase induction and synchronous machine.
CO6: Compute the model of three phase and multiphase induction and synchronous machine.

REFERENCES:

1. Stephen D. Umans, "Fitzgerald & Kingsley's Electric Machinery", Tata McGraw Hill, 7th Edition, 2020.
2. Bogdan M. Wilamowski, J. David Irwin, The Industrial Electronics Handbook, Second Edition, Power Electronics and Motor Drives, CRC Press, 2011, 1st Edition.
3. Paul C. Krause, Oleg Wasynczuk, Scott D. Sudhoff, Steven D. Pekarek, "Analysis of Electric Machinery and Drive Systems", 3rd Edition, Wiley-IEEE Press, 2013.
4. R. Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Pearson Education, 1st Imprint, 2015, 1st Edition.
5. R.Ramanujam, Modeling and Analysis of Electrical Machines, I.k.International Publishing House Pvt.Ltd,2018.
6. Chee Mun Ong, Dynamic Simulation of Electric Machinery using MATLAB, Prentice Hall, 1997, 1st Edition.
7. Atif Iqbal,Shaikh Moinoddin, Bhimireddy Prathap Reddy, Electrical Machine Fundamentals with Numerical Simulation using MATLAB/SIMULINK, Wiley,2021,1st Edition

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3		2	1		3		2	3	3	3
CO2	3	3	3	3	3		2	1		3		2	3	3	3
CO3	3	3	3	3	3		2	1		3		2	3	3	3
CO4	3				3		2	1		3		2	3	3	3
CO5	3				3		2	1		3		2	3	3	3
CO6	3	3	3	3	3		2	1		3		2	3	3	3
Avg	3	3	3	3	3		2	1		3		2	3	3	3

TIEE3010 MULTILEVEL POWER CONVERTERS

L	T	P	C
2	0	2	3

COURSE OBJECTIVES:

- To learn multilevel topology (Symmetry & Asymmetry) with common DC bus link.
- To study the working of cascaded H Bridge, Diode Clamped and Flying Capacitor MLI.
- To study the working of MLI with reduced switch count.
- To simulate three level diode clamped MLI and three level flying capacitor based MLI with resistive and reactive load
- To simulate the MLI with reduced switch count.

UNIT I **MULTILEVEL TOPOLOGIES** **6**

Introduction – Generalized Topology with a Common DC bus – Converters derived from the generalized topology – symmetric topology without a common DC link – Asymmetric topology.

UNIT II **CASCADED H-BRIDGE MULTILEVEL INVERTERS** **6**

Introduction -H-Bridge Inverter, Bipolar Pulse Width Modulation, Unipolar Pulse Width Modulation. Multilevel Inverter Topologies, CHB Inverter with Equal DC Voltage, H-Bridges with Unequal DC Voltages – PWM, Carrier-Based PWM Schemes, Phase-Shifted Multicarrier Modulation, Level-Shifted Multicarrier Modulation, Comparison Between Phase- and Level-Shifted PWM Schemes-Staircase Modulation

UNIT III **DIODE CLAMPED MULTILEVEL CONVERTER** **6**

Introduction – Converter structure and Functional Description – Modulation of Multilevel converters – Voltage balance Control – Effectiveness Boundary of voltage balancing in DCMC converters – Performance results.

UNIT IV **FLYING CAPACITOR MULTILEVEL CONVERTER** **6**

Introduction – Flying Capacitor topology – Modulation scheme for the FCMC – Dynamic voltage balance of FCMC.

UNIT V **MULTILEVEL CONVERTER WITH REDUCED SWITCH COUNT** **6**

Multilevel inverter with reduced switch count-structures, working principles and pulse generation methods.

30 PERIODS

LAB COMPONENT: **30 PERIODS**

1. Simulation of Fixed PWM, Sinusoidal PWM for an inverter,
2. Simulation of H bridge inverter with R load .
3. Simulation of three level diode clamped MLI with R load.
4. Simulation of three level capacitor clamped MLI with R load
5. Simulation of MLI with reduced switch configuration.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students should be able to:

CO1: Examine the different topologies of multilevel inverters (MLIs) with and without DC link capacitor.

CO2: Examine the performance of MLIs with Bipolar Pulse Width Modulation (PWM) Unipolar PWM Carrier-Based PWM Schemes Phase Level Shifted Multicarrier Modulation

CO3: Demonstrate the working principles of Cascaded H-Bridge MLI, diode clamped MLI, flying capacitor MLI and MLI with reduced switch count

CO4: Analyze the voltage balancing performance in Diode clamped MLI.

CO5: Simulate three level, capacitor clamed and diode clamped MLI with R and RL load.

CO6: Simulate MLI with reduced switch configuration using fundamental switching scheme

TEXT BOOKS:

1. Rashid M.H,"Power Electronics Circuits, Devices and Applications", Prentice Hall India, Third Edition, New Delhi, 2014 Pearson 4th edition.
2. Sergio Alberto Gonzalez, Santiago Andres Verne, Maria Ines Valla,"Multilevel Converters

for Industrial Applications", CRC Press, 22-Jul-2013, 20171st Edition.
3. BinWu, Mehdi Narimani,High Power Converters and AC drives by IEEE press 2017, 2nd Edition.

REFERENCEBOOKS:

1. Thomas A. Lipo, Pulse Width Modulation for Power Converters: Principles and Practice, D.Grahame Holmes, John Wiley & Sons, Oct-2003, 1st Edition.
2. Fang Lin Luo, Hong Ye,Advanced DC/AC Inverters: Applications in Renewable Energy, CRC Press, 22-Jan-2013, 2017, 1st Edition.
3. Hani Vahedi, Mohamed Trabelsi, Single-DC-Source Multilevel Inverters, Springer, 2019, 1st Edition.
4. Ersan Kabalcı, Multilevel Inverters Introduction and Emergent Topologies, Academic Press Inc,2021, 1st Edition.
5. Iftekhar Maswood, Dehghani Tafti,Advanced Multilevel Converters and Applications in Grid Integration, Wiley, 2018, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3			2	1		3		3	3	3	3
CO2	3	2	2	3			2	1		3		3	3	3	3
CO3	3	2	2	3			2	1		3		3	3	3	3
CO4	3	3	3	3			2	1		3		3	3	3	3
CO5	3	3	3	3	3		2	1		3		3	3	3	3
CO6	3	3	3	3	3		2	1		3		3	3	3	3
Avg	3	2.5	2.5	3	3		2	1		3		3	3	3	3

TIEE3011 ELECTRICAL DRIVES L T P C
2 0 2 3

COURSE OBJECTIVES:

At the end of the course, students should have the:

- To understand steady state operation and transient dynamics of a motor load system.
- To study and analyze the operation of the converter / chopper fed dc drive, both qualitatively and quantitatively.
- To study and understand the operation and performance of AC Induction motor drives.
- To study and understand the operation and performance of AC Synchronous motor drives.
- To analyze and design the current and speed controllers for a closed loop solid state DC motor drives.

UNIT I DRIVE CHARACTERISTICS 6

Electric drive – Equations governing motor load dynamics – steady state stability – multi quadrant Dynamics: acceleration, deceleration, starting & stopping – typical load torque characteristics – Selection of motor.

UNIT II CONVERTER / CHOPPER FED DC MOTOR DRIVE 6

Steady state analysis of the single and three phase converter fed separately excited DC motor drive – continuous and discontinuous conduction – Time ratio and current limit control – 4 quadrant operation of converter / chopper fed drive.

UNIT III INDUCTION MOTOR DRIVES 6

Stator voltage control – energy efficient drive – v/f control – constant air gap flux – field weakening mode – voltage / current fed inverter – closed loop control,

UNIT IV SYNCHRONOUS MOTOR DRIVES 6

V/f control and self-control of synchronous motor: Margin angle control and power factor control – permanent magnet synchronous motor.

UNIT V DESIGN OF CONTROLLERS FOR DRIVES 6

Transfer function for DC motor / load and converter – closed loop control with current and speed feedback – armature voltage control and field weakening mode – design of controllers; current controller and speed controller-converter selection and characteristics.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simulation of converter and chopper fed DC drive
2. Simulation of closed loop operation of stator voltage control of induction motor drive
3. Simulation of closed loop operation of v/f control of induction motor drive
4. Simulation of synchronous motor drive

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

After completion the above subject, students will be able to
CO1: Understand the basic requirements of motor selection for different load profiles.
CO2: Analyse the steady state behavior and stability aspects of drive systems.
CO3: Analyse the dynamic performance of the DC drive using converter and chopper control.
CO4: Simulate the AC drive.
CO5: Design the controller for electrical drives.

TEXTBOOKS:

1. Gopal K.Dubey, Fundamentals of Electrical Drives, Narosa Publishing House, 2nd Edition January 2010.
2. Bimal K.Bose. Modern Power Electronics and AC Drives, Pearson Education, 2002 1st Edition.

REFERENCES:

1. S.K.Pillai, A First course on Electrical Drives, Wiley Eastern Limited, 3rd Edition 2012.
2. Murphy J.M.D and Turnbull, Thyristor Control of AC Motor, Pergamon Press, Oxford 1988, 1st Edition.
3. Gopal K.Dubey, Power semiconductor controlled Drives, Prentice Hall Inc., New Jersey,1989, 1st Edition.
4. R.Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Prentice hall of India, 2001, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3	3			1				2	3	3	2
CO2	3	2	2	3	3			1				2	3	3	2
CO3	3	2	2	3	3			1				2	3	3	3
CO4	3	2	2	3	3			1				2	3	3	3
CO5	3	2	2	3	3			1				2	3	3	3
CO6	3	2	2	3	3			1				2	3	3	3
Avg	3	2	2	3	3			1				2	3	3	2

TIEE3012 **SMPS AND UPS** **L T P C**
2 0 2 3

COURSE OBJECTIVES:

- To learn the working of isolated & non-isolated DC-DC converters
- To design isolated & non-isolated DC-DC converters.
- To drive the equations related with converter dynamics.
- To design and simulate P, PI & PID controller for buck, boost and buck-boost converters.
- To identify and study different configurations of the UPS.

UNIT I ANALYSIS OF NON-ISOLATED DC-DC CONVERTERS 6

Basic topologies: Buck, Boost and Buck-Boost - Principles of operation – Continuous conduction mode– Concepts of volt-sec balance and charge balance – Analysis and design based on steady-state relationships – Introduction to discontinuous conduction mode.

UNIT II ANALYSIS OF ISOLATED DC-DC CONVERTERS 6

Introduction - classification- forward- flyback- pushpull – half bridge – full bridge topologies- C'uk converter as cascade combination of boost followed by buck – isolated version of C'uk converter - design of SMPS – Introduction to design of magnetic components for SMPS, using relevant software- Simulation of bidirectional DC DC converter (both non-isolated and isolated) considering EV as an example application.

UNIT III CONVERTER DYNAMICS 6

AC equivalent circuit analysis – State space averaging – Circuit averaging – Transfer function model for buck, boost and buck-boost converters – Simulation of basic topologies using state space model derived – Comparison with the circuit model based simulation already carried out.

UNIT IV CONTROLLER DESIGN 6

Review of P, PI, and PID control concepts – gain margin and phase margin – Bode plot based analysis – Design of controller for buck, boost and buck-boost converters.

UNIT V POWER CONDITIONERS AND UPS 6

Introduction – Power line disturbances – Power conditioners – UPS: Offline and On-line – Need for filters – Filter for PWM VSI – Front-end battery charger – boost charger.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simulation of Basic topologies.
2. Simulation of bidirectional DC DC converter (both non-isolated and isolated) considering
   EV as an example application.
3. Simulation of basic topologies using state space model derived – Comparison with the circuit model based simulation already carried out.
4. Simulation study of controller design for basic topologies.
5. Simulation of battery charger for EV applications.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students should have the following capabilities:

CO1: Demonstrate the working of buck boost and buck- boost converters in continuous and discontinuous conduction mode.

CO2: Build buck/boost converters using suitable design method.

CO3: Analyze the behaviors of isolated DC-DC converters and to design SMPS for battery operated vehicle.

CO4: Compute state space averaged model and transfer function for buck, boost and buck-boost converters.

CO5: Demonstrate the P, PI and PID controller performance analytically and by simulation for buck boost and buck- boost converters.

CO6: Compare the different topologies of UPS and also simulate them.

TEXT BOOKS:

1. Robert W. Erickson & Dragon Maksimovic, " Fundamentals of Power Electronics", Third Edition, 2020
2. Ned Mohan," Power Electronics: A First Course", Johnwiley, 2013.
3. Marian K. Kazimierczuk and Agasthya Ayachit,"Laboratory Manual for Pulse-Width Modulated DC– DC Power Converters", Wiley 2016.
4. Power Electronics handbook, Industrial Electronics series, S.K.Varenina, CRC press, 2002.
5. Power Electronic Converters, Teuvo Suntio, Tuomas Messo, Joonas Puukko, First Edition 2017.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3			3	3		2		3	3	3	3
CO2	3	3	3	3			3	3		2		3	3	3	3
CO3	3	3	3	3			3			3		3	3	3	3
CO4	3	3	3	3						2		3	3	3	3
CO5	3	3	3	3			3	3		3		3	3	3	3
CO6	3	3	3	3			3	3		3		3	3	3	3
Avg	3	3	3	3			3	3		2.5		3	3	3	3

TIEE3013	POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEMS	L T P C 2 0 2 3

COURSE OBJECTIVES:

- To learn the various types of renewable sources of energy.
- To understand the electrical machines to be used for wind energy conversion systems.
- To learn the principles of power converters used in solar PV system.
- To study the principle of power converters used in Wind system.
- To simulate the AC-DC, AC-AC Converters, Matrix Converters and PWM Inverters.

UNIT I INTRODUCTION TO RENEWABLE ENERGY SYSTEMS 6

Classification of Energy Sources – Importance of Non-conventional energy sources – Advantages and disadvantages of conventional energy sources - Environmental aspects of energy - Impacts of renewable energy generation on the environment - Qualitative study of renewable energy resources: Ocean energy, Biomass energy, Hydrogen energy, - Solar Photovoltaic (PV), Fuel cells: Operating principles and characteristics, Wind Energy: Nature of wind, Types, control strategy, operating area.

UNIT II ELECTRICAL MACHINES FOR WIND ENERGY CONVERSION SYSTEMS (WECS) 6

Construction, Principle of operation and analysis: Squirrel Cage Induction Generator (SCIG), Doubly Fed Induction Generator (DFIG) - Permanent Magnet Synchronous Generator (PMSG).

UNIT III POWER CONVERTERS AND ANALYSIS OF SOLAR PV SYSTEMS 6

Power Converters: Line commutated converters (inversion-mode) - Boost and buck-boost converters- selection of inverter, battery sizing, array sizing. Simulation of line commutated converters, buck/boost converters. Analysis: Block diagram of the solar PV systems - Types of Solar PV systems: Stand-alone PV systems, Grid integrated solar PV Systems - Grid Connection Issues.

UNIT IV POWER CONVERTERS FOR WIND SYSTEMS 6

Power Converters: Three-phase AC voltage controllers- AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters, Grid-Interactive Inverters - Matrix converter.

UNIT V HYBRID RENEWABLE ENERGY SYSTEMS 9

Need for Hybrid Systems- Range and type of Hybrid systems- Case studies of Diesel-PV, Wind-PV, Micro hydel-PV, Biomass-Diesel systems - Maximum Power Point Tracking (MPPT).

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simulation on modelling of Solar PV System- V I Characteristics
2. Simulation on Modelling of fuel cell- V I Characteristics
3. Simulation of self- excited Induction Generator.
4. Simulation of DFIG/ PMSG based Wind turbine.
5. Simulation on Grid integration of RES.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students should be able to:

CO1: Examine the available renewable energy sources.

CO2: Demonstrate the working principles of electrical machines and power converters used for wind energy conversion system

CO3: Demonstrate the principles of power converters used for solar PV systems

CO4: Examine the available hybrid renewable energy systems.

CO5: Simulate AC-DC converters, buck/boost converters, AC-AC converters and PWM inverters.

REFERENCES:

1. S.N.Bhadra, D. Kastha, & S. Banerjee "Wind Electrical Systems", Oxford University Press, 2009, 7th impression.
2. Rashid .M. H "Power electronics Hand book", Academic press,2nd Edition, 2006 4th Edition, 2017
3. Rai. G.D, "Non-conventional energy sources", Khanna publishers, 6th Edition, 2017.
4. Rai. G.D," Solar energy utilization", Khanna publishers, 5th Edition, 2008.
5. Gray, L. Johnson, "Wind energy system", prentice hall of india, 2nd Edition, 2006.
6. H.Khan "Non-conventional Energy sources ",Tata McGraw-hill Publishing Company, New Delhi, 2017, 3rd Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		2							2		2	3	3	3
CO2	3		2							2		2	3	3	3
CO3	3		2							2		2	3	3	3
CO4	3		3							2		2	3	3	3
CO5	3	3	2.25	3	3			3		2		3	3	3	3
Avg	3	3	2	3	3			3		2		2.2	3	3	3

TIEE3014 CONTROL OF POWER ELECTRONICS CIRCUITS

L	T	P	C
2	0	2	3

COURSE OBJECTIVES:

- To learn the basics of control system simulation.
- To do symbolic calculation.
- To study the principles of sliding mode control and the way of apply smc for buck converter.
- To learn the concept of power factor correction.
- To design simulate smc for buck converter and power factor correction circuit with controller.

UNIT I SIMULATION BASICS IN CONTROL SYSTEMS 6

Transfer Function-How to build transfer function, identify Poles, zeros, draw time response plots, bode plot (Bode Plots for Multiplication Factors, Constant, Single and Double Integration Functions, Single and Double Differentiation Functions, Single Pole and Single Zero Functions, RHP Pole and RHP Zero Functions), state space modelling-transfer function from state space Model.

UNIT II SYMBOLIC CALCULATIONS 6

Symbolic Variables - Symbolic Vector Variables, Commands for Handling Polynomial Expressions - Extracting Parts of a Polynomial -. Factorization and Roots of Polynomials, Symbolic Matrix Algebra - Operations with Symbolic Matrices - Other Symbolic Matrix Operations.

UNIT III SLIDING MODE CONTROL BASICS 6

Introduction- Introduction to Sliding-Mode Control- Basics of Sliding-Mode Theory- Application of Sliding-Mode Control to DC-DC Converters—Principle-Sliding mode control of buck converter.

UNIT IV POWER FACTOR CORRECTION CIRCUITS 6

Introduction, Operating Principle of Single-Phase PFCs, Control of boost converter based PFCs, Designing the Inner Average-Current-Control Loop, Designing the Outer Voltage-Control Loop, Example of Single-Phase PFC Systems.

UNIT V CONTROLLER DESIGN FOR PFC CIRCUITS 6

Power factor correction circuit using other SMPS topologies: C'uk and SEPIC converter - PFC circuits employing bridgeless topologies.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simulation exercises on zero, first and second order basic blocks.
2. Simulation exercises based on symbolic calculations.
3. Simulation of Sliding mode control based buck converter.
4. Simulation of Single-Phase PFC circuit employing boost converter.
5. Simulation of Single-Phase PFC circuit employing C'uk converters.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students should have the:

CO1: To calculate transfer function for constant, differential, integral, First order and Second order factors.

CO2: To illustrate the effect of poles and zero's in the 's' plane.

CO3: To select Symbolic equations for solving problems related with Matrices, Polynomial and vectors.

CO4: To compute the control expression for DC – DC buck converter using sliding mode control theory.

CO5: To determine the controller expression for power factor correction circuits.

CO6: To simulate sliding mode control of buck converter and power factor correction circuit.

TEXT BOOKS:

1. Feedback Control problems using MATLAB and the Control system tool box By Dean Frederick and Joe Chow, 2000, 1st Edition, Cengage Learning.
2. Ned Mohan,"Power Electronics: A First Course", Johnwiley, 2013, 1st Edition.
3. Marian K. Kazimierczuk and AgasthyaAyachit,"Laboratory Manual for Pulse-Width Modulated DC-DC Power Converters", Wiley 2016, 1st Edition.
4. Power Electronics handbook, Industrial Electronics series, S.K.Varenina, CRC press, 2002, 1st Edition.

REFERENCES:

1. Sliding mode control for Switching Power Converters:, Techniques and Implementation, Slew-Chong Tan, Yuk Ming Lai Chi-Kong Tse, 1st Edition, CRC Press.
2. Andre Kislovski, "Dynamic Analysis of Switching-Mode DC/DC Converters", Springer 1991.
3. MATLAB Symbolic Algebra and Calculus Tools, Lopez Cesar, Apress, 2014.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3			1		2		3	3	3	3
CO2	3	3	3	3	3			1		2		3	3	3	3
CO3	3	3	3	3	3			1		2		3	3	3	3
CO4	3	3	3	3	3			1		2		3	3	3	3
CO5	3	3	3	3	3			1		2		3	3	3	3
CO6	3	3	3	3	3			1		2		3	3	3	3
Avg	3	3	3	3	3			1		2		3	3	3	3

EMBEDDED SYSTEMS

TIEE3015 EMBEDDED SYSTEM DESIGN LT P C
2 0 2 3

COURSE OBJECTIVES:

- To introduce the Building Blocks of an embedded System and Software Tools
- To emphasize the role of Input/output interfacing with Bus Communication protocol.
- To illustrate the ISR and scheduling for the multitasking process.
- To explain the basics of a Real-time operating system
- To analyze the applications based on embedded design approaches

UNIT I INTRODUCTION TO EMBEDDED SYSTEMS 6

Introduction to Embedded Systems –Structural units in Embedded processor, selection of processor & memory devices- DMA — Memory management methods- Timer and Counting devices, Real Time Clock, In-circuit emulator, Target Hardware Debugging.

UNIT II EMBEDDED NETWORKING 6

Embedded Networking: Introduction, I/O Device Ports & Buses– Serial Bus communication protocols RS232 standard – RS485 – CAN Bus- Serial Peripheral Interface (SPI) – Inter-Integrated Circuits (I^2C).

UNIT III INTERRUPTS THE SERVICE MECHANISM AND DEVICE DRIVER 6

Programmed-I/O busy-wait approach without interrupt service mechanism-ISR concept-interrupt sources – multiple interrupts – context and periods for context switching, interrupt latency and deadline – Introduction to Device Drivers.

UNIT IV RTOS-BASED EMBEDDED SYSTEM DESIGN 6

Introduction to basic concepts of RTOS- Task, process & threads, interrupt routines in RTOS, Multiprocessing and Multitasking, Preemptive and non-preemptive scheduling, Task communication- shared memory, message passing- Interprocess Communication- Introduction to process synchronization using semaphores.

UNIT V EMBEDDED SYSTEM APPLICATION DEVELOPMENT 6

Embedded Product Development Life Cycle - Case Study: Precision Agriculture- Autonomous car.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Laboratory exercise: Use any Embedded processor/IDE/open source platform to give hands-on training on basic concepts of embedded system design:
   a) Introduction to IDE and Programming Environment.
   b) Configure timer block for signal generation (with given frequency).
   c) Interrupts programming example using GPIO.
   d) I^2C communication with peripherals

e) Master-slave communication between processors using SPI.
f) Networking of processor using Wi-Fi.
g) Basic RTOS concept and programming

2. Assignment: Introduction to VxWorks, ЧC/OS-II, RT Linux
3. Embedded systems-based Mini project.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

After completion of the above subject, students will be able to understand

CO1: The hardware functionals and software strategies required to develop various Embedded systems
CO2: The basic differences between various Bus communication standards
CO3: The incorporation of the interface as Interrupt services
CO4: The various scheduling algorithms through a Real-time operating system.
CO5: The various embedded concepts for developing automation applications.

TEXTBOOKS:

1. Rajkamal, 'Embedded system-Architecture, Programming, Design, McGraw-Hill Edu, 3rd edition 2017
2. Peckol, "Embedded system Design", John Wiley & Sons,2010.

REFERENCES:

1. Shibu. K.V, "Introduction to Embedded Systems", TataMcgraw Hill, 2nd edition 2017.
2. Lya B.Das," Embedded Systems" ,Pearson Education, 1st edition 2012.
3. Parag H.Dave,Himanshu B.Dave," Embedded Systems-Concepts ,Design and Programming, Pearson Education,2015, 1st edition.
4. Elicia White, "Making Embedded systems", O'Reilly Series ,SPD,2011, 1st edition.
5. Jonathan W. Valvano, 'Embedded Microcomputer Systems Real-time Interfacing', Cengage Learning , 3rd edition 2010.
6. Tammy Noergaard, "Embedded Systems Architecture", Newnes, 2nd edition, 2013.

List of Open Source Software/ Learning websites:

1. https://nptel.ac.in/courses/108102045
2. https://ece.uwaterloo.ca/~dwharder/icsrts/Lecture_materials/A_practical_introduction_to_real-time_systems_for_undergraduate_engineering.pdf
3. https://www.circuitbasics.com/basics-of-the-i2c-communication-protocol/
4. https://www.tutorialspoint.com/embedded_systems/es_interrupts.htm
5. https://www.theengineeringprojects.com/2016/11/examples-of-embedded-systems.html#:~:text=Embedded%20Product%3A%20Automatic%20Washing%20Machine,done%20by%20your%20machine%20itself.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	1								2	2	3
CO2	3	2	3	2	1								2	1	3
CO3	3	3	2	3	1								2	1	2
CO4	3	2	2	2	1								1	2	3
CO5	3	2	1	2	1				1				3	1	2
Avg	3	2.2	2	2.2	1				1				2	1.4	2.6

TIEE3016 **EMBEDDED C- PROGRAMMING** **LT P C**
2 0 2 3

COURSE OBJECTIVES:

- To expose the students to the fundamentals of embedded Programming
- To Introduce the GNU C Programming Tool Chain.
- To study the basic concepts of embedded C.
- To teach the basics of 8051 Programming
- To involve Discussions/ Practice/Exercise in revising & familiarizing the concepts acquired over the 5 Units of the subject for improved employability skills.

UNIT I BASIC C PROGRAMMING 6

Typical C Program Development Environment - Introduction to C Programming - Structured Program Development in C - Data Types and Operators - C Program Control - C Functions - Introduction to Arrays.

UNIT II EMBEDDED C 6

Adding Structure to 'C' Code: Object-oriented programming with C, Header files for Project and Port, Examples. Meeting Real-time constraints: Creating hardware delays - Need for timeout mechanism - Creating loop timeouts - Creating hardware timeouts.

UNIT III 8051 Programming in C 6

Data types and time delay in 8051, I/O programming in 8051, Logic operations in 8051, Data conversion program in 8051 Accessing code ROM space in 8051, Data serialization using 8051

UNIT IV 8051 SERIAL PORT AND INTERRUPT PROGRAMMING IN C 6

Basics of serial communication, 8051 interface to RS232- serial port programming in 8051. 8051 interrupts and programming, Programming for timer configuration.

UNIT V 8051 INTERFACING 6

8051: ADC interfacing , DAC interfacing, Sensor interfacing, LCD interfacing, Stepper motor interfacing.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Laboratory exercise: Use 8051 microcontroller/Embedded processor/IDE/open source platform to give hands-on training on Embedded C- programming.

   a. Introduction to IDE (like code blocks, vscode ,etc)and Programming Environment (like Keililu vision, Proteus)
   b. Configuring an I/O port using bitwise programming.
   c. Configuring timer for generating hardware delay.
   d. Flashing an LED using an interrupt
   e. Serial communication using UART port of 8051
   f. Interfacing an ADC with 8051
   g. Interfacing an analog sensor with 8051
   h. Interfacing 16x2 LCD with 8051
   i. configuring timer for generating PWM signal

j. Interfacing a stepper motor with 8051

2. Assignment: Introduction to Arduino IDE, Raspberry Pi
3. Embedded C-Programming -based Mini project.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Deliver insight into embedded C programming and its salient features for embedded systems.

CO2:Illustrate the software and hardware architecture for distributed computing in embedded systems

CO3: Develop a solution for problems by using the conceptlearnednt in programming using the embedded controllers

CO4: Develop simple applications with 8051 by using its various features and interfacing with various external hardware.

CO5: Improved Employability and entrepreneurship capacity due to knowledge upgradation on recent trends in embedded programming skills.

TEXTBOOKS:

1. Paul Deitel and Harvey Deitel, “C How to Program”, 9th Edition, Pearson Education Limited, 2022, 1st edition.
2. Michael J Pont, "Embedded C", Addison-Wesley, An imprint of Pearson Education, 2002.
3. William von Hagen, "The Definitive Guide to GCC", 2nd Edition, Apress Inc., 2006.
4. Gowrishankar S and Veena A, "Introduction to Python Programming", CRC Press, Taylor & Francis Group, 2019.

REFERENCES:

1. Noel Kalicharan, "Learn to Program with C", Apress Inc., 2015, 1st edition.
2. Steve Oualline, "Practical C programming", O'Reilly Media, 1997, 3rd edition.
3. Muhammad Ali Mazidi, Janice G. Mazidi and Rolin D. McKinlay, ‘The 8051 Microcontroller and Embedded Systems’ Prentice Hall, 2nd Edition 2007.
4. Myke Predko, “Programming and customizing the 8051 microcontrollers”,McGraww Hill 2000, 1st edition.

List of Open Source Software/ Learning websites:

- https://www.hackerrank.com/
- https://www.cprogramming.com/
- https://www.allaboutcircuits.com/technical-articles/introduction-to-the-c-programming-language-for-embedded-applications/
- https://onlinecourses.nptel.ac.in/noc19_cs42/preview
- https://microcontrollerslab.com/8051-microcontroller-tutorials-c/
- https://www.circuitstoday.com/getting-started-with-keil-uvision

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	3	1								1	2	2
CO2	1	1	2	2	1								1	3	2
CO3	2	2	3	2	3								2	3	3
CO4	3	2	3	2	3								1	1	1
CO5	3	2	1	2	1				1				2	3	2
Avg	2	1.6	2.2	2.2	1.8				1				1.4	2.4	2

TIEE3017 EMBEDDED PROCESSORS LT P C
2 0 2 3

COURSE OBJECTIVES:

- To introduce the architecture of the ARM processor.
- To train students in ARM programming.
- To discuss memory management, append location development with an ARM processor.
- To involve Discussions/ Practice/Exercise in revising & familiarizing the concepts
- To impart the knowledge on single board embedded processors.

UNIT I ARM ARCHITECTURE 6

Architecture – Memory Organization – addressing modes -Registers – Pipeline - Interrupts – Coprocessors – Interrupt Structure

UNIT II ARM MICROCONTROLLER PROGRAMMING 6

ARM general Instruction set – Thumb instruction set –Introduction to DSP on ARM- basic programming.

UNIT III PERIPHERALS OF ARM 6

ARM: I/O Memory – EEPROM – I/O Ports – SRAM –Timer –UART - Serial Communication with PC – ADC/DAC Interfacing-stepper motor interfacing

UNIT IV ARM COMMUNICATION 6

ARM With CAN, I^2C, and SPI protocols

UNIT V INTRODUCTION TO SINGLE BOARD EMBEDDED PROCESSOR 6

Raspberry Pi Architecture - Booting Up RPi- Operating System and Linux Commands -Working with RPi using Python and Sensing Data using Python-programming - GPIO and interfacing peripherals With Raspberry Pi

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory exercise:
   a) Programming with IDE - ARM microcontroller
   b) Advanced Timer Features, PWM Generator.
   c) RTC interfacing with ARM using Serial communication programming, Stepper motor control.
   d) ARM-Based Wireless Environmental Parameter Monitoring System displayed through Mobile device.
2. Seminar:
   a) ARM and GSM/GPS interfacing

b) Introduction to ARM Cortex Processor

3. Raspberry Pi based Mini project.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Interpret the basics and functionality of processor functional blocks.
CO2: Observe the specialty of RISC processor Architecture.
CO3: Incorporate the I/O hardware interface of processor with peripherals.
CO4: Emphasis the communication features of the processor.
CO5: Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in commercial embedded processors.

TEXTBOOKS:

1. Steve Furber, 'ARM system on chip architecture',Addisonn Wesley,2nd Edition,2015.
2. Andrew N. Sloss, Dominic Symes, Chris Wright, John Rayfield's ARM System Developer's Guide Designing and Optimizing System Software', Elsevier 2004, 1st Edition.

REFERENCES:

1. William Hohl, ' ARMAssebly Language' Fundamentals and Techniques, CRC Press, 2nd Edition 2014.
2. Rajkamal," Microcontrollers Architecture, Programming, Interfacing, & System Design, Pearson,2012, 2nd Edition.
3. ARM Architecture Reference Manual, LPC214x User Manual www.Nuvoton .com/websites on Advanced ARM Cortex Processors
4. ARM System Developer's Guide: Designing and Optimizing System Software 1st Edition (Designing and Optimizing System Software) Publisher: Morgan Kaufmann Publishers, 2011.

List of Open Source Software/ Learning websites:

1. https://nptel.ac.in/courses/117106111
2. https://onlinecourses.nptel.ac.in/noc20_cs15/preview
3. https://www.csie.ntu.edu.tw/~cyy/courses/assembly/12fall/lectures/handouts/lec08_ARMarch.pdf
4. https://maxembedded.com/2013/07/introduction-to-single-board-computing/
5. https://www.youtube.com/watch?v=J4fhE4Pp55E&list=PLGs0VKk2DiYypuwUUM2wxzcI9BJHK4Bfh

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	1								2	1	2
CO2	1	1	2	2	1								1	2	2
CO3	3	2	3	2	3								3	3	3
CO4	3	2	3	2	3								2	3	3
CO5	3	2	1	2	1				1				1	2	2
Avg	2.2	1.6	2.2	2	1.8				1				1.8	2.2	2.4

TIEE3018 EMBEDDED CONTROL FOR ELECTRIC DRIVES L T P C
2 0 2 3

COURSE OBJECTIVES:

- To provide the control concept for electrical drives
- To emphasize the need of embedded systems for controlling the electrical drives
- To provide knowledge about various embedded system-based control strategies for electrical drives
- To Impart the knowledge of optimization and machine learning techniques used for electrical drives
- To familiarize the high-performance computing for electrical drives.

UNIT I INTRODUCTION TO ELECTRIC DRIVES 6

Electric drives and its classification-Four-quadrant drive-Solid State Controlled Drives-Machine learning and optimization techniques for electrical drives.

UNIT II EMBEDDED SYSTEM FOR MOTOR CONTROL 6

Embedded Processors choice for motor control- Sensors and interface modules for Electric drives-IoT for Electrical drives applications

UNIT III INDUCTION MOTOR CONTROL 6

Speed control methods-PWM techniques- VSI fed three-phase induction motor- Fuzzy logic Based speed control for three-phase induction motor- Embedded processor based three phase induction motor speed control.

UNIT IV BLDC MOTOR CONTROL 6

Overview of BLDC Motor -Speed control methods -PWM techniques- Embedded processor based BDLC motor speed control.

UNIT V SRM MOTOR CONTROL 6

Overview of SRM Motor -Speed control methods -PWM techniques- Embedded processor based SRM motor speed control.

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory exercise: Use any System level simulator/MATLAB/open source platform to give hands-on training on simulation study on Electric drives and control.
    a. Simulation of four quadrant operation and speed control of DC motor
    b. Simulation of 3-phase inverter.
    c. Simulation of Speed control of Induction motor using any suitable software package.
    d. Simulation of Speed control of BLDC motor using any suitable software package.
    e. Simulation of Speed control of SRM using any suitable software package
2. Seminar: IoT-based Control and Monitoring for DC Motor/ any Electric drives.
3. Mini project.: Any Suitable Embedded processor-based speed control of Motors (DC/IM/BLDC/PMSM/SRM)

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Interpret the significance of embedded control of electrical drives
CO2: Deliver insight into various control strategies for electrical drives.
CO3: Developing knowledge of Machine learning and optimization techniques for motor control.

CO4: Develop embedded system solutions for real-time application such as Electric vehicles and UAVs.

CO5: Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded system skills required for motor control strategy.

TEXT BOOKS:

1. R.Krishnan, “Electric Motor Drives – Modeling, Analysis and Control”,Prentice-Hall of India Pvt. Ltd., New Delhi,2010, 1st Edition.
2. Steve Kilts, "Advanced FPGA Design: Architecture, Implementation, and Optimization" Willey, 2007, 1st Edition.

REFERENCES:

1. VedamSubramanyam, “Electric Drives – Concepts and Applications”, Tata McGraw- Hill publishing company Ltd., New Delhi, 2002, 2nd Edition.
2. K. Venkataratnam ,Special Electrical Machines, Universities Press, 2014, 1st Edition.
3. Steve Furber, ‘ARM system on chip architecture’, Addision Wesley, 2nd Edition 2015.
4. Ron Sass and AnderewG.Schmidt, “ Embedded System design with platform FPGAs: Principles and Practices”, Elsevier, 2010, 1st Edition.
5. Tim Wescott , Applied Control Theory for Embedded Systems , Elsevier, 2006, 1st Edition.

List of Open Source Software/ Learning website:

1) https://archive.nptel.ac.in/courses/108/104/108104140/
2) https://www.embedded.com/mcus-or-dsps-which-is-in-motor-control/
3) https://www.e3s-conferences.org/articles/e3sconf/pdf/2019/13/e3sconf_SeFet2019_01004.pdf
4) https://www.electronics-tutorials.ws/blog/pulse-width-modulation.html
5) http://kaliasgoldmedal.yolasite.com/resources/SEM/SRM.pdf

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	2	1								2	1	2
CO2	2	1	3	2	1								2	1	2
CO3	3	2	3	3	3								1	3	3
CO4	3	2	3	3	3								3	3	3
CO5	3	2	1	2	1				1				2	2	3
Avg	2.4	1.6	2.4	2.4	1.8				1				2	2	2.6

TIEE3019 SMART SYSTEM AUTOMATION LT P C
2 0 2 3

COURSE OBJECTIVES:

- To introduce the smart system technologies and its role in real time applications
- To teach the architecture and requirements of Home Automation.
- To provide an insight into smart appliances and energy management concepts.
- To familiarize the design and needs of smart wearable devices
- To teach the basics of robotics and its role for automation.

UNIT I INTRODUCTION 6

Overview of a smart system - Hardware and software selection - Smart sensors and Actuators – Communication protocols used for smart systems.

UNIT II HOME AUTOMATION 6

Home Automation – System Architecture - Essential Components- Design Considerations: Control Unit, Sensing Requirements, Communication, Data Security.

UNIT III SMART APPLIANCES AND ENERGY MANAGEMENT 6

Significance of smart appliances for energy management -Smart Meters: Significance, Architecture & Energy Measurement Technique – Security Considerations.

UNIT IV SMART WEARABLE DEVICES 6

Body Area Networks - Sensors– communication protocol for Wearable devices- Application of Smart Wearable in Healthcare & Activity Monitoring.

UNIT V EMBEDDED SYSTEMS AND ROBOTICS 6

Fundamental concepts in Robotics- Robots and Controllers components - Embedded processor based: pick and place robot- Mobile Robot Design- UAV.

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory exercise: Use Arduino/ R pi/ any other Embedded processors to give hands on training to understand concepts related to smart automation.
   a) Hands on experiments based on Ubidots & Thing speak / Open-source Analytics Platform
   b) Design and implementation of a smart home system .
   c) Bluetooth Based Home Automation Project using Android Phone
   d) GSM Based Home Devices Control
   e) Pick and place robots using Arduino/ any suitable Embedded processor
2. Assignment: Revolution of Smart Automation system across the world and its current scope available in India
3. Mini project: Design of a Smart Automation system (for any application of students choice)

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Understand the concepts of smart system design and its present developments.

CO2: Illustrate different embedded open-source and COst-effective techniques for developing solution for real time applications.

CO3: Acquire knowledge on different platforms and Infrastructure for Smart system design.

CO4: Infer about smart appliances and energy management concepts.

CO5: Improve Employability and entrepreneurship capacity due to knowledge upgradation on embedded system technologies.

TEXTBOOKS:

1. Grimm, Christoph, Neumann, Peter, Mahlknech and Stefan, Embedded Systems for Smart Appliances and Energy Management, Springer 2013, 1st Edition.
2. KazemSohraby, Daniel Minoli and TaiebZnati, Wireless Sensor Networks Technology, Protocols, and Applications, John Wiley & Sons, 2007, 1st Edition.
3. NilanjanDey, Amartya Mukherjee, Embedded Systems and Robotics with Open-Source Tools, CRC press, 2016, 1st Edition.

REFERENCES:

1. Thomas Bräunl, Embedded Robotics, Springer, 2003.
2. Raj Kamal, Embedded Systems - Architecture, Programming and Design, McGraw- Hill, 2008
3. Karim Yaghmour, Embedded Android, O'Reilly, 2013.
4. Steven Goodwin, Smart Home Automation with Linux and Raspberry Pi, Apress , 2013
5. C.K. Toh, AdHoc mobile wireless networks, Prentice Hall, Inc, 2002.
6. Anna Ha´c, Wireless Sensor Network Designs, John Wiley & Sons Ltd, 2003.
7. J. J. Craig, “Introduction to Robotics Mechanics and Control”, Pearson Education.
8. Y. Koren, “Robotics for Engineers”, McGraw-Hill.
9. Robert Faludi, Wireless Sensor Networks, O’Reilly, 2011.

List of Open Source Software/ Learning website:

1. https://microcontrollerslab.com/home-automation-projects-ideas/
2. https://www.learnrobotics.org/blog/simple-robot/
3. https://robolabor.ee/homelab/en/iot
4. https://electrovolt.ir/wp-content/uploads/2018/03/Exploring_Raspberry_Pi_Molloy_Derek_ElectroVolt.ir_.pdf
5. http://www.robot.bmstu.ru/files/books/(Ebook%20-%20English)%20Mcgraw-Hil,%20Pic%20Robotics%20--%20A%20Beginner'S%20Guide%20To%20Robotic.pdf

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	3	1	3								1	2	2
CO2	3	1	2	2	3								1	1	3
CO3	2	2	3	2	3								2	2	2
CO4	2	2	2	1	3								1	2	2
CO5	3	2	2	2	3				1				2	2	3
Avg	2.4	1.6	2.4	1.6	3				1				1.4	1.8	2.4

TIEE3020 EMBEDDED SYSTEM FOR AUTOMOTIVE APPLICATIONS LT P C
2 0 2 3

COURSE OBJECTIVES:

- To expose the students to the fundamentals and building of Electronic Engine Control systems.
- To teach on sensor functional components for vehicles.
- To discuss on programmable controllers for vehicles management systems.
- To teach logics of automation & communication techniques for vehicle communication.
- To introduce the infotainment system development.

UNIT I INTRODUCTION TO AUTOMOTIVE SYSTEMS 6

Overview of Automotive systems, fuel economy, air-fuel ratio, emission limits and vehicle performance; Electronic control Unit– open-source ECU.

UNIT II SENSORS AND ACTUATORS FOR AUTOMOTIVES 6

Review of automotive sensors- sensors interface to the ECU, Smart sensor and actuators for automotive applications.

UNIT III VEHICLE MANAGEMENT SYSTEMS 6

Energy Management system -Adaptive cruise control - anti-locking braking system - Safety and Collision Avoidance.

UNIT IV ONBOARD DIAGONSTICS AND COMMUNICATION 6

OBD , Vehicle communication protocols- Bluetooth, CAN, LIN, FLEXRAY and MOST.

UNIT V RECENT TRENDS 6

Navigation- Autonomous car- Role of IoT in Automotive systems.

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory exercise: Use MATLAB SIMULINK /equivalent simulation /open source tools
   a) Simulation study of automotive sensors and actuators components
   b) Adaptive cruise control, Anti-Lock Braking System
   c) CAN Connectivity in an Automotive Application using vehicle network toolbox
   d) Interfacing a sensor used in car with microcontroller.
   e) Establishing connection between Bluetooth module and microcontroller.
2. Assignment: AUTOSAR
3. Mini project : Battery Management system for EV batteries.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability in

CO1: Insight into the significance of the role of embedded system for automotive applications.
CO2: Illustrate the need, selection of sensors and actuators and interfacing with ECU
CO3: Develop the Embedded concepts for vehicle management and control systems.

CO4: Demonstrate the need of Electrical vehicle and able to apply the embedded system technology for various aspects of EVs

CO5: Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design and its application in automotive systems.

TEXTBOOKS:

1. William B. Ribbens ,"Understanding Automotive Electronics", Elseiver,8th Edition, 2017.
2. Jurgen, R., Automotive Electronics Hand Book, McGraw Hill, 2nd Edition, 1999.
3. L.Vlacic,M.Parent,F.Harahima,"Intelligent Vehicle Technologies",SAE International, 2001, 1st Edition, 2017.

REFERENCES:

1. Ali Emedi, Mehrdedehsani, John M Miller , "Vehicular Electric power system- land, Sea, Air and Space Vehicles" Marcel Decker, 2004, 1st Edition.
2. Jack Erjavec,JeffArias,"Alternate Fuel Technology-Electric ,Hybrid& Fuel Cell Vehicles",Cengage ,2012, 2nd Edition.
3. Electronic Engine Control technology – Ronald K Jurgen Chilton's guide to Fuel Injection – Ford 2nd Edition, 2004.
4. Automotive Electricals / Electronics System and Components, Tom Denton, 5th Edition, 2017.
5. Uwe Kiencke, Lars Nielsen, "Automotive Control Systems: For Engine, Driveline, and Vehicle", Springer; 1st Edition, 2005.
6. Automotive Electricals Electronics System and Components, Robert Bosch Gmbh, 5th Edition, 2014.
7. Automotive Hand Book, Robert Bosch, Bently Publishers, 10th Edition, 2018.

List of Open Source Software/ Learning website:

1) https://www.autosar.org/fileadmin/ABOUT/AUTOSAR_EXP_Introduction.pdf
2) https://microcontrollerslab.com/can-communication-protocol/
3) https://ackodrive.com/car-guide/different-types-of-car-sensors/
4) https://www.tomtom.com/blog/automated-driving/what-is-adaptive-cruise-control/
5) https://prodigytechno.com/difference-between-lin-can-and-flexray-protocols/
6) https://www.synopsys.com/automotive/what-is-autonomous-car.html

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	1								2	1	3
CO2	2	3	3	2	2								2	2	2
CO3	3	3	3	3	3								2	1	3
CO4	3	3	3	3	3								1	3	2
CO5	3	3	1	2	1				1				2	2	3
Avg	2.4	3	2.4	2.4	2				1				1.8	1.8	2.6

TIEE3021 **VLSI DESIGN** **LT P C**
2 0 2 3

COURSE OBJECTIVES

- To explain the basic concepts of CMOS and
- To introduce the IC fabrication methods
- To introduce the Reconfigurable Processor technologies
- To introduce the basics of analog VLSI design and its importance.
- To learn about the programming of Programmable device using Hardware description Language.

UNIT I CMOS BASICS **6**
MOSFET Scaling - CMOS logic design- Dynamic CMOS –Transmission Gates- BiCMOS

UNIT II IC FABRICATION **6**
CMOS IC Fabrications: n well, p well, twin tub, SoI - Design Rules and Layout.

UNIT III PROGRAMABLE LOGIC DEVICES **6**
PAL, PLA, CPLD architecture and application.

UNIT IV RECONFIGURABLE PROCESSOR **6**
FPGA- Architecture, FPGA based application development- Introduction to FPAA.

UNIT V HDL PROGRAMMING **6**
Verilog HDL- Overview - structural and behavioural modeling concepts-Design examples- Carry Look ahead adders, ALU, Shift Registers.

30 PERIODS

LAB COMPONENTS: **30 PERIODS**

1. Laboratory exercise : Use any FPGA Board /IDE/open source package/ platform to give hands on training on CMOS design/ reconfigurable processor based applications.

   a) CMOS logic circuit simulation using any open source software package
   b) Experiments : structural and behavioural modeling based Verilog HDL programs
   c) Experiment: Combinational and sequential Digital logic implementation with FPGA.
   d) Implementation of carry look ahead adder with FPGA
   e) Implementation of ALU with FPGA

2. Assignment : Low Power VLSI.
3. FPGA based Mini project .

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:
At the end of this course, the students will have the ability to
CO1: Develop CMOS design techniques
CO2: Learn and build IC fabrication
CO3: Explain the need of reconfigurable computing with PLDs.
CO4: Design and development of reprogrammable FPGA.
CO5: Illustrate and develop HDL computational processes with improved design strategies.

TEXTBOOKS:

1. M.J.S Smith, “Application Specific integrated circuits”,Addition Wesley Longman Inc. 1st Edition 2010.
2. Kamran Eshraghian,Douglas A.pucknell and Sholeh Eshraghian,”Essentials of VLSI circuits and system”, Prentice Hall India,2005, 1st Edition.

REFERENCES:

1. Donald G. Givone, “Digital principles and Design”, Tata McGraw Hill 2002, 1st Edition.
2. Charles H. Roth Jr., “Fundamentals of Logic design”, Thomson Learning, 7th Edition 2013.
3. Nurmi, Jari (Ed.) "Processor Design System-On-Chip Computing for ASICs and FPGAs" Springer, 2007, 1st Edition.
4. Joao Cardoso, Michael Hübner, "Reconfigurable Computing: From FPGAs to Hardware/Software Codesign" Springer, 2011, 1st Edition.
5. Pierre-Emmanuel Gaillardon, Reconfigurable Logic: Architecture, Tools, and Applications, 1st Edition, CRC Press , 2018.

List of Open Source Software/ Learning website:

1) https://archive.nptel.ac.in/courses/108/107/108107129/
2) http://gn.dronacharya.info/ECEDept/Downloads/QuestionPapers/7th_Sem/VLSI-DESIGN/UNIT-1/Lecture-3.pdf
3) https://web.itu.edu.tr/~ateserd/vlsi2/2007/FPGAs&CPLD.pdf
4) https://kanchiuniv.ac.in/coursematerials/GSK_Notes_on_PLD_in_VLSI_design.pdf
5) https://www.xilinx.com/products/silicon-devices/resources/programming-an-fpga-an-introduction-to-how-it-works.html
6) https://www.allaboutcircuits.com/technical-articles/what-is-an-fpga-introduction-to-programmable-logic-fpga-vs-microcontroller/
7) https://www.tutorialspoint.com/vlsi_design/vlsi_design_vhdl_introduction.htm#:~:text=VHDL%20stands%20for%20very%20high,DoD)%20under%20the%20VHSIC%20program.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	2	1								2	2	3
CO2	3	1	2	3	1								1	1	3
CO3	3	2	2	2	3								2	1	3
CO4	3	2	2	2	3								2	2	3
CO5	3	2	1	3	3				1				2	2	3
Avg	3	1.6	1.6	2.4	2.2				1				1.8	1.6	3

TIEE3022	MEMS AND NEMS	LT P C 2 0 2 3

COURSE OBJECTIVES:

- To introduce the diverse technological and functional approaches of MEMS/NEMS and applications.
- To understand the microstructures and fabrication methods.
- To provide an insight of micro and nano sensors, actuators.
- To emphasis the need for NEMS technology.
- To update the ongoing trends and real time applications of MEMS and NEMS technology.

UNIT I INTRODUCTION TO MEMS and NEMS 6

Overview of Micro electro mechanical systems and Nano Electro mechanical systems, devices and technologies, Laws of scaling- Materials for MEMS and NEMS - Applications of MEMS and NEMS.

UNIT II MICRO-MACHINING AND MICROFABRICATION TECHNIQUES 6

Photolithography- Micro manufacturing, Bulk micro machining, surface micro machining, LIGA.

UNIT III MICRO SENSORS AND MICRO ACTUATORS 6

Micromachining : Capactive Sensors- Piezoresistive Sensors- Piezoelectric actuators.

UNIT IV NEMS TECHNOLOGY 6

Atomic scale precision engineering- Nano Fabrication techniques – NEMS for sensors and actuators.

UNIT V MEMS and NEMS APPLICATION 6

Bio MEMS- Optical NEMS- Micro motors- Smart Sensors - Recent trends in MEMS and NEMS.

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory experiment: Simulation of MEMS sensors and actuators using Multi physics tool
   a) Simulation of a typical piezo resistive sensor
   b) Simulation of a typical Piezoelectric actuator
   c) Simulation study of a bio sensor
   d) Simulation study of a micro motor
2. Assignment: Role of MEMS AND NEMS devices for Industry Standard 5.0.
3. Mini project : Design and analysis of any MEMS/NEMS device using multi physics tool.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Explain the material properties and the significance of MEMS and NEMS for industrial automation.

CO2: Demonstrate knowledge delivery on micromachining and micro fabrication.

CO3: Apply the fabrication mechanism for MEMS sensor and actuators.

CO4: Apply the concepts of MEMS and NEMS to models ,simulate and process the sensors and actuators.

CO5: Improved Employability and entrepreneurship capacity due to knowledge up gradation on MEMS and NEMS technology.

TEXTBOOKS:

1. Chang Liu, "Foundations of MEMS", Pearson International Edition, 2011, 2nd Edition.
2. Tai-.Ran Hsu, "MEMS and Microsystems: design , manufacture, and Nanoscale"- 2nd Edition, John Wiley & Sons, Inc., Hoboken, New Jersey, 2008.
3. Lyshevski, S.E. " Nano- and Micro-Electromechanical Systems: Fundamentals of Nano-and Microengineering " (2nd ed.). CRC Press,2005.
4. Julian W Gardner and Vijay K Varadan, " Microsensors, MEMS and Smart Devices", John Wiley and Sons Ltd, 2001, 1st Edition.

REFERENCES:

1. Marc F madou" Fundamentals of micro fabrication" CRC Press 2002 2nd Edition Marc Madou.
2. M.H.Bao "Micromechanical transducers :Pressure sensors, accelerometers and gyroscopes",Elsevier, Newyork, 16 Oct 2000, 1st Edition.
3. Maluf, Nadim "An introduction to Micro Electro-mechanical Systems Engineering "AR Tech house, Boston, June 30 2004, 2nd Edition.
4. Mohamed Gad – el – Hak "MEMS Handbook" Edited CRC Press 2001, 1st Edition.

List of Open Source Software/ Learning website:

1. https://www.academia.edu/Lectures_on_MEMS_and_MICROSYSTEMS_DESIGN_AND_MANUFACTURE
2. https://nptel.ac.in/courses
3. https://www.iitk.ac.in/me/mems-fabrication
4. http://mems.iiti.ac.in/
5. https://onlinecourses.nptel.ac.in/noc22_ee36/preview

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	1								1	3	2
CO2	2	1	2	2	1								1	1	2
CO3	2	2	2	1	3								2	3	3
CO4	3	2	2	2	3								2	2	3
CO5	3	2	3	3	3				1				2	1	2
Avg	2.4	1.8	2	1.8	2.4				1				1.6	2	2.4

TIEE3023 DIGITAL SIGNAL PROCESSING SYSTEM DESIGN L T P C
2 0 2 3

COURSE OBJECTIVES:

- To introduce the concept of analyzing discrete time signals & systems in the time and frequency domain through mathematical representation.
- To study the various time to frequency domain transformation techniques.
- To Understand the computation algorithmic steps for Fourier Transform.
- To study about filters and their design for digital implementation.
- To introduce the programmable digital signal processor & its application.

UNIT I INTRODUCTION 6

Classification of systems: Continuous, discrete, linear, causal, stable, dynamic, recursive, time variance; classification of signals: continuous and discrete, energy and power; mathematical representation of signals; spectral density; sampling techniques, quantization, quantization error, Nyquist rate, aliasing effect. Digital signal representation.

UNIT II DISCRETE TIME SYSTEM ANALYSIS 6

Z-transform and its properties, inverse z-transforms; difference equation – Solution by z-transform, application to discrete systems - Stability analysis, frequency response – Convolution – Introduction to Fourier Transform– Discrete time Fourier transform.

UNIT III DISCRETE FOURIER TRANSFORM & COMPUTATION 6

DFT properties, magnitude and phase representation - Computation of DFT using FFT algorithm – DIT & DIF - FFT using radix 2 – Butterfly structure.

UNIT IV DESIGN OF DIGITAL FILTERS 6

FIR & IIR filter realization – Parallel & cascade forms. FIR design: Windowing Techniques – Need and choice of windows – Linear phase characteristics. IIR design: Analog filter design - Butterworth and Chebyshev approximations; digital design using impulse invariant and bilinear transformation - Warping, prewarping -Frequency transformation.

UNIT V DIGITAL SIGNAL PROCESSORS 6

Introduction – Architecture of one DSP processor for motor control – Features – Addressing Formats– Functional modes - Introduction to Commercial Processors

30 PERIODS

LAB COMPONENTS: 30 PERIODS

1. Laboratory exercise : Use any DSP processor/MATLAB/open source platform to give hands on training on basic concepts of Digital Signal Processing
   a) To determine impulse and step response of two vectors
   b) To perform convolution between two vectors .
   c) To compute DFT and IDFT of a given sequence.
   d) To perform linear convolution of two sequence using DFT
   e) Design and Implementation of FIR Filter
   f) Design and Implementation of IIR Filter
   g) To determine z-transform from the given transfer function and its ROC
2. Assignment : Implementation of FIR/IIR filter with FPGA.
3. DSP processors based Mini project.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will have the ability to

CO1: Explain the concepts of digital signal processing
CO2: Illustrate the system representation using transforms
CO3: Learn the transformation techniques for time to frequency conversion
CO4: Design suitable digital FIR, IIR algorithm for the given specification
CO5: Use digital signal processor for application development

TEXTBOOKS:

1. J.G. Proakis and D.G. Manolakis, 'Digital Signal Processing Principles, Algorithms and Applications', Pearson Education, New Delhi, 4th Edition 2007.
2. Robert J.Schilling & Sandra L.Harris ,' Introduction to Digital Signal Processing using MATLAB', Cengage Learning, 2nd Edition 2013.

REFERENCES:

1. Emmanuel C Ifeachor and Barrie W Jervis ,"Digital Signal Processing – A Practical approach" Pearson Education, Second edition, 2002.
2. Alan V. Oppenheim, Ronald W. Schafer and John R. Buck, 'Discrete – Time Signal Processing', Pearson Education, New Delhi, 2nd Edition 2012.
3. SenM.kuo, Woonseng…s.gan, "Digital Signal Processors, Architecture, Implementations & Applications, Pearson, 1st Edition 2004.
4. S.K. Mitra, 'Digital Signal Processing – A Computer Based Approach', Tata McGraw Hill, New Delhi, 4th Edition 2013.
5. B. Venkataramani, M. Bhaskar, 'Digital Signal Processors, Architecture, Programming and Applications', Tata McGraw Hill, New Delhi, 2003, 1st Edition.

List of Open Source Software/ Learning website:

1. https://nptel.ac.in/courses/117102060
2. https://www.tutorialspoint.com/digital_signal_processing/index.htm
3. https://www.elprocus.com/digital-signal-processor/
4. https://www.sciencedirect.com/topics/computer-science/digital-signal-processing-algorithm#:~:text=Digital%20signal%20processing%20algorithms%20are,known%20as%20operations%20or%20ops.
5. https://www.electronicshub.org/introduction-to-fpga/

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	3	2	2	1								1	2	1
CO2	2	3	3	2	2								2	3	1
CO3	3	3	3	3	3								2	2	2
CO4	3	3	3	3	3								2	2	3
CO5	3	3	3	2	1				1				2	2	3
Avg	2.4	3	2.8	2.4	2				1				1.8	2.2	2

ELECTRIC VEHICLE TECHNOLOGY

TIEE3024 DESIGN OF MOTOR AND POWER CONVERTERS FOR ELECTRIC VEHICLES **L T P C 2 0 2 3**

COURSE OBJECTIVES:

- To review the drive cycles and requirements of EVs
- To know the working of motors used in Electric Vehicle
- To analyze and model the buck/boost converter operation and to design the same
- To learn the simulation basics of control systems
- To derive transfer functions for DC-DC converters

UNIT I ELECTRIC VEHICLE DYNAMICS 6

Standard drive cycles-Dynamics of Electric Vehicles-Tractive force-Maximum speed, torque, power, energy requirements of EVs.

UNIT II MOTORS FOR ELECTRIC VEHICLES 6

Introduction – Speed And Torque control of above and below rated speed-Speed control of EV in the constant power region of electric motors. DC Motors, Induction Motor, Permanent Magnet Synchronous Motors (PMSM), Brushless DC Motors, Switched Reluctance Motors (SRMs). Synchronous Reluctance Machines-Choice of electric machines for EVs.

UNIT III BASICS OF SIMULATION IN CONTROL SYSTEMS 6

Transfer Function-How to build transfer function, identify Poles, zeros, draw time response plots, bode plot (Bode Plots for Multiplication Factors, Constant, Single and Double Integration Functions, Single and Double Differentiation Functions, Single Pole and Single Zero Functions, RHP Pole and RHP Zero Functions), state space modelling-transfer function from state space Model.

UNIT IV MODELING OF DC-DC CONVERTERS 6

Overview of PWM Converter Modelling -Power Stage Modelling - PWM Block Modelling - Voltage Feedback Circuit and Small-Signal Model of PWM Converter - Averaging Power Stage Dynamics - Average Models for buck/boost Converter - Small-Signal Model of Converter Power Stage - Frequency Response of Converter

UNIT V POWER STAGE TRANSFER FUNCTIONS OF DC – DC CONVERTERS 6

Power Stage Transfer Functions of buck-boost Converter in CCM Operation, Input-to-Output Transfer Function, Duty Ratio-to-Output Transfer Function, Load Current-to-Output Transfer Function.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simple simulation exercises of basic control systems
2. Bode plots and calculation of Gain margin and Phase margin for power stage transfer function via simulation.
3. Design of buck converter
4. Design of boost converter
5. Simulation of buck, boost and buck boost converter-open loop (With power circuit and Transfer function).

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: To use appropriate electric machine for electric vehicle application

CO2: To compute transfer function with factors such as constant, integral, differential, first order factor and second order factor (both numerators & denominators)

CO3: To compute transfer function from state models

CO4: To design buck, boost and buck-boost converter.

CO5: To compute a power stage transfer functions for DC-DC converters

CO6: To simulate DC-DC converters and to obtain gain margin and phase margin.

REFERENCES:

1. Power Electronic Converters, Teuvo Suntio, Tuomas Messo, Joonas Puukko, First Edition 2017.
2. Fundamentals of Power Electronics with MATLAB, Randall Shaffer, 2nd Edition, 2013, Lakshmi publications
3. Feedback Control problems using MATLAB and the Control system tool box, Dean Frederick and Joe Cho, 2000, 1st Edition, Cengage learning.
4. Handbook of Automotive Power Electronics and Motor Drives, Ali Emadi, Taylor & Francis, 2005,1st Edition.
5. Electrical Machine Fundamentals with Numerical Simulation using MATLAB/SIMULINK, Atif Iqbal, Shaikh Moinoddin, Bhimireddy Prathap Reddy, Wiley,2021, 1st Edition.
6. Emerging Power Converters for Renewable Energy and Electric Vehicles Modeling, Design, and Control, Md. Rabiul Islam,Md. Rakibuzzaman Shah, Mohd. Hasan Ali, CRC Press,2021, 1st Edition.
7. Iqbal Hussain, "Electric and Hybrid Vehicles: Design Fundamentals, Second Edition" CRC Press, Taylor & Francis Group, Third Edition 2021.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		3					1		3		3	3		1
CO2	3	3	3	3	3			1		3		3	3	3	3
CO3	3	3	3	3	3			1		3		3	3	3	3
CO4	3	3	3	3	3			1		3		3	3	3	3
CO5	3	3	3	3	3			1		3		3	3	3	3
CO6	3	3	3	3	3			1		3		3	3	3	3
Avg	3	3	3	3	3			1		3		3	3	3	2.6

TIEE3025 ELECTRIC VEHICLE DESIGN, MECHANICS AND CONTROL

L	T	P	C
2	0	2	3

COURSE OBJECTIVES:

- To learn the basics of EV and vehicle mechanics
- To know the EV architecture
- To study the energy storage system concepts
- To derive model for batteries and to know the different types of batteries and its charging methods
- To learn the control preliminaries for DC-DC converters.

UNIT I INTERNAL COMBUSTION ENGINES 6

IC Engines, BMEP and BSFC, Vehicle Fuel Economy, Emission Control Systems, Treatment of Diesel Exhaust Emissions.

UNIT II ELECTRIC VEHICLES AND VEHICLE MECHANICS 6

Electric Vehicles (EV), Hybrid Electric Vehicles (HEV), Engine ratings- Comparisons of EV with internal combustion Engine vehicles- Fundamentals of vehicle mechanics.

UNIT III BATTERY MODELING, TYPES AND CHARGING 6

Batteries in Electric and Hybrid Vehicles - Battery Basics -Battery Parameters. Types- Lead Acid Battery - Nickel-Cadmium Battery - Nickel-Metal-Hydride (NiMH) Battery - Li-Ion Battery - Li-Polymer Battery, Zinc-Air Battery, Sodium-Sulphur Battery, Sodium-Metal-Chloride, Research and Development for Advanced Batteries. Battery Modelling, Electric Circuit Models. Battery Pack Management, Battery Charging.

UNIT IV CONTROL PRELIMINARIES 6

Control Design Preliminaries - Introduction - Transfer Functions – Bode plot analysis for First order and second order systems - Stability - Transient Performance- Power transfer function for boost converter - Gain margin and Phase margin study-open loop mode.

UNIT V CONTROL OF AC MACHINES 6

Introduction- Reference frame theory, basics-modeling of induction and synchronous machine in various frames-Vector control- Direct torque control.

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Develop a model that could estimate Soc and SoH of Li-Ion Battery.
2. Modelling and thermal analysis of Li-Ion Battery.
3. Simulation of boost converter and calculating gain and phase margin from the transfer function.
4. Simulation of vector control of induction motor

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: To describe the concepts related with EV, HEV and to compare the same with internal combustion engine vehicles

CO2: To find gain margin & phase margin for various types of transfer functions of

boost converter

CO3: To demonstrate the Control of A C Machines

CO4: To explain the concepts related with batteries and parameters of battery

CO5: To module the battery and to study the research and development for batteries

REFERENCES:

1. Electric and Hybrid Vehicles, Design Fundamentals, Third Edition, Iqbal Husain, CRC Press, 2021.
2. Power Electronic Converters,: Dynamics and Control in Conventional and Renewable Energy Applications, Teuvo Suntio, Tuomas Messo, Joonas Puukko, 1st Edition, Wiley - VCH.
3. Ali Emadi, Mehrdad Ehsani, John M.Miller, “Vehicular Electric Power Systems”, Special Indian Edition, Marcel dekker, Inc 2003, 1st Edition.
4. C.C. Chan and K.T. Chau, 'Modern Electric Vehicle Technology', OXFORD University Press, 2001, 1st Edition.
5. Wie Liu, “Hybrid Electric Vehicle System Modeling and Control”, Second Edition, John Wiley & Sons, 2017, 2nd Edition.
6. Dynamic Simulation of Electric Machinery using MATLAB, Chee Mun Ong, Prentice Hall,1997, 1st Edition.
7. Electrical Machine Fundamentals with Numerical Simulation using MATLAB/ SIMULINK, Atif Iqbal, Shaikh Moinoddin, Bhimireddy Prathap Reddy, Wiley, 2021, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3								1	2		2	3		3
CO2	3								1	3		2	3		3
CO3	3						3		1	2		2	3		3
CO4	3						3		1	2		2	3		3
CO5	3						3		1	2		2	3	2	3
Avg	3	3	3	3	3		3		1	2.3		2	3	2.5	3

TIEE3026	DESIGN OF ELECTRIC VEHICLE CHARGING SYSTEM	L	T	P	C
		2	0	2	3

COURSE OBJECTIVES:

- To know the charging station and standards
- To learn the concepts of power converters in charging
- To find the charging scheme in renewable based EV charging
- To demonstrate the wireless power transfer technique
- To design & simulate power factor correction circuits

UNIT I CHARGING STATIONS AND STANDARDS 6

Introduction-Charging technologies- Conductive charging, EV charging infrastructure, International standards and regulations - Inductive charging, need for inductive charging of EV, Modes and operating principle, Static and dynamic charging, Bidirectional power flow, International standards and regulations

UNIT II POWER ELECTRONICS FOR EV CHARGING 6

Layouts of EV Battery Charging Systems-AC charging-DC charging systems- Power Electronic Converters for EV Battery Charging- AC–DC converter with boost PFC circuit, with bridge and without bridge circuit - Bidirectional DC–DC Converters- Non-isolated DC–DC bidirectional converter topologies- Half-bridge bidirectional converter.

UNIT III EV CHARGING USING RENEWABLE AND STORAGE SYSTEMS 6

Introduction- - EV charger topologies , EV charging/discharging strategies - Integration of EV charging-home solar PV system , Operation modes of EVC-HSP system , Control strategy of EVC-HSP system - fast-charging infrastructure with solar PV and energy storage.

UNIT IV WIRELESS POWER TRANSFER 6

Introduction - Inductive, Magnetic Resonance, Capacitive types. Wireless Chargers for Electric Vehicles - Types of Electric Vehicles - Battery Technology in EVs -Charging Modes in EVs - Benefits of WPT. - WPT Operation Modes - Standards for EV Wireless Chargers, SAE J2954, IEC 61980. ISO 19363

UNIT V POWER FACTOR CORRECTION IN CHARGING SYSTEM 6

Need for power factor correction- Boost Converter for Power Factor Correction, Sizing the Boost Inductor, Average Currents in the Rectifier and calculation of power losses-

30 PERIODS

LAB COMPONENT: 30 PERIODS

1. Simulation and analysis for bi-directional charging V2G and G2V.
2. Design and demonstrate solar PV based EV charging station.
3. Simulate and infer wireless power charging station for EV charging.
4. Simulation of boost converter based power factor correction.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

CO1: To illustrate various charging techniques and to know charging standards and regulations.
CO2: To demonstrate the working o DC-DC converters used for charging systems and principles
CO3: To illustrate the advantages of renewable system based charging systems
CO4: To demonstrate the principles of wireless power transfer.
CO5: To analyze the standards for wireless charging
CO6: To design and simulate boost converter based power factor correction.

REFERENCES:

1. Mobile Electric Vehicles Online Charging and Discharging, Miao Wang Ran Zhang Xuemin (Sherman) Shen, Springer 2016, 1st Edition.
2. Alicia Triviño-Cabrera, José M. González-González, José A. Aguado, Wireless Power Transferor Electric Vehicles: Foundations and Design Approach, Springer Publisher 1st Edition. 2020.
3. Nil Patel, Akash Kumar Bhoi, Sanjeevikumar Padmanaban, Jens Bo Holm-Nielsen, Electric Vehicles Modern Technologies and Trends. Springer Publisher 1st Edition, 2021.
4. Cable Based and Wireless Charging Systems for Electric Vehicles, Technology and control, management and grid integration, Rajiv Singh, Sanjeevikumar Padmanaban, Sanjeet Dwivedi, Marta Molinas and Frede Blaabjerg, IET 2021, 1st Edition.
5. Electric and Hybrid Electric Vehicles, James D Halderman, Pearson, 2022, 1st Edition.
6. Handbook of Automotive Power Electronics and Motor Drives, Ali Emadi, Taylor & Francis, 2005.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3			2	2		3		3	3		
CO2	3	3	3	3			2	2		3		3	3	3	3
CO3	3												3	3	3
CO4	3	3	3	3			2	2		2		1	3	3	3
CO5	3												3	3	3
CO6	3	3	3	3	3		2	2		3		2	3	3	3
Avg	3	3	3	3	3		2	2		2.75		2.25	3	3	3

TIEE3027 TESTING OF ELECTRIC VEHICLES

L	T	P	C
2	0	2	3

COURSE OBJECTIVES:

- To know various standardization procedures
- To learn the testing procedures for EV & HEV components
- To know the functional safety and EMC
- To realize the effect of EMC in EVs
- To study the effect of EMI in motor drives and in DC-DC converter system

UNIT I EV STANDARDIZATION **6**

Introduction - Current status of standardization of electric vehicles, electric Vehicles and Standardization - Standardization Bodies Active in the Field – Standardization activities in countries like Japan. The International Electro Technical Commission - Standardization of Vehicle Components.

UNIT II TESTING OF ELECTRIC MOTORS AND CONTROLLERS FOR ELECTRIC AND HYBRID ELECTRIC VEHICLES **6**

Test Procedure Using M-G Set, electric motor, controller, application of Test Procedure, Analysis of Test Items for the Type Test - Motor Test and Controller Test (Controller Only). - Test Procedure Using Eddy Current Type Engine Dynamometer, Test Strategy, Test Procedure, Discussion on Test Procedure. Test Procedure Using AC Dynamometer.

UNIT III FUNDAMENTALS OF FUNCTIONAL SAFETY AND EMC **6**

Functional safety life cycle - Fault tree analysis - Hazard and risk assessment - re development - Process models - Development assessments - Configuration management - Reliability - Reliability block diagrams and redundancy - Functional safety and EMC - Functional safety and quality - Standards - Functional safety of autonomous vehicles.

UNIT IV EMC IN ELECTRIC VEHICLES **6**

Introduction - EMC Problems of EVs, EMC Problems of Motor Drive, EMC Problems of DC-DC Converter System, EMC Problems of Wireless Charging System, EMC Problem of Vehicle Controller, EMC Problems of Battery Management System, Vehicle EMC Requirements-

UNIT V EMI IN MOTOR DRIVE AND DC-DC CONVERTER SYSTEM **6**

Overview -EMI Mechanism of Motor Drive System, Conducted Emission Test of Motor Drive System, IGBT EMI Source, EMI Coupling Path, EMI Modelling of Motor Drive System. EMI in DC-DC Converter, EMI Source, The Conducted Emission High-Frequency, Equivalent Circuit of DC-DC Converter System, EMI Coupling Path

30 PERIODS

LAB COMPONENT: **30 PERIODS**

1. Design and simulate motor controller for hybrid electric vehicle applications
2. Simulation of EMC analysis for Wireless power transfer EV charging.
3. Design and simulation of EMI filter

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: To describe the status and other details of standardization of EVs
CO2: To illustrate the testing protocols for EVs and HEV components
CO3: To analyze the safety cycle and need for functions safety for EVs
CO4: To analyze the problems related with EMC for EV components.
CO5: To evaluate the EMI in motor drive and DC-DC converter system.

REFERENCES:

1. Handbook of Automotive Power Electronics and Motor Drives, Ali Emadi, Taylor & Francis, 2005, 1st Edition.
2. Electromagnetic Compatibility of Electric Vehicle, Li Zhai, Springer 2021, 1st Edition.
3. EMC and Functional Safety of Automotive Electronics, Kai Borgeest, IET 2018, 1st Edition.
4. EMI/EMC Computational Modeling Handbook, Druce Archam beault, colin branch, Omar M.Ramachi ,Springer 2012, 2nd Edition.
5. Automotive EMC, Mark Steffika, Springer 2013, 1st Edition.
6. Electric Vehicle Systems Architecture and Standardization Needs, Reports of the PPP European Green Vehicles Initiative, Beate Müller, Gereon Meyer, Springer 2015, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1				2						3		2
CO2	3	1	1				1						3		2
CO3	3	1	1				2						3		2
CO4	3	1	1				1						3		2
CO5	3	1	1				2						3		3
Avg	3	1	1				1.8	2		3		2	3	3	2.3

TIEE3028 GRID INTEGRATION OF ELECTRIC VEHICLES L T P C

3 0 0 3

COURSE OBJECTIVES:

- To know the basic details of V2G
- To study the benefits & challenges of V2G
- To learn EV & V2G on the smart grids renewable energy systems
- To know the grid integration

UNIT I DEFINITION, And STATUS Of V2G (7+2 Skill) 9

Defining V2G - History and Development of V2G. Incorporating V2G to the EV, Auditing and Metering , V2G in Practice , V2G, Power Markets and Applications . Electricity Markets and V2G Suitability , Long-Term Storage, Renewable Energy, and Other Grid Applications , Beyond the Grid: Other Concepts Related to V2G.

UNIT II BENEFITS AND CHALLENGES OF V2G (7+2 Skill) 9

Benefits of V2G, Technical Benefits: Storage Superiority and Grid Efficiency, Economic Benefits: EV Owners and Societal Savings, Environment and Health Benefits: Sustainability in Electricity and Transport, Other Benefits.

UNIT III CHALLENGES TO V2G (7+2 Skill) 9

Technical Challenges-Battery Degradation, Charger Efficiency, Aggregation and Communication, V2G in a Digital Society. **The Economic and Business Challenges to V2G** - Evaluating V2G COsts and Revenues , EV COsts and Benefits , Adding V2G COsts and Benefits , Additional V2G COsts , The Evolving Nature of V2G COsts and Benefits. **Regulatory and Political Challenges to V2G** , V2G and Regulatory Frameworks , Market Design Challenges. Other V2G Regulatory and Legal Challenges.

UNIT IV IMPACT OF EV AND V2G ON THE SMART GRID AND RENEWABLE ENERGY SYSTEMS (7+2 Skill) 9

Introduction - Types of Electric Vehicles - Motor Vehicle Ownership and EV Migration - Impact of Estimated EVs on Electrical Network - Impact on Drivers and the Smart Grid - Standardization and Plug-and-Play - IEC 61850 Communication Standard and IEC 61850-7-420 Extension.

UNIT V GRID INTEGRATION AND MANAGEMENT OF EVS (7+2 Skill) 9

Introduction-M2M in distributed energy management systems - M2M communication for EVs - M2M communication architecture (3GPP) - Electric vehicle data logging - Scalability of electric vehicles - M2M communication with scheduling.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / etc) 10

1. Simulation of connecting three phase inverter to the grid.
2. Simulate and analyse the power quality issues of V2G systems
3. Design and simulate battery management system for smart grid with distributed generation.

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1 : Explain the concepts related with V2G
CO2 : Study the grid connection of 3 phase Q inverter
CO3 : Explain the technical, economics. business, regulatory & political challenges related with V2G
CO4 : Demonstrate the impact of EV and V2G on smart grid and renewable energy system
CO5 : Explain the concept of grid integration and management of EVs.

REFERENCES:

1. Advanced Electric Drive Vehicles, Ali Emadi, CRC Press 2017, 1st Edition.
2. Plug In Electric Vehicles in Smart Grids, Charging Strategies, Sumedha Rajakaruna , Farhad Shahnia and Arindam Ghosh,Springer,2015, 1st Edition.
3. ICT for Electric Vehicle Integration with the Smart Grid, Nand Kishor [1;] Jesus Fraile-Ardanuy, IET 2020, 1st Edition.
4. Vehicle-to-Grid: Linking Electric Vehicles to the Smart Grid, Junwei Lu and Jahangir Hossain, IET 2015, 1st Edition.
5. Lance Noel · Gerardo Zarazua de Rubens Johannes Kester · Benjamin K. Sovacool, Vehicle-to-Grid A Sociotechnical Transition Beyond Electric Mobility, 2019, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3						2	1		2			3	3	1
CO2	3	3			3		2	1		2			3		
CO3	3						2	1		2			3		
CO4	3						2	1		2			3		2
CO5	3						2	1		2			3		3
Avg	3	3			3		2	1		2			3	3	1.2

TIEE3029	INTELLIGENT CONTROL OF ELECTRIC VEHICLES	L	T	P	C
		2	0	2	3

COURSE OBJECTIVES:

- To design and drive the mathematical model of a BLDC motor and its characteristics
- To learn the different control schemes for BLDC motor
- To study the basics of fuzzy logic
- To study the FPGA & VHDL basics
- To implement fuzzy logic control of BLDC motor in real time

UNIT I MATHEMATICAL MODEL AND CHARACTERISTICS ANALYSIS OF THE BLDC MOTOR **6**

Structure and Drive Modes - Basic Structure, General Design Method, Drive Modes. Mathematical Model, Differential Equations, Transfer Functions, State-Space Equations. Characteristics Analysis, Starting Characteristics, Steady-State Operation, Dynamic Characteristics, Load Matching Commutation Transients.

UNIT II SPEED CONTROL FOR ELECTRIC DRIVES **6**

Introduction -PID Control Principle, Ant windup Controller, Intelligent Controller. Vector Control. Control applied to BLDC motor-.

UNIT III FUZZY LOGIC **6**

Membership functions: features, fuzzification, methods of membership value assignments Defuzzification: lambda cuts - methods - fuzzy arithmetic and fuzzy measures: fuzzy arithmetic - extension principle - fuzzy measures - measures of fuzziness -fuzzy integrals - fuzzy rule base and approximate reasoning : truth values and tables, fuzzy propositions, formation of rules decomposition of rules, aggregation of fuzzy rules, fuzzy reasoning-fuzzy inference systems, overview of fuzzy expert system-fuzzy decision making..

UNIT IV FPGA AND VHDL BASICS **6**

Introduction – FPGA Architecture-Advantages-Review of FPGA family processors- Spartan 3, Spartan 6 and Spartan 7. VHDL Basics- Fundamentals-Instruction set-data type-conditional statements- programs like arithmetic, sorting, PWM generation, Speed detection.

UNIT V REAL TIME IMPLEMENTATION **6**

Inverter design, identifying rotor position via hall effect sensors, open loop and fuzzy logic control of 48 V BLDC motor using FPGA**.** .

30 PERIODS

LAB COMPONENT: **30 PERIODS**

1. Design and simulate speed controller for induction motors in EV for both dynamic and steady state performance
2. Simulate a fuzzy logic controller based energy storage system for EV.
3. Fuzzy logic control of BLDC motor using FPGA in real time

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: To design the mathematical model of a BLDC motor and to discuss about its characteristics

CO2: To demonstrate the PID control, ant windup controller, Intelligent Controller and Vector

Control. Control applied to BLDC motor.

CO3: To illustrate the basics of fuzzy logic system

CO4: To describe the basics of VHDL & FPGA applied to control of EVs.

CO5: To design and implement of fuzzy logic control scheme for BLDC motor using FPGA in real time.

REFERENCES:

1. Electric Powertrain Energy Systems, Power Electronics and Drives for Hybrid, Electric and Fuel Cell Vehicles, John G. Hayes, G. Abas Goodarzi, Wiley 1st Edition 2018.
2. VHDL Primer, A (3rd Edition), Jayaram Bhasker, Prentice Hall, 1st Edition 2015.
3. Iqbal Hussain, "Electric and Hybrid Vehicles: Design Fundamentals, Third Edition" CRC Press, Taylor & Francis Group, 2021, 1st Edition.
4. Chang-liang, Permanent Magnet Brushless DC Motor Drives and Controls, Xia Wiley 2012, 1st Edition.
5. M.N. Cirstea, A. Dinu, J.G. Khor,M. McCormick, Neural and Fuzzy Logic Control of Drives and Power Systems, Newnes publications, 1st Edition, 2002.
6. Wei Liu, Hybrid Electric Vehicle System Modeling and Control, Wiley 2017, 2nd Edition
7. Electric and Plug-in Hybrid Vehicle Networks Optimization and Control, Emanuele Crisostomi • Robert Shorten, Sonja Stüdli • Fabian Wirth, CRC Press, 1st Edition. 2018.

MAPPING OF COs WITH POs AND PSOs

	PO 1	PO 2	PO3	PO 4	PO5	PO6	PO 7	PO 8	PO 9	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2	PSO 3
CO1	3	3	2	2				3		2		3	3	3	
CO2	3	3	2	2				3		2		3	3	3	3
CO3	3	3	3	3						2		3	3	2	3
CO4	3	3	3	3						2		3	3	3	3
CO5	3	3	3	3	3			3		2		3	3	3	3
Avg	3	3	2.6	2.6	3			3		2		3	3	2.8	2.4

TIEE3030 PROCESS MODELLING AND SIMULATION L T P C

3 0 0 3

COURSE OBJECTIVES:

- To understand the important of mathematical models for Industrial processes
- To acquaint students with different forms of mathematical models.
- To develop and simulate mathematical models for different Industrial processes.
- To apply Mathematical tools while developing mathematical models.
- To analyze the graphical response of developed mathematical models.

UNIT I GENERAL PRINCIPLES OF MODELLING (7+2 SKILL) 9

Introduction to mathematical modeling; Advantages and limitations of models and applications of process models of stand-alone unit operations and unit processes; Classification of models: Linear vs Nonlinear, Lumped parameter vs. Distributed parameter; Static vs. Dynamic, Continuous vs. Discrete; Numerical Methods: Iterative convergence methods, Numerical integration of ODE- IVP and ODEBVP

UNIT II MODELLING OF DISTRIBUTED PROCESSES (7+2 SKILL) 9

Steady state models giving rise to differential algebraic equation (DAE) systems; Rate basedApproaches for staged processes; Modeling of differential contactors – distributed parameter models of packed beds; Packed bed reactors; Modeling of reactive separation processes; Review of solution strategies for Differential Algebraic Equations (DAEs), Partial Differential Equations (PDEs), and available numerical software libraries.

UNIT III INTRODUCTION TO PROCESS MODELLING (7+2 SKILL) 9

Concept of degree of freedom analysis: System and its subsystem, System interaction, Degree of freedomin a system e.g. Heat exchanger, Equilibrium still, Reversal of information flow, Design variable selectionalgorithm, Information flow through subsystems, Structural effects of design variable selection, PersistentRecycle.

UNIT IV MODELLING OF INDUSTRIAL PROCESSES (7+2 SKILL) 9

Simple examples of process models; Models giving rise to nonlinear algebraic equation (NAE) systems, -steady state models of flash vessels, equilibrium staged processes distillation columns, absorbers,strippers, CSTR, heat exchangers, etc.; Review of solution procedures and available numerical softwarelibraries

UNIT V SIMULATION OF MATHEMATICAL MODELLING (7+2 SKILL) 9

Simulation and their approaches, Modular, Sequential, Simultaneous and Equation solving approach, Simulation softwares and their applications, Review of solution techniques and available numerical software libraries.- Case Studies.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Developing steady state /Dynamic mathematical model of different unit processes (ODE or PDE)
2. Simulation of steady state/ dynamic models using appropriate software
3. Open loop study based on the developed mathematical model.
4. Development and simulation of unsteady state models for simple processes.

COURSE OUTCOMES:

CO1 Will be able to understand different methods of developing models for industrial processes.

CO2 Able to build mathematical models by applying relevant mathematics.

CO3 Able to implement mathematical models using relevant software.

CO4 Effectively perform analysis and subsequent conclusion for the developed mathematical models.

CO5 Able to interpret the results obtained from the mathematical model in terms of original real world problem

TEXT BOOKS:

1. Denn M. M.,"Process Modeling", Longman, 1986, 1st Edition.
2. Aris R.,"Mathematical Modeling,A Chemical Engineering Perspective (Process System Engineering)", Academic Press, 1999, Volume 1.

REFERENCES:

1 .Luyben W.L., “Process Modeling, Simulation, and Control for Chemical Engineering”, McGraw Hill, 2nd Edition, 1990.
2. D. F. Rudd and C. C. Watson, “ Strategy of Process Engineering”, Wiley international, 1st Edition, 1968.
3. M.M. Denn, “Process Modelling”, Wiley, New York, 1st Edition, 1986.
4. A. K. Jana, “Chemical Process Modelling and Computer Simulation”, PHI,1st Edition, 2011.
5. C.D. Holland, “Fundamentals of Modelling Separation Processes”, Prentice Hall, , 1st Edition, 1975.
6. HussainAsghar, “Chemical Process Simulation”, Wiley Eastern Ltd., New Delhi, , 1st Edition, 1986.

List of Open Source Software/ Learning website:

https://archive.nptel.ac.in/courses/103/107/103107096/

https://nptel.ac.in/courses/103101111

https://nptel.ac.in/courses/111107105

https://www.academia.edu/37228967/Process_Modeling_Simulation_and_Control_for_Chemical_Engineers

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1-L4	3	1			2	1		1	1	1	1	1	1	2	2
2-L5	3	1	2			1		1	1	1	1	1	1	2	2
3-L5	1		2	3		1		1	1	1	1	1	1	2	2
4-L5	1		3			1	2	1	1	1	1	1	1	2	2
5-L5	1	2		3		1		1	1	1	1	1	1	2	2
Avg.	3	1			2	1	2	1	1	1	1	1	1	2	2

1-low, 2-medium, 3-high, ‘-“- no correlation -

TIEE3031	COMPUTER CONTROL OF PROCESSES	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To represent the linear time invariant System in discrete State Space form
- To analyze the controllability, observability and stability of a Discrete time System.
- To estimate model parameters from input/output measurements
- To Design Digital Controllers
- To Design Multi-loop and Multivariable Controllers for multivariable system

UNIT I DISCRETE STATE-VARIABLE TECHNIQUE (7+2 SKILL) 9

State equation of discrete data system with sample and hold – State transition equation – Methods of computing the state transition matrix – Decomposition of discrete data transfer functions – State diagrams of discrete data systems – System with zero-order hold – Controllability and observability of linear time invariant discrete data system–Stability tests of discrete-data system.

UNIT II SYSTEM IDENTIFICATION (7+2 SKILL) 9

Identification of Non-Parametric Input-Output Models: -Transient analysis–Frequency analysis– Correlation analysis– Spectral analysis – Identification of Parametric Input-Output Models: - Least Squares Method – Recursive Least Square Method.

UNIT III DIGITAL CONTROLLER DESIGN (7+2 SKILL) 9

Review of z-transform – Modified of z-transform – Pulse transfer function – Digital PID controller – Dead-beat controller and Dahlin's controller – Kalman's algorithm, Pole Placement Controller

UNIT IV MULTI-LOOP REGULATORY CONTROL (7+2 SKILL) 9

Multi-loop Control - Introduction – Process Interaction – Pairing of Inputs and Outputs -The Relative Gain Array (RGA) – Properties and Application of RGA - Multi-loop PID Controller – Biggest Log Modulus Tuning Method – De-coupler.

UNIT V MULTIVARIABLE REGULATORY CONTROL (7+2 SKILL) 9

Introduction to Multivariable control –Multivariable PID Controller – Multivariable Dynamic Matrix Controller – Case Studies: - Distillation Column, CSTR and Four-tank system.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/ Assignment/ Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Calculate the RGA to determine the recommended pairing between controlled and manipulated variables for any system.
2. Seminar on LS, RLS methods.
3. Design of DMC for distillation Column, CSTR and Four-tank systemin MATLAB.
4. Design a Multi-loop & Multivariable controller for MIMO system.
5. Design a model for any industrial process using parametric & non-parametric system.

COURSE OUTCOMES:

CO1 Develop mathematical models for discrete time systems using state variable techniques and analyze the stability of the systems. L4

CO2 Construct models from input-output data by least square and recursive least square method. L5

CO3 Ability to design different digital controllers to satisfy the required criterion. L5

CO4 Design a multi-loop controller and multivariable controller for multi-variable systems. L5

CO5 Ability to design multivariable dynamic matrix controller for industrial processes. L5

TEXT BOOKS:

1. Stephanopoulos, G., "Chemical Process Control -An Introduction to Theory and Practice", Prentice Hall of India, 1st Edition, 2015.
2. Sigurd Skogestad, Ian Postlethwaite, "Multivariable Feedback Control: Analysis and Design", John Wiley and Sons, 2005, 2nd Edition.

REFERENCE

1. Thomas E. Marlin, Process Control – Designing Processes and Control systems for Dynamic Performance, Mc-Graw-Hill,2000, 2nd Edition.
2. Gopal, M., "Digital Control and State Variable Methods", Tata Mc Graw Hill, 4th Edition, 2017.
3. P. Albertos and A. Sala, "Multivariable Control Systems An Engineering Approach", Springer Verlag, 1st Edition, 2004
4. Bequette, B.W., "Process Control Modeling, Design and Simulation", Prentice Hall of India, 1st Edition, 2003.
5. Dale E. Seborg, Duncan A. Mellichamp, Thomas F. Edgar, "Process Dynamics and Control", Wiley John and Sons, 4th Edition, 2016.

List of Open Source Software/ Learning website:

https://nptel.ac.in/courses/103104050

https://www.mathworks.com/matlabcentral/mlc-downloads/downloads/submissions/10816/versions/1/previews/Mimotools/rga.m/index.html
https://in.mathworks.com/help/ident/

https://ctms.engin.umich.edu/CTMS/index.php?example=Introduction&section=ControlDigital

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1-L4	3	3	3	2	1	1	1	1	1	1	1	1	2	2	2
2-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
3-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
4-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
5-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
Avg.	3	3	3	2.8	1	1	1	1	1	1	1	1	2	2	2

1-low, 2-medium, 3-high, '-"- no correlation –

TIEE3032	SYSTEM IDENTIFICATION	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To elaborate the concept of estimating the state variables of a system using state estimation algorithms.
- To elaborate the concept of estimating the parameters of the Input-output models using parameter estimation algorithms.
- To make the student understand the various closed loop system identification techniques.
- To make the student understand the various closed loop system identification techniques.
- To provide the background on the practical aspects of conducting experiments for real time system identification.

UNIT I NON PARAMETRIC METHODS (7+2 SKILL) 9

Nonparametric methods: Transient analysis - frequency analysis - Correlation analysis - Spectral analysis.

UNIT II PARAMETRIC METHODS (7+2 SKILL) 9

Parametric model structures: ARX, ARMAX, OE, BJ models - The Least square estimate - Best linear unbiased estimation under linear constraints - Updating the Parameter estimates for linear regression models - Prediction error methods: Description of Prediction error methods - Optimal Prediction – Relationships between prediction error methods and other identification methods - theoretical analysis. Instrumental variable methods: Description of Instrumental variable methods - Theoretical analysis - covariance matrix of IV estimates - Comparison of optimal IV and prediction error methods.

UNIT III RECURSIVE IDENTIFICATION METHODS (7+2 SKILL) 9

The recursive least squares method - Recursive Instrumental variable method-the recursive prediction error method-model validation and model structure determination. Identification of systems operating in closed loop: Identifiability considerations - Direct identification - Indirect identification - Joint input – Output identification.

UNIT IV CLOSED- LOOP IDENTIFICATION (7+2 SKILL) 9

Identification of systems operating in closed loop: direct identification and indirect identification – Subspace Identification methods: classical and innovation forms – Relay feedback identification of stable processes.

UNIT V NONLINEAR SYSTEM IDENTIFICATION (7+2 SKILL) 9

Modeling of nonlinear systems using ANN- NARX & NARMAX - Training Feed-forward and Recurrent Neural Networks – TSK model – Adaptive Neuro-Fuzzy Inference System (ANFIS) - Introduction to Support Vector Regression.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Familiarization of various system identification methods in MATLAB.
2. Seminar on ANFIS
3. Exploration of other advanced system identification methods.

COURSE OUTCOMES:

CO1 Ability to design and implement state estimation schemes. L5
CO2 Ability to develop various models (Linear & Nonlinear) from the experimental data. L5
CO3 Be able to choose a suitable model and parameter estimation algorithm for the

identification of systems. L3

CO4 Be able to illustrate verification and validation of identified model. L3

CO5 Ability to develop the model for prediction and simulation purposes using suitable control schemes. L5

TEXT BOOKS:

1. Lennart Ljung, "System Identification: Theory for the user", 2nd Edition, Prentice Hall, 1999.
2. Dan Simon, "Optimal State Estimation Kalman, H-infinity and Non-linear Approaches", John Wiley and Sons, 2006,
3. Tangirala, A.K., "Principles of System Identification: Theory and Practice", CRC Press, 2014, 1st Edition.

REFERENCE

1. Cortes, C., and Vapnik, V., "Support-Vector Networks, Machine Learning", 1995, 1st Edition.
2. Miller, W.T., Sutton, R.S., and Webrose, P.J., "Neural Networks for Control", MIT Press, 1996, 1st Edition.
3. Van der Heijden, F., Duin, R.P.W., De Ridder, D., and Tax, D.M.J., "Classification, Parameter Estimation and State Estimation", An Engineering Approach Using MATLAB, John Wiley & Sons Ltd., 2017, 2nd Edition.
4. Karel J. Keesman, "System Identification an Introduction", Springer, 2011, 1st Edition.
5. Tao Liu and Furong Gao, "Industrial Process Identification and control design, Step-test and relay-experiment-based methods", Springer- Verlag London Ltd., 2012, 1st Edition.

List of Open Source Software/ Learning website:

https://in.mathworks.com/help/ident/

https://nptel.ac.in/courses/103106149

https://in.mathworks.com/help/curvefit/nonparametric-fitting.html

https://nptel.ac.in/courses/111102143

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
2-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
3-L3	3	2	2	2	1	1	1	1	1	1	1	1	2	2	2
4-L3	3	2	2	2	1	1	1	1	1	1	1	1	2	2	2
5-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
AVg.	3	2.6	2.6	2.6	1	1	1	1	1	1	1	1	2	2	2

1-low, 2-medium, 3-high, '-"- no correlation

TIEE3033	MODEL BASED CONTROL	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To introduce the Knowledge about Multivariable and Multiloop systems.
- To understand the Model predictive control schemes and its elements.
- Get exposed to state space MPC along with case studies.
- To acquire knowledge on various constrained MPC.
- To make the student understand the principles of STR, MRAC and Gain scheduling.
- To make the student design simple adaptive controllers for linear systems

UNIT I INTRODUCTION TO MIMO CONTROL (7+2 SKILL) 9

Introduction to MIMO Systems-Multivariable control-Multiloop Control-Multivariable IMC-IMCPID-Case studies

UNIT II MODEL PREDICTIVE CONTROL SCHEMES (7+2 SKILL) 9

Introduction to Model Predictive Control - Model Predictive Control Elements - Generalized Predictive Control Scheme – Multivariable Generalized Predictive Control Scheme – Multiple Model based Model Predictive Control Scheme Case Studies

UNIT III STATE SPACE BASED MODEL PREDICTIVE CONTROL SCHEME (7+2 SKILL) 9

State Space Model Based Predictive Control Scheme - Review of Kalman Update based filters – State Observer Based Model Predictive Control Schemes – Case Studies

UNIT IV CONSTRAINED MODEL PREDICTIVE CONTROL SCHEME (7+2 SKILL) 9

Constraints Handling: Amplitude Constraints and Rate Constraints –Constraints and Optimization – Constrained Model Predictive Control Scheme – Case Studies.

UNIT V ADAPTIVE CONTROL SCHEME (7+2 SKILL) 9

Introduction to Adaptive Control-Gain Scheduling-Self tuning regulators–MARS-Adaptive Model Predictive Control Scheme –Case Studie

TOTAL:45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1 Explore various MIMO controllers presently used in industries.
2 Develop MPC, Adaptive and MIMO controllers for industrial processes.
3 Implement the controllers for MIMO systems.
4 Using software tools for practical exposures to the controllers used in industries by undergoing training.
5 Realisation of various optimization techniques for economical operation of process.

COURSE OUTCOMES:

Students able to

CO1 Ability to apply engineering knowledge to understand the control schemes on MIMO systems L3.
CO2 Ability to design controller for MIMO systemL5.
CO3 Ability to analyze the control schemes available in industries L4.
CO4 Ability to design MPC, Adaptive controllers for practical engineering problems L5.
CO5 Ability to choose suitable controllers for the given problems L5.

TEXT BOOKS:

1. Coleman Brosilow, Babu Joseph, “Techniques of Model-Based Control”, Prentice Hall PTR Pub 2002, 1st Edition.
2. E. F. Camacho, C. Bordons ,“Model Predictive Control”,Springer-Verlag London Limited 2007, 2nd Edition.
3. K.J. Astrom and B. J. Wittenmark, “Adaptive Control”, Second Edition, Pearson Education Inc., second Edition 2013.

REFERENCES:

1. Paul Serban Agachi, Zoltan K. Nagy, Mircea Vasile Cristea, and Arpad Imre-Lucaci Model Based Control Case Studies in Process Engineering,WILEY-VCH Verlag GmbH & Co. KGaA, Weinheim 2007.1st Edition.
2. Ridong Zhang, Anke Xue Furong Gao,“Model Predictive Control Approaches Based on the Extended State Space Model and Extended Non-minimal State Space Model”,Springer Nature Singapore Pte Ltd. 2019, 1st Edition.
3. J.A. ROSSITER “Model-Based Predictive Control A Practical Approach”Taylor & Francis e-Library, 2005, 1st edition.

List of Open Source Software/ Learning website:

1. https://nptel.ac.in/courses/103103037
2. https://nptel.ac.in/courses/108103007
3. https://onlinecourses.nptel.ac.in/noc21_ge01/preview
4. https://nptel.ac.in/courses/127106225

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1-L3	3	2	2	2	1	1	1	1	1	1	1	1	2	2	2
2-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
3-L4	3	3	3	2	1	1	1	1	1	1	1	1	2	2	2
4-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
5-L5	3	3	3	3	1	1	1	1	1	1	1	1	2	2	2
Avg.	3	2.8	2.8	2.6	1	1	1	1	1	1	1	1	2	2	2

1-low, 2-medium, 3-high, ‘-“- no correlation

TIEE3034	NON LINEAR CONTROL	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To provide knowledge on design in state variable form
- To provide knowledge in phase plane analysis.
- To give basic knowledge in describing function analysis.
- To study the design of optimal controller.
- To study the design of optimal estimator including Kalman Filter

UNIT I STATE VARIABLE DESIGN (7+2 SKILL) 9

Introduction to state Model- effect of state Feedback- Necessary and Sufficient Condition for Arbitrary Pole-placement- pole placement Design- design of state Observers- separation principle- servo design: -State Feedback with integral control

UNIT II PHASE PLANE ANALYSIS (7+2 SKILL) 9

Features of linear and non-linear systems - Common physical non-linearities – Methods of linearization Concept of phase portraits – Singular points – Limit cycles – Construction of phaseportraits – Phase plane analysis of linear and non-linear systems – Isocline method.

UNIT III DESCRIBING FUNCTION ANALYSIS (7+2 SKILL) 9

Basic concepts, derivation of describing functions for common non-linearities – Describing function analysis of non-linear systems – limit cycles – Stability of oscillations.

UNIT IV OPTIMAL CONTROL (7+2 SKILL) 9

Introduction - Time varying optimal control – LQR steady state optimal control – Solution of Ricatti's equation – Application examples.

UNIT V OPTIMAL ESTIMATION (7+2 SKILL) 9

Optimal estimation – KalmanBucy Filter-Solution by duality principle-Discrete systems-Kalman Filter-Application examples.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/ Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Design of linear quadratic regulator (LQR) control system for any application of your own
2. Familiarization of Kalman filter in MATLAB
3. Seminar on pole placement design

COURSE OUTCOMES:

Students able to

CO1 Able to apply the knowledge gained on state feedback control and nonlinear control. (L3)
CO2 Ability to carryout analysis for common nonlinearities in a system. (L4)
CO3 Apply advanced control theory to practical engineering problems. (L3)
CO4 Design optimal controller. (L5)
CO5 Understand the basics and Importance of Kalman filter. (L2)

TEXT BOOKS:

1. G. J. Thaler, "Automatic Control Systems", Jaico Publishing House 1993.
2. M.Gopal, Modern Control System Theory, New Age International Publishers, 2002, 2nd Edition.
3. K. P. Mohandas, "Modern Control Engineering", Sanguine Technical Publishers, 2006, 1st Edition.

REFERENCES:

1. Ashish Tewari, 'Modern Control Design with Matlab and Simulink', John Wiley, New Delhi, 2002, 1st Edition.
2. K. Ogata, 'Modern Control Engineering', 5th Edition, PHI, New Delhi, 2009.
3. T. Glad and L. Ljung,, "Control Theory –Multivariable and Non-Linear Methods", Taylor & Francis, 2002, 1st Edition.
4. D.S.Naidu, "Optimal Control Systems" First Indian Reprint, CRC Press, 2009, 1st Edition.
5. William S Levine, "Control System Fundamentals," The Control Handbook, CRC Press, Tayler and Francies Group, 2011, 2nd Edition.

List of Open Source Software/ Learning website:

https://in.mathworks.com/discovery/kalman-filter.html

https://in.mathworks.com/help/control/getstart/design-an-lqr-servo-controller-insimulink.html

https://onlinecourses.nptel.ac.in/noc22_ee24/preview

http://www.nitttrc.edu.in/nptel/courses/video/101108047/lec22.pdf

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1 L3	3	2	2	2	1	1	1	3	1	3	1	1	2	2	2
2 L4	3	3	3	2	1	1	1	3	1	3	1	1	2	2	2
3 L3	3	2	2	2	1	1	1	3	1	3	1	1	2	2	2
4 L5	3	3	3	3	1	1	1	3	1	3	1	1	2	2	2
5 L2	2	1	2	1	1	1	1	2	1	2	1	1	2	2	2
AVg.	2.8	2.2	2.4	2	1	1	1	2.8	1	2.8	1	1	2	2	2

1.low, 2-medium, 3-high, '-"- no correlation

TIEE3035 **OPTIMAL CONTROL** **L T P C**
3 0 0 3

COURSE OBJECTIVES:

- To provide an exposure to different type of optimal control problems such as time- optimal, fuel optimal, energy optimal control problems.
- To impart knowledge and skills needed to design Linear Quadratic Regulator for Time-invariant and Time-varying Linear system (Continuous time and Discrete-time systems).
- To introduce concepts needed to design optimal controller using Dynamic Programming Approach and H-J-B equation.
- To provide an exposure to various types of fault tolerant control schemes such as Passive and active approaches.
- To introduce concepts needed to design optimal controller in the presence of state constraints and time optimal controller.

UNIT I CALCULUS OF VARIATIONS AND OPTIMAL CONTROL (7+2 SKILL) 9

Introduction – Performance Index- Constraints – Formal statement of optimal control system – Calculus of variations – Function, Functional, Increment, Differential and variation and optimum of function and functional – The basic variation problem Extrema of functions and functional with conditions – variational approach to optimal control system

UNIT II LINEAR QUADRATIC OPTIMAL CONTROL SYSTEM (7+2 SKILL) 9

Problem formulation – Finite time Linear Quadratic regulator – Infinite time LQR system: Time Varying case- Time-invariant case – Stability issues of Time-invariant regulator – Linear Quadratic Tracking system: Fine time case and Infinite time case

UNIT III DISCRETE TIME OPTIMAL CONTROL SYSTEMS (7+2 SKILL) 9

Variational calculus for Discrete time systems – Discrete time optimal control systems:- Fixedfinal state and open-loop optimal control and Free-final state and open-loop optimal control - Discrete time linear state regulator system – Steady state regulator system

UNIT IV PONTRYAGIN MINIMUM PRINCIPLE (7+2 SKILL) 9

Pontryagin Minimum Principle – Dynamic Programming:- Principle of optimality, optimal control using Dynamic Programming – Optimal Control of Continuous time and Discrete-time systems – Hamilton-Jacobi-Bellman Equation – LQR system using H-J-B equation

UNIT V CONSTRAINED OPTIMAL CONTROL SYSTEMS (7+2 SKILL) 9

Time optimal control systems – Fuel Optimal Control Systems- Energy Optimal Control Systems – Optimal Control Systems with State Constraints

TOTAL:45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Interactive MATLAB based project learning in an optimal control system.
2. Familiarize yourself with optimal control software tool boxes.
3. Arrange a group brainstorming process to generate new ideas and possible solutions to an optimal control problem in any field.
4. Analyse the difference between optimal control systems with other types of control system.
5. Homework assignment on optimal control.

COURSE OUTCOMES:

Students able to

- **CO1** Explain different type of optimal control problems such as time-optimal, fuel optimal, energy optimal control problems.
- **CO2** Design Linear Quadratic Regulator for Time-invariant and Time-varying Linear system (Continuous time and Discrete-time systems)
- **CO3** Design optimal controller using Dynamic Programming Approach and H-J-B equation.
- **CO4** Explain the Pontryagin Minimum Principle.
- **CO5** Design optimal controller in the presence of state constraints and time optimal controller.
- **CO6** Understand the concepts of dynamic programming

TEXT BOOKS:

1. Donald E. Kirk, Optimal Control Theory – An Introduction, Dover Publications, Inc. Mineola, New York, 2012, 10th Edition.

REFERENCE BOOKS

1. D. Subbaram Naidu, Optimal Control Systems, CRC Press, New York, 2003, 1st Edition.
2. Frank L. Lewis, Draguna Vrabie, Vassilis L. Syrmos, Optimal Control, 3rd Edition, Wiley Publication, 2012, 3rd Edition.
3. Yan Wang, Cheng-Lin Liu, Zhi-Cheng Ji, Quantitative Analysis and Optimal Control of Energy Efficiency in Discrete Manufacturing System, Springer, 2020, 1st Edition.

List of Open Source Software/ Learning website:

- **1** https://in.mathworks.com/discovery/optimal-control.html#lgrlqg
- **2** https://www.codeproject.com/Articles/863257/Simple-Software-for-Optimal-Control
- **3** https://joss.theoj.org/papers/10.21105/joss.02809
- **4** https://www.ieee-ras.org/model-based-optimization-for-robotics/resources/optimization-tools
- **5** https://www.vlab.co.in/
- **6** https://ocw.mit.edu/courses/16-323-principles-of-optimal-control-spring-2008/

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	**2**	**3**	**4**	**5**	**6**	**7**	**8**	**9**	**10**	**11**	**12**	**1**	**2**	**3**
1	2	-	1		1	-	1	1	1	1	1	1	2	2	2
2		2	2	2	1	2	1	1	1	1	1	1	2	2	2
3	2	2	2		1	1	1	1	1	1	1	1	2	2	2
4	2	2	2		1	1	1	1	1	1	1	1	2	2	2
5	-	1	2	1	1	1	1	1	1	1	1	1	2	2	2
6	1	1	1	1	1	-	1	1	1	1	1	1	**2**	**2**	**2**
AVg.	2	2	1.75	2	**1**	1.3	**1**	**1**	**1**	**1**	**1**	**1**	2	2	2

1. low, 2-medium, 3-high, '-"- no correlation

TIEE3036	ADAPTIVE CONTROL	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES:

- To impart knowledge on how to recursively estimate the parameters of discrete input – output models using recursive parameter estimation methods
- To make the student understand the principles of STR, MRAC and Gain scheduling.
- To make the student design simple adaptive controllers for linear systems using STR, MRAC and Gain scheduling

UNIT I INTRODUCTION (7+2 SKILL) 9

Introduction - Adaptive Schemes - The adaptive Control Problem – Applications-Parameter estimation:-LS, RLS: and ERLS

UNIT II GAIN SCHEDULING (7+2 SKILL) 9

Introduction- The principle - Design of gain scheduling controllers- Nonlinear transformations - application of gain scheduling - Auto-tuning techniques: Methods based on Relay feedback.

UNIT III DETERMINISTIC SELF-TUNING REGULATORS (7+2 SKILL) 9

Introduction- Pole Placement design - Indirect Self-tuning regulators - direct self-tuning regulators – Disturbances with known characteristics

UNIT IV STOCHASTIC AND PREDICTIVE SELF-TUNING REGULATORS (7+2 SKILL) 9

Introduction – Design of minimum variance controller - Design of moving average controller - stochastic self-tuning regulators

UNIT V MODEL – REFERENCE ADAPTIVE SYSTEM (7+2 SKILL) 9

Introduction- MIT rule – Determination of adaptation gain - Lyapunov theory –Design of MRAS using Lyapunov theory – Relations between MRAS and STR.

TOTAL:45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Learn any one relevant software tool (MATLAB/ SCILAB/ LABVIEW/ Equivalent open source software)
2. Design of gain scheduling adaptive control using any one software tool
3. Analysis/Problem Solving - Ability to identify and define problems and solutions
4. Design and verification of MRAC by simulation.

COURSE OUTCOMES:

Students able to

- **CO1** Ability to apply the estimation algorithm to estimate the parameters of the process.(L3)
- **CO2** Ability to apply the adaptive control concepts to control a process. (L3)
- **CO3** Use appropriate software tools for design of adaptive controllers and analysis of the process. (L5)
- **CO4** Identify, formulate, carry out research by designing suitable adaptive schemes for complex instrumentation problem. (L5)
- **CO5** Apply the concepts to design adaptive control for multidisciplinary problem(L3)
- **CO6** Choose the techniques for self and lifelong learning to keep in pace with the new technology(L3)

TEXT BOOKS:

1. K.J. Astrom and B. J. Wittenmark, "Adaptive Control", Second Edition, Pearson Education Inc., second Edition 2013.

REFERENCE BOOKS

1. T. Soderstorm and Petre Stoica, "System Identification", Prentice Hall International(UK) Ltd., 1989, 1st Edition.
2. Lennart Ljung, "System Identification: Theory for the User", Second Edition, Prentice Hall, 1999.

List of Open Source Software/ Learning website:

1 https://archive.nptel.ac.in/courses/108/102/108102113/
2 https://in.mathworks.com/help/slcontrol/adaptive-control-design.html
3 https://in.mathworks.com/videos/nonlinear-model-based-adaptive-robust-controller-in-an-oil-and-gas-wireline-operation-1637577967956.html
4 https://www.dynalog-us.com/adaptive-robot-control.htm
5 https://www.vlab.co.in/

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	2	1	1	1	3	1	1	1	1	2	2	2
CO2	3	2	2	2	1	1	1	3	1	1	1	1	2	2	2
CO3	3	3	3	3	1	1	1	3	1	3	1	1	2	2	2
CO4	3	3	3	3	1	1	1	3	1	3	1	1	2	2	2
CO5	3	2	2	2	1	1	1	3	1	1	1	1	2	2	2
CO6	3	2	2	2	1	1	1	3	1	1	1	1	2	2	2
AVg.	3	2.3	2.3	2.3	1	1	1	3	1	1.6	1	1	2	2	2

1-low, 2-medium, 3-high, '-" - no correlation

TIEE3037 MACHINE MONITORING SYSTEM L T P C
3 0 0 3

COURSE OBJECTIVES:

- To make the students familiarize with the concept of condition-based maintenance for effective utilization of machines.
- To Impart the knowledge of artificial intelligence for machinery fault diagnosis.
- To give basic knowledge on vibration monitoring.
- To study the machinery vibrations using signal processing techniques.
- To provide knowledge on FMECA.

UNIT I INTRODUCTION TO MACHINE CONDITION MONITORING (7+2 SKILL) 9

Machinery condition monitoring - Present status - Fault prognosis - Future needs.

UNIT II MACHINERY MAINTENANCE (7+2 SKILL) 9

Maintenance strategies – Reactive, Preventive, and Predictive – Benefits of planned maintenance – Bath tub curve – Failure Modes Effects and Criticality Analysis (FMECA).

UNIT III INTRODUCTION TO MACHINERY VIBRATION AND MONITORING (7+2 SKILL) 9

Characteristics of Vibration systems – Mode shapes & operational deflection shapes – Experimental modal analysis – Principles of vibration monitoring – Machinery faults diagnosed by vibration analysis.

UNIT IV SIGNAL PROCESSING IN MACHINERY MONITORING (7+2 SKILL) 9

FFT analysis – Time domain analysis – Time-frequency analysis – Signal filtering – Cepstrum analysis – Health condition of compressor & engine.

UNIT V MACHINE LEARNING FOR CONDITION MONITORING (7+2 SKILL) 9

Machine Learning: Feature extraction and feature selection methods – Feature reduction – Classification techniques – Case studies of condition monitoring in Nuclear plant components, Distillation column.

TOTAL:45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/ Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Survey of critical machinery that requires monitoring system.
2. Exposure to practical machinery vibration & monitoring system presently in use.
3. Carryout FMECA using software.
4. Analyze the health condition of any machinery.

COURSE OUTCOMES:

- **CO1** Ability to identify the faults in machinery L1.
- **CO2** Choose the proper maintenance strategies and condition monitoring techniques for identification of failure in a machine L3.
- **CO3** Construct a classifier model for machine learning based fault diagnosis L5.
- **CO4** Predict the faulty component in a machine by analyzing the acquired vibration signals L2.
- **CO5** Ability to analyze & build a model using modern tools L4.

TEXT BOOKS:

1. Cornelius SchefferandPareshGirdhar, “Practical Machinery Vibration Analysis and Predictive Maintenance”, Elsevier, 2004, 1st Edition.
2. A. R. Mohanty, “Machinery Condition Monitoring: Principles and Practices” , CRC Press, Taylor & Francis, 1st Edition, 2017.

REFERENCES:

1 Stephen Marsland, Machine Learning: An Algorithmic Perspective, 2nd Edition, 2014, CRC, Press.

2. Collacot, "Mechanical Fault Diagnosis and Condition Monitoring", Chapman- Hall, 1st Edition, 2011.
3. Davies, "Handbook of Condition Monitoring – Techniques and Methodology", Springer, 1st Edition, 2011.
4. Ian H. Witten, Eibe Frank, Mark A. Hall, Data Mining: Practical Machine Learning Tools and Techniques, Elsevier, 3rd Edition 2011.
5. Ferdinand van der Heijden, Robert Duin, Dick de Ridder, David M. J. Tax, Classification, Parameter Estimation and State Estimation: An Engineering Approach Using MATLAB, John Wiley & Sons, 2nd Edition, 2017.

List of Open Source Software/ Learning website:

1 https://onlinecourses.nptel.ac.in/noc22_cs29/preview

2 https://www.udemy.com/topic/maintenance-management/

3 https://www.vi-institute.org/analyst-categories/

4 https://in.mathworks.com/help/predmaint/ug/condition-monitoring-and-prognostics-using-vibration-signals.html

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1-L1	1	1	1	1	1	1	1	1	1	1	1	1	1	2	2
2-L3	3	2	2	2	1	1	1	1	1	1	1	1	1	2	2
3-L5	3	3	3	3	1	1	1	1	1	1	1	1	1	2	2
4-L2	2	2	1	2	1	1	1	1	1	1	1	1	1	2	2
5-L4	3	3	3	2	1	1	1	1	1	1	1	1	1	2	2
Avg.	2.4	2.2	2	2	1	1	1	1	1	1	1	1	1	2	2

1-low, 2-medium, 3-high, '-"- no correlation

DIVERSIFIED COURSES

TIEE3038 ENERGY STORAGE SYSTEMS LT P C
3 0 0 3

COURSE OBJECTIVES:

Students will be able to:

- understand the various types of energy storage Technologies.
- analyze thermal storage system.
- analyze different battery storage technologies
- analyze the thermodynamics of Fuel Cell
- study the various applications of energy storage systems.

UNIT I INTRODUCTION (7+2 SKILL) 9

Necessity of energy storage – types of energy storage – comparison of energy storage technologies – Applications.

UNIT II THERMAL STORAGE SYSTEM (7+2 SKILL) 9

Thermal storage – Types – Modeling of thermal storage units – Simple water and rock bed storage system – pressurized water storage system – Modelling of phase change storage system – Simple units, packed bed storage units - Modelling using porous medium approach, Use of TRNSYS.

UNIT III ELECTRICAL ENERGY STORAGE (7+2 SKILL) 9

Fundamental concept of batteries – measuring of battery performance, charging and discharging, power density, energy density, and safety issues. Types of batteries – Lead Acid, Nickel – Cadmium, Zinc Manganese dioxide, Li-ion batteries - Mathematical Modelling for Lead Acid Batteries – Flow Batteries.

UNIT IV FUEL CELL (7+2 SKILL) 9

Fuel Cell – History of Fuel cell, Principles of Electrochemical storage – Types – Hydrogen oxygen cells, Hydrogen air cell, Hydrocarbon air cell, alkaline fuel cell, detailed analysis – advantages and disadvantages.

UNIT V ALTERNATE ENERGY STORAGE TECHNOLOGIES (7+2 SKILL) 9

Flywheel, Super capacitors, Principles & Methods – Applications, Compressed air Energy storage, Concept of Hybrid Storage – Applications, Pumped Hydro Storage – Applications.

TOTAL: 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / etc) 10

1. Model, simulate and analyze the performance characteristics of thermal storage systems
2. Develop a model for latent heat storage in phase changing materials.
3. Model, simulate and analyze the performance characteristics of Lead Acid Batteries
4. Model, simulate and analyze the performance characteristics of Fuel Cell
5. techno-economic analysis of different types of storage systems

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Understand different types storage technologies
CO2: Design a thermal storage system
CO3: Model battery storage system
CO4: Analyze the thermodynamics of fuel cell
CO5: Analyze the appropriate storage technologies for different applications
CO6: explore the alternate energy storage technologies.

TEXT BOOKS:

1. Ibrahim Dincer and Mark A. Rosen, 'Thermal Energy Storage Systems and Applications', John Wiley & Sons, 3rd Edition, 2021.
2. Ru-shi Liu, Lei Zhang and Xueliang sun, 'Electrochemical technologies for energy storage and conversion', Wiley publications, 2nd Volume set, 2012.
3. James Larminie and Andrew Dicks, 'Fuel cell systems Explained', Wiley publications, 3rd Edition, 2018.

REFERENCES:

1. Lunardini.V.J, 'Heat Transfer in Cold Climates', John Wiley and Sons 1981, 1st Edition.
2. Schmidt.F.W. and Willmott.A.J., 'Thermal Energy Storage and Regeneration', Hemisphere Publishing Corporation, 1981, 1st Edition.

List of Open Source Software/ Learning website:

1. Prof. Subhasish Basu Majumder, "Electrochemical Energy Storage", NPTEL Course, https://nptel.ac.in/courses/113105102.
2. Prof. PK Das, "Energy conservation and waste heat recovery", NPTEL Course, https://nptel.ac.in/courses/112105221.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1											2		3
3	3		2										2		3
3	3		2										2		3
3	3		2										2		3
3	3		2										2		3
3		3				2		1					2		3
Avg.	3	2	2			2		1					2		3

TIEE3039 HYBRID ENERGY TECHNOLOGY LT P C
3 0 0 3

COURSE OBJECTIVES:

- To provide knowledge about different types of hybrid energy systems.
- To analyze the various electrical Generators used for the Wind Energy Conversion Systems.
- To design the power converters used in SPV Systems.
- To analyze the various power converters used in hybrid energy systems and to understand the importance of standalone and grid-connected operation in Hybrid renewable energy systems.
- To analyze the performance of the various hybrid energy systems

UNIT I INTRODUCTION TO HYBRID ENERGY SYSTEMS (7+2 Skill) 9

Hybrid Energy Systems – Need for Hybrid Energy Systems – Solar-Wind-Fuel Cell-Diesel, Wind-Biomass-Diesel, Micro-Hydel-PV, Ocean and geyser energy - Classification of Hybrid Energy systems – Importance of Hybrid Energy systems – Advantages and Disadvantages - Environmental aspects of renewable energy - Impacts of renewable energy generation on the environment - Present Indian and international energy scenario of conventional and RE sources - Ocean energy, Hydel Energy - Wind Energy, Biomass energy, Hydrogen energy - Solar Photovoltaic (PV) and Fuel cells: Operating principles and characteristics.

UNIT II ELECTRICAL MACHINES FOR WIND ENERGY CONVERSION SYSTEMS (WECS) (7+2 Skill) 9

Review of reference theory fundamentals –Construction, Principle of operation and analysis: Squirrel Cage Induction Generator (SCIG), Doubly Fed Induction Generator (DFIG) - Permanent Magnet Synchronous Generator (PMSG).

UNIT III POWER CONVERTERS AND ANALYSIS OF SOLAR PV SYSTEMS (7+2 Skill) 9

Power Converters for SPV Systems **-** Line commutated converters (inversion-mode) - Boost and buck-boost converters- selection of inverter, battery sizing, array sizing - Analysis of SPV Systems - Block diagram of the solar PV systems - Types of Solar PV systems: Stand-alone PV systems,

UNIT IV ANALYSIS OF POWER CONVERTERS FOR HYBRID ENERGY SYSTEMS (7+2 Skill) 9

Introduction to Power Converters **–** Stand-alone Converters -AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters - Bi-Directional Converters - Grid-Interactive Inverters - Matrix converter – Merits and Limitations.

UNIT V CASE STUDIES FOR HYBRID RENEWABLE ENERGY SYSTEMS (7+2 Skill) 9

Hybrid Systems- Range and type of Hybrid systems – Performance Analysis – COst Analysis - Case studies of Diesel-PV, Wind-PV-Fuel-cell, Micro-hydel-PV, Biomass-Diesel-Fuel-cell systems.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Simulation of Wind energy conversion system
2. Simulation of power converters
3. Simulations of AC-DC-AC converters, PWM inverters and Matrix Converters with Resistive and dynamic loads

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: Analyze the impacts of hybrid energy technologies on the environment and demonstrate them to harness electrical power.

CO2: Select a suitable Electrical machine for Wind Energy Conversion Systems and simulate wind energy conversion system

CO3: Design the power converters such as AC-DC, DC-DC, and AC-AC converters for SPV systems.

CO4: Analyze the power converters such as AC-DC, DC-DC, and AC-AC converters for Hybrid energy systems.

CO5: Interpret the hybrid renewable energy systems.

TEXTBOOKS:

1. Bahman Zohuri, "Hybrid Energy Systems", Springer, First Edition, 2018.
2. S.M. Muyeen, "Wind Energy Conversion Systems", Springer First Edition, 2012
3. Md. Rabiul Islam, Md. Rakibuzzaman Shah, Mohd Hasan Ali, "Emerging Power Converters for Renewable Energy and Electric Vehicles", CRC Press, First Edison, 2021

REFERENCES:

1. Ernst Joshua, Wind Energy Technology, PHI, India, 2018, 3rd Edition.
2. S.N.Bhadra, D. Kastha, & S. Banerjee "Wind Electrical Systems", Oxford University Press, 7th Impression, 2005.
3. Rashid.M. H "Power electronics Hand book", Academic press,4th Edition, 2018.
4. Rai. G.D, "Non-conventional energy sources", Khanna publishers, 6th Edition, 2017.
5. Rai. G.D, "Solar energy utilization", Khanna publishers, 3rd Edition, 1987.
6. Gray, L. Johnson, "Wind energy system", Prentice Hall of India, 2nd Edition, 2006.
7. B.H.Khan "Non-conventional Energy sources", Tata McGraw hill Publishing Company, New Delhi, 2017, 3rd Edition.

List of Open Source Software/ Learning website:

1. https://www.sciencedirect.com/topics/engineering/hybrid-energy-system
2. https://www.sciencedirect.com/topics/engineering/wind-energy-conversion-system
3. https://www.academia.edu/35619294/Modeling_and_Performance_Analysis_of_Solar_PV_S
4. System_and_DC_DC_Converters
5. https://www.mdpi.com/journal/energies/special_issues/Power_Converter_Electric_Machines
6. _Renewable_Energy_Systems_Transportation
7. https://www.intechopen.com/chapters/64317

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2						3		3	3	3	3
CO2	3	3	3	2	3					3		3	3	3	3
CO3	3	3	3	2	3					3		3	3	3	3
CO4	3	3	3	2	3					3		3	3	3	3
CO5	3	3	3	2						3		3	3	3	3
Avg	3	3	3	2	3					3		3	3	3	3

TIEE3040 **DESIGN AND MODELLING OF RENEWABLE ENERGY SYSTEMS** **L T P C 3 0 0 3**

COURSE OBJECTIVES:

- To review the renewable energy systems and technology
- To learn the Single phase grid-connected photovoltaic systems and three phase photovoltaic systems
- To illustrate the small wind energy systems
- To simulate the Doubly-fed induction generator based WECS

UNIT I RENEWABLE ENERGY SYSTEMS: TECHNOLOGY OVERVIEW AND PERSPECTIVES **(7+2 Skill) 9**

Introduction-State of the Art- Examples of Recent Research and Development Challenges and Future Trends

UNIT II SINGLE-PHASE GRID-CONNECTED PHOTOVOLTAIC SYSTEMS (7+2 Skill) 9

Introduction- Demands for Grid-Connected PV Systems-Power Converter Technology for Single-Phase PV Systems, Transformer less AC-Module Inverters (Module-Integrated PV Converters, Transformer less Single-Stage String Inverters, DC-Module Converters in Transformer less Double-Stage PV Systems

UNIT III THREE-PHASE PHOTOVOLTAIC SYSTEMS: STRUCTURES, TOPOLOGIES **(7+2 Skill) 9**

Introduction-PV Inverter Structures, Three-Phase PV Inverter Topologies- -Control Building Blocks for PV Inverters, Modulation Strategies for Three-Phase PV Inverters, Implementation of the Modulation Strategies., Grid Synchronization, Implementation of the PLLs for Grid Synchronization, Current Control, Implementation of the Current Controllers, Maximum Power Point Tracking.

UNIT IV SMALL WIND ENERGY SYSTEMS **(7+2 Skill) 9**

Introduction-Generator Selection for Small-Scale Wind Energy Systems- Turbine Selection for Wind Energy- Self-Excited Induction Generators for Small Wind Energy Applications- Permanent Magnet Synchronous Generators for Small Wind Power Applications- Grid-Tied Small Wind Turbine Systems-Magnus Turbine–Based Wind Energy System

UNIT V DOUBLY-FED INDUCTION GENERATOR-BASED WECS (7+2 Skill) 9

Introduction – modelling of induction machine in machine variable form and arbitrary reference frame, modelling of Doubly-fed Induction Generator.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 10

1. Simulation of inverter for PV systems
2. Simulation of WECS with DFIG

List of Open Source Software/ Learning website:

1. https://www.mdpi.com/journal/applsci/topical_collections/Susta_Energy
2. https://www.mathworks.com/help/sps/ug/single-phase-grid-connected-in-pv-system.html
3. https://www.sciencedirect.com/topics/engineering/three-phase-inverter
4. academia.edu/32704493/Wind_Power_Lecture_Notes
5. https://www.syscop.de/files/2018ss/WES/handouts/script.pdf
6. https://www.sciencedirect.com/topics/engineering/wound-rotor-induction-generator

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: Review the perspectives of renewable energy systems
CO2: Integrate photovoltaic systems with grid
CO3: Study inverter for PV systems
CO4: Elaborate the working of small wind power systems
CO5: Study the features of induction machine and doubly fed induction machine

TEXT BOOKS:

1. Ahmad Azar, Nashwa Kamal, "Design, Analysis and Applications of Renewable Energy Systems", Academic Press, First Edition, 2021
2. Ahmad Azar, Nashwa Kamal, "Renewable Energy Systems", Academic Press, First Edition, 2021
3. Nabil Derbel, Quanmin ZhuModeling, "Identification and Control Methods in Renewable Energy Systems" , Springer, First Edition, 2019

REFERENCES:

1. Power Conversion and Control of Wind Energy Systems, Bin Wu, 2011, Wiley-IEEE, 1st Edition.
2. Wind Electrical Systems, S.N. Bhadra, 2005, Oxford, 7th Impression.
3. Wind Power Integration - Connection and System Operational Aspects, Brendan Fox, 2014, IET, 2nd Edition.
4. Renewable Energy Devices and Systems with Simulations in MATLAB and ANSYS, Frede Blaabjerg, Dan M. Ionel, CRC press, 2017, 1st Edition.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		3	2									3		2
CO2	3	2	3	3									3	3	3
CO3	3	2	3	3	2								3	3	3
CO4	3	2	3	3									3	3	3
CO5	3	2	3	3	2								3	3	3
Avg	3	2	3	2.8	2								3	3	2.8

TIEE3041 GRID INTEGRATING TECHNIQUES AND CHALLENGES L T P C

2 0 2 3

COURSE OBJECTIVES:

- To study about the present power Scenario
- To model a micro grid system
- To model power converter for grid interconnection
- To integrate wind energy conversion system with grid
- To simulate power converters like three phase inverters and DC-DC converters

UNIT I PRESENT POWER SCENARIO IN INDIA 6

Introduction - Thermal Power Plant , Components of Thermal Power Plant , Major Thermal Power Plants in India- Gas-Based Power Generation - Nuclear Power Plants -Hydropower Generation - Pumped Storage Plants - Solar Power - Wind Energy – Power plants India

UNIT II POWER GRIDS 6

Introduction -Electric Power ,Background , The Construction of a Power Grid System , Basic Concepts of Power Grids -Load Models - Transformers in Electric Power Grids - Modelling a Microgrid System

UNIT III MODELING OF CONVERTERS IN POWER GRID DISTRIBUTED GENERATION SYSTEMS 6

Introduction - Single-Phase DC/AC Inverters with Two Switches, Three-Phase DC/AC Inverters, Pulse Width Modulation Methods, The Triangular, The Identity Method, Analysis of DC/AC Three-Phase Inverters. Micro grid of Renewable Energy Systems- DC/DC Converters in Green Energy -Pulse Width Modulation -Sizing of an Inverter for Microgrid Operation, Sizing of a Rectifier for Microgrid Operation, The Sizing of DC/DC Converters for Micro grid

UNIT IV WIND ENERGY SYSTEM GRID INTEGRATION 6

Introduction- Significance of Electrical Power Quality in Wind Power System- Integration Issues in Grid-Connected Wind Energy- Effect of Power Quality Issues, Importance of Custom Power

Devices- Power Quality Point of View.

UNIT V GRID INTER CONNECTION **6**

Grid Code requirements-Grid integration of WECS-Grid Integration of PV systems

30 PERIODS

LAB COMPONENT **30 PERIODS**

1. Develop a model for the control of DC micro grid for non linear loads
2. Simulation study of three phase inverters with fixed and sine PWM techniques, Simulation and Design of buck/boost converters.
3. Simulate a Grid Connected Wind Energy System with STATCOM and investigate the improvement in power quality.

TOTAL: 30+30 = 60 PERIODS

COURSE OUTCOMES:

Upon completion of the course, Students able to

CO1 Review the power sector scenario in India.

CO2 Model a microgrid system

CO3 Model a converter for power grid distributed system.

CO4 Integrate wind energy system.

CO5 Simulate three phase inverter with fixed and sine PWM.

TEXT BOOKS:

1. Brian D'Andrade "The Power Grid", Academic Press, 1st Edition, 2017.
2. Yang Han, "Modeling and Control of Power Electronic Converters for Microgrid Applications", Springer, 1st Edition 2022.
3. Siegfried Heier, "Grid Integration of Wind Energy: Onshore and Offshore Conversion Systems", John Wiley & Sons, Ltd, 2014, 3rd Edition.

REFERENCES:

1. Integration of Renewable Energy Sources with Smart Grid, M. Kathiresh, A. Mahaboob Subahani, and G.R. Kanaga chidambaresan, Scrivener & Wiley, 2021, 1st Edition.
2. Control and Operation of Grid-Connected Wind Energy Systems, Ali M. Eltamaly, Almoataz Y. Abdelaziz, Ahmed G. Abo-Khalil, Springer 2021, 1st Edition.
3. Design of smart power grid renewable energy systems, Third Edition, Ali Keyhani, Wiley 2019.
4. Power Electronic Converters, Teuvo Suntio, Tuomas Messo, Joonas Puukko, Wiley 2017, 1st Edition.
5. Fundamentals of Power Electronics with MATLAB, Randall Shaffer, Laxmi publications, 2013, 2nd Edition.
6. Power Conversion and Control of Wind Energy Systems, Bin Wu, 2011, Wiley-IEEE, 1st Edition.
7. Wind Power Integration - Connection and System Operational Aspects, Brendan Fox, 2014, IET, 2nd Edition.
8. Renewable Energy Devices and Systems with Simulations in MATLAB and ANSYS, Frede Blaabjerg, Dan M. Ionel, CRC press, 2017, 1st Edition.

List of Open Source Software/ Learning website:

1. https://www.academia.edu/14628492/Current_Power_Scenario_In_India
2. https://energyeducation.ca/encyclopedia/Electrical_grid
3. https://www.academia.edu/32120081/Power_Converters_Modeling_in_Matlab_Simulink_for_Micr
4. ogrid_Simulations_Power_Converters_Modeling_in_Matlab_Simulink_for_Microgrid_Simulations
5. https://dnv.com/services/wind-farm-control-and-grid-integration
6. https://www.wind-energy-the-facts.org/images/chapter2.pdf

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3									3		3	3	3	3
CO2	3		2		3					3		3	3	3	3
CO3	3	3	3	2	3					3		3	3	3	3
CO4	3	3	1	3	3					3		3	3	3	3
CO5	3	3	2	3						3		3	3	3	3
Avg	3	3	2	2	3					3		3	3	3	3

TIEE3042 SUSTAINABLE AND ENVIRONMENTAL FRIENDLY HV INSULATION SYSTEM **LT P C 3 0 0 3**

COURSE OBJECTIVES:

- To Know about the products related with sustainable applicaton.
- To learn about Green Gaseous, liquid solid insulators.
- To understand the standards for green insulation systems.

UNIT I SUSTAINABLE AND ENVIRONMENTAL ENERGY AND PRODUCTS 9

Carbon print, global warming potential, environment requirement for any product and system.

UNIT II ALTERNATE GREEN GASEOUS INSULATORS 9

SF6 gas and its hazardous environmental effects, alternate gases, gaseous mixtures and other sources and it's properties.

UNIT III ALTERNATE GREEN LIQUID INSULATORS 9

hazardous effects of existing liquid dielectric materials (such as organic oil), alternate sources of environmental friendly liquid such as ester oil, vegetable oils dielectric and it's properties.

UNIT IV ALTERNATE GREEN SOLID INSULATORS 9

hazardous effects of existing solid dielectric materials, alternate sources of environmental friendly solid dielectric and its properties.

UNIT V EVOLVING STANDARDS FOR GREEN INSULATION SYSTEMS 9

Requirements, evolving standards of management, testing, usage and disposal of alternate insulation systems, Major applications and standards

TOTAL : 45 PERIODS

REFERENCES:

1. https://www.iso.org/standard/79064.html
2. https://www.ictfootprint.eu/en/iec-tr-627252013-factsheet
3. https://www.iec.ch/dyn/www/f?p=103:7:0::::FSP_ORG_ID,FSP_LANG_ID:1275,25
4. https://www.iec.ch/ords/f?p=103:41:628762356646470::::FSP_ORG_ID,FSP_LANG_ID:3237, 25
5. https://www.iec.ch/dyn/www/f?p=103:7:0::::FSP_ORG_ID,FSP_LANG_ID:1299,25
6. https://www.iec.ch/sdgs/sdg13
7. http://highperformanceinsulation.eu/wp- content/uploads/ 2016/08/ sustainability_a_guide.pdf

COURSE OUTCOMES:

Upon completion of the course, students will be able to:

CO1: Know about sustainable and environmental energy and products.
CO2: Describe the alternate green gaseous insulators.
CO3: Describe the alternate green liquid insulators
CO4: Describe the alternate green solid insulators
CO5: Elaborate the standards for Green insulation systems.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		3				3						3		3
CO2	3		3				3						3		3
CO3	3		3				3						3		3
CO4	3		3				3						3		3
CO5	3		3				3						3		3
Avg	3		3				3						3		3

TIEE3043 POWER SYSTEM TRANSIENTS LT P C
3 0 0 3

OBJECTIVES:

- To study the generation of switching transients and their control using circuit – theoretical concept.
- To study the mechanism of lighting strokes and the production of lighting surges.
- To study the propagation, reflection and refraction of travelling waves.
- To study the impact of voltage transients caused by faults, circuit breaker action, load rejection on integrated power system.

UNIT I INTRODUCTION AND SURVEY (7+2 Skill) 9

Sources of different types of transients - RL circuit transient with sine wave excitation - double frequency transients - basic transforms of the RLC circuit transients - study of transients in system planning - Importance of grounding.

UNIT II SWITCHING TRANSIENTS (7+2 Skill) 9

Basic concept of switching transients - resistance switching and equivalent circuit for interrupting the resistor current - load switching and equivalent circuit - waveforms for transient voltage across the load and the switch - normal and abnormal switching transients. Current suppression - current chopping - effective equivalent circuit - capacitance switching with a restrike, with multiple restrikes - ferro resonance.

UNIT III LIGHTNING TRANSIENTS (7+2 Skill) 9

Theories of cloud formation - mechanism of lightning discharges and characteristics of lightning strokes – model for lightning stroke - factors contributing to good line design - protection using ground wires - tower footing resistance - Interaction between lightning and power system.

UNIT IV TRAVELING WAVES ON TRANSMISSION LINE COMPUTATION OF TRANSIENTS (7+2 Skill) 9

Computation of transients - transient response of systems with series and shunt lumped parameters and distributed lines. Traveling wave concept - step response - Bewely's lattice diagram - standing waves and natural frequencies - reflection and refraction of travelling waves. Computation of overvoltages using EMTP.

UNIT V TRANSIENTS IN INTEGRATED POWER SYSTEM 9

The short line and kilometric fault - distribution of voltages in a power system - Line dropping and load rejection - voltage transients on closing and reclosing lines - overvoltage induced by faults - switching surges on integrated system Qualitative application of EMTP for transient computation.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) 8

1. Simulation of circuit transients
2. Computation of over voltages for switching surges
3. Computation of over voltages for lightning surges
4. Computation of transients

COURSE OUTCOMES:

After completing the course, the students will be above to

CO1 : Explain the principles of transients and its concepts

CO2 : Know the different types of switching transients and the way to draw the necessary equivalent circuit.

CO3: Explain the concepts behind lighting and the way to protect the same.

CO4: Compute the transient behavior in transmission line

CO5: Explain the behavior of the Circuit during switching and to learn the simulation tool.

TEXT BOOKS:

1. Allan Greenwood, 'Electrical Transients in Power Systems', Wiley Inter Science, New York, 2nd Edition, 1991.
2. Pritindra Chowdhari, "Electromagnetic transients in Power System", John Wiley and Sons Inc., Second Edition, 2009.
3. C.S. Indulkar, D.P.Kothari, K. Ramalingam, 'Power System Transients – A statistical approach', PHI Learning Private Limited, Second Edition, 2010.

REFERENCES:

1. M.S.Naidu and V.Kamaraju, 'High Voltage Engineering', Tata McGraw Hill, Fifth Edition, 2013.
2. R.D. Begamudre, 'Extra High Voltage AC Transmission Engineering', Wiley Eastern Limited, 1986.
3. Y.Hase, Handbook of Power System Engineering," Wiley India, 2012.
4. J.L.Kirtley, "Electric Power Principles, Sources, Conversion, Distribution and use," Wiley, 2012.

MAPPING OF COs WITH POs AND PSOs

	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	3	3	3	2		2					3	3	3	3
CO2	3	3	3	3	2		2					3	3	3	3
CO3	3	3	3	3	2		2					3	3	3	3
CO4	3	3	3	3	2		2					3	3	3	3
CO5	3	3	3	3	2		2					3	3	3	3
Avg	3	3	3	3	2		2					3	3	3	3

TIEE3044 PLC PROGRAMMING L T P C
3 0 0 3

COURSE OBJECTIVES:

To know about the basics of PLC and Automation
To understand the importance of Automation
To explore various types and manufactures of PLCs.
To introduce types of programming languages of PLC and some exercise few programs.

UNIT I INTRODUCTION (7+2 SKILL) 9

Programmable Logic Controller (PLC)- Block diagram of PLC- Programming languages of PLC- Basic instruction sets- Design of alarm and interlocks- Networking of PLC- Overview of safety of PLC with case studies- Process Safety Automation: Levels of process safety through use of PLCs- IEC 61131-3 Standard - Application of international standards in process safety control.

UNIT II IEC 61131-3 (7+2 SKILL) 9

Rails- Rungs- Relay Logic- Latch switch- Timers- Counters- Boolean logics- Math Instructions- Data manipulation Instructions- Requirement of communication networks for PLC, PLC to PC Communication to computer- FBD equivalent to LL- FBD Programming- IL- SFC-ST.

UNIT III SCADA (7+2 SKILL) 9

Elements of SCADA system- History of SCADA, Remote Terminal Unit- Discrete control- Analog control, Master Terminal Unit- Operator interface.

UNIT IV HART and Field Bus (7+2 SKILL) 9

Introduction- Evolution of signal standards- HART communication protocol- communication modes- HART networks- HART commands- HART and OSI model- Field bus- Architecture- Basic requirements of field Busstandard- Field bus Topology- Interoperability- Interchangeability.

UNIT V PLC PROGRAMMING (7+2 SKILL) 9

Exercise in Programming Languages from IEC 61131-3: Traffic Light Control- Two way- Four way – Water Level Control- Automatic Material Sorting System- Automatic Bottle Filling System, Code Converters- DC motor Control- Alarm Circuit.

TOTAL : 45 PERIODS

SKILL DEVELOPMENT ACTIVITIES (Group Seminar/Mini Project/Assignment/Content Preparation / Quiz/ Surprise Test / Solving GATE questions/ etc) **10**

1 Taking Local area to implement simple closed loop system for any system using PLC.
2 Making a complete automated control loop with Supervisory and HMI system.
3 Implementing an Alarm based control scheme and run in a simulated environment.
4 Designing an entire PLC logic for filling and draining water tank automatically.

COURSE OUTCOMES:

CO1 Understand the basics and need for Automation in industries .
CO2 Explain the logic and flow of any particular programming written for a process .
CO3 Apply the knowledge to design or improve an existing program to increase productivity of any process .
CO4 Breakdown SCADA architecture and communication protocols.
CO5 Build and logic in any of the programming languages from IEC- 61131- 3 standard .

TEXT BOOKS:

1. Frank D. Petruzella, “Programmable Logic Controllers”, 5th Edition, McGraw- Hill, New York, 2019.
2. Stuart Boyer A, “SCADA: Supervisory control and data Acquisition”, Fourth Edition, ISA- The Instrumentation, Systems, and Automation Society,2010

REFERENCES

1. Bolton. W, “Programmble Logic Controllers”, Elsevier Newnes, 6th Edition 2015.

List of Open-Source Software/ Learning website:

1 https://nptel.ac.in/courses/108105062
2 https://nptel.ac.in/courses/108105088
3 http://www.nitttrc.edu.in/nptel/courses/video/105105201/lec56.pdf
4 https://nptel.ac.in/courses/108106022
5 https://new.siemens.com/global/en/products/automation/systems/industrial/plc/logo/logo-software.html
6 https://componentsearchengine.com/library/proteus?gclid=CjwKCAjw_ISWBhBkEiwAdqxb9okU2ZZHcQoa9fSRK2Uq41Rq0GZxdGUP6_6GlBv77p4JqGt_iDAljhoCksEQAvD_BwE

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2	2	2	-	-	-	1	-	1	-	-	-	-	-
CO2	2	2	2	2	-	-	-	1	-	1	-	-	-	-	-
CO3	3	2	2	2	-	-	-	1	-	1	-	-	-	-	-
CO4	3	3	3	2	-	-	-	1	-	1	-	-	-	-	-
CO5	3	2	2	2	-	-	-	1	-	1	-	-	-	-	-
AVg.	2.6	2.2	2.2	2	-	-	-	1	-	1	-	-	-	-	-

1-low, 2-medium, 3-high, '-" - no correlation

TIEE3045 BIG DATA ANALYTICS L T P C
2 0 2 3

COURSE OBJECTIVES:

- To understand big data.
- To learn and use NoSQL big data management.
- To learn mapreduce analytics using Hadoop and related tools.
- To work with map reduce applications
- To understand the usage of Hadoop related tools for Big Data Analytics

UNIT I UNDERSTANDING BIG DATA 5

Introduction to big data – convergence of key trends – unstructured data – industry examples of big data – web analytics – big data applications– big data technologies – introduction to Hadoop – open source technologies – cloud and big data – mobile business intelligence – Crowd sourcing analytics – inter and trans firewall analytics.

UNIT II NOSQL DATA MANAGEMENT 7

Introduction to NoSQL – aggregate data models – key-value and document data models – relationships – graph databases – schemaless databases – materialized views – distribution models – master-slave replication – consistency - Cassandra – Cassandra data model – Cassandra examples – Cassandra clients

UNIT III MAP REDUCE APPLICATIONS 6

MapReduce workflows – unit tests with MRUnit – test data and local tests – anatomy of MapReduce job run – classic Map-reduce – YARN – failures in classic Map-reduce and YARN – job scheduling – shuffle and sort – task execution – MapReduce types – input formats – output formats.

UNIT IV BASICS OF HADOOP 6

Data format – analyzing data with Hadoop – scaling out – Hadoop streaming – Hadoop pipes – design of Hadoop distributed file system (HDFS) – HDFS concepts – Java interface – data flow –

Hadoop I/O – data integrity – compression – serialization – Avro – file-based data structures - Cassandra – Hadoop integration.

UNIT V HADOOP RELATED TOOLS 6

Hbase – data model and implementations – Hbase clients – Hbase examples – praxis. Pig – Grunt – pig data model – Pig Latin – developing and testing Pig Latin scripts. Hive – data types and file formats – HiveQL data definition – HiveQL data manipulation – HiveQL queries.

TOTAL:30 PERIODS

COURSE OUTCOMES:

After the completion of this course, students will be able to:

- Describe big data and use cases from selected business domains.
- Explain NoSQL big data management.
- Install, configure, and run Hadoop and HDFS.
- Perform map-reduce analytics using Hadoop.
- Use Hadoop-related tools such as HBase, Cassandra, Pig, and Hive for big data analytics.

LIST OF EXPERIMENTS: PRACTICALS:30 PERIODS

1. Downloading and installing Hadoop; Understanding different Hadoop modes. Startup scripts, Configuration files.
2. Hadoop Implementation of file management tasks, such as Adding files and directories, retrieving files and Deleting files
3. Implement of Matrix Multiplication with Hadoop Map Reduce
4. Run a basic Word Count Map Reduce program to understand Map Reduce Paradigm.
5. Installation of Hive along with practice examples.
7. Installation of HBase, Installing thrift along with Practice examples
8. Practice importing and exporting data from various databases.

Software Requirements:

Cassandra, Hadoop, Java, Pig, Hive and HBase.

TOTAL:60 PERIODS

TEXT BOOKS:

1. Michael Minelli, Michelle Chambers, and AmbigaDhiraj, "Big Data, Big Analytics: Emerging Business Intelligence and Analytic Trends for Today's Businesses", Wiley, 2013.
2. Eric Sammer, "Hadoop Operations", O'Reilley, 2012.
3. Sadalage, Pramod J. “NoSQL distilled”, 2013

REFERENCES:

1. E. Capriolo, D. Wampler, and J. Rutherglen, "Programming Hive", O'Reilley, 2012.
2. Lars George, "HBase: The Definitive Guide", O'Reilley, 2011.
3. Eben Hewitt, "Cassandra: The Definitive Guide", O'Reilley, 2010.
4. Alan Gates, "Programming Pig", O'Reilley, 2011.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	3	3	3	3	3	-	-	-	2	2	3	1	1	3	3
2	3	3	2	3	2	-	-	-	2	2	3	3	2	3	2
3	3	3	3	2	3	-	-	-	2	2	1	2	2	3	3
4	2	3	3	3	3	-	-	-	2	2	3	2	3	3	2
5	3	3	3	3	3	-	-	-	3	1	3	2	3	2	3
AVg.	2.8	3	2.8	2.8	2.8	-	-	-	2.2	1.8	2.6	2	2.2	2.8	2.6

1 - low, 2 - medium, 3 - high, '-' - no correlation

TIGE3801 **PRINCIPLES OF MANAGEMENT**

L	T	P	C
3	0	0	3

COURSE OBJECTIVES:

- Sketch the Evolution of Management.
- Extract the functions and principles of management.
- Learn the application of the principles in an organization.
- Study the various HR related activities.
- Analyze the position of self and company goals towards business.

UNIT I INTRODUCTION TO MANAGEMENT AND ORGANIZATIONS 9

Definition of Management – Science or Art – Manager Vs Entrepreneur- types of managers-managerial roles and skills – Evolution of Management –Scientific, human relations, system and contingency approaches– Types of Business organization- Sole proprietorship, partnership, company-public and private sector enterprises- Organization culture and Environment – Current trends and issues in Management.

UNIT II PLANNING 9

Nature and purpose of planning – Planning process – Types of planning – Objectives – Setting objectives – Policies – Planning premises – Strategic Management – Planning Tools and Techniques – Decision making steps and process.

UNIT III ORGANISING 9

Nature and purpose – Formal and informal organization – Organization chart – Organization structure – Types – Line and staff authority – Departmentalization – delegation of authority – Centralization and decentralization – Job Design - Human Resource Management – HR Planning, Recruitment, selection, Training and Development, Performance Management, Career planning and management.

UNIT IV DIRECTING 9

Foundations of individual and group behaviour– Motivation – Motivation theories – Motivational techniques – Job satisfaction – Job enrichment – Leadership – types and theories of leadership – Communication – Process of communication – Barrier in communication – Effective communication – Communication and IT.

UNIT V CONTROLLING 9

System and process of controlling – Budgetary and non - Budgetary control techniques – Use of computers and IT in Management control – Productivity problems and management – Control and performance – Direct and preventive control – Reporting.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

CO1: Upon completion of the course, students will be able to have clear understanding of managerial functions like planning, organizing, staffing, leading & controlling.
CO2: Have same basic knowledge on international aspect of management.
CO3: Ability to understand management concept of organizing.
CO4: Ability to understand management concept of directing.
CO5: Ability to understand management concept of controlling.

TEXT BOOKS:

1. Harold Koontz and Heinz Weihrich “Essentials of management” Tata McGraw Hill,1998.
2. Stephen P. Robbins and Mary Coulter, “ Management”, Prentice Hall (India)Pvt. Ltd., 10th Edition, 2009.

REFERENCES:

1. Robert Kreitner and MamataMohapatra, " Management", Biztantra, 2008.
2. Stephen A. Robbins and David A. Decenzo and Mary Coulter, "Fundamentals of Management" Pearson Education, 7th Edition, 2011.
3. Tripathy PC and Reddy PN, "Principles of Management", Tata Mcgraw Hill, 1999.

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	3		-	-	-	1	-	-	-	-	-	-	2	1	1
2	-	1	1	-	-	-	-	-	-	-	-	-	2	1	-
3	1		-	2	-	-	1	-	2	-	1	1	-	-	2
4	-	1	1	1	2	-	-	1	2	-	-	-	1	1	1
5	1		-	-	1	1	-	-	-	3	-	1	1	-	1
AVg.	1.66	1	1	1.5	1.5	1	1	1	2	3	1	1	1.5	1	1.25

TIGE3802 TOTAL QUALITY MANAGEMENT L T P C
3 0 0 3

COURSE OBJECTIVES:

- Teach the need for quality, its evolution, basic concepts, contribution of quality gurus, TQMframework, Barriers and Benefits of TQM.
- Explain the TQM Principles for application.
- Define the basics of Six Sigma and apply Traditional tools, New tools, Benchmarking andFMEA.
- Describe Taguchi's Quality Loss Function, Performance Measures and apply Techniqueslike QFD, TPM, COQ and BPR.
- Illustrate and apply QMS and EMS in any organization.

UNIT I INTRODUCTION 9

Introduction - Need for quality - Evolution of quality - Definition of quality - Dimensions of product and service quality –Definition of TQM-- Basic concepts of TQM - Gurus of TQM (Brief introduction) -- TQM Framework- Barriers to TQM –Benefits of TQM.

UNIT II TQM PRINCIPLES 9

Leadership - Deming Philosophy, Quality Council, Quality statements and Strategic planning- Customer Satisfaction –Customer Perception of Quality, Feedback, Customer complaints, Service Quality, Kano Model and Customer retention – Employee involvement – Motivation, Empowerment, Team and Teamwork, Recognition & Reward and Performance Appraisal-- Continuous process improvement –Juran Trilogy, PDSA cycle, 5S and Kaizen - Supplier partnership – Partnering, Supplier selection, Supplier Rating and Relationship development.

UNIT III TQM TOOLS & TECHNIQUES I 9

The seven traditional tools of quality - New management tools - Six-sigma Process Capability- Bench marking - Reasons to benchmark, Benchmarking process, What to Bench Mark, Understanding Current Performance, Planning, Studying Others, Learning from the data, Using the findings, Pitfalls and Criticisms of Benchmarking - FMEA - Intent , Documentation, Stages: Design FMEA and Process FMEA.

UNIT IV TQM TOOLS & TECHNIQUES II 9

Quality circles – Quality Function Deployment (QFD) - Taguchi quality loss function – TPM – Concepts, improvement needs – Performance measures- COst of Quality - BPR.

UNIT V QUALITY MANAGEMENT SYSTEM 9

Introduction-Benefits of ISO Registration-ISO 9000 Series of Standards-Sector-Specific Standards - AS 9100, TS16949 and TL 9000-- ISO 9001 Requirements-Implementation-Documentation- Internal Audits-Registration-ENVIRONMENTAL MANAGEMENT SYSTEM: Introduction—ISO 14000 Series Standards—Concepts of ISO 14001—Requirements of ISO 14001-Benefits of EMS.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

CO1: Ability to apply TQM concepts in a selected enterprise.

CO2: Ability to apply TQM principles in a selected enterprise.

CO3: Ability to understand Six Sigma and apply Traditional tools, New tools, Benchmarking andFMEA.

CO4: Ability to understand Taguchi's Quality Loss Function, Performance Measures and applyQFD, TPM, COQ and BPR.

CO5: Ability to apply QMS and EMS in any organization.

COs- POs & PSOs MAPPING

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1		3										3	2		3
2						3						3		2	
3					3				3					2	3
4		2			3	2	3	2				3	3	2	
5			3			3	3	2							
AVg.		2.5	3		3	2.6	3	2	3			3	2.5	2	3

TEXT BOOK:

1. Dale H.Besterfiled, Carol B.Michna,Glen H. Bester field,MaryB.Sacre, HemantUrdhwareshe and RashmiUrdhwareshe, “Total Quality Management”, Pearson Education Asia, RevisedThird Edition, Indian Reprint, Sixth Impression,2013.

REFERENCES:

1 Joel.E. Ross, “Total Quality Management – Text and Cases”,Routledge.,2017.
2. Kiran.D.R, “Total Quality Management: Key concepts and case studies, Butterworth –Heinemann Ltd, 2016.
3. Oakland, J.S. “TQM – Text with Cases”, Butterworth – Heinemann Ltd., Oxford, Third Edition,2003.
4. Suganthi,L and Anand Samuel, “Total Quality Management”, Prentice Hall (India) Pvt. Ltd.,2006 .

TIGE3803 ENGINEERING ECONOMICS AND FINANCIAL ACCOUNTING L T P C
3 0 0 3

COURSE OBJECTIVES:

- Understanding the concept of Engineering Economics.
- Implement various micro economics concept in real life.
- Gaining knowledge in the field of macro economics to enable the students to have better
- understanding of various components of macro economics.
- Understanding the different procedures of pricing.
- Learn the various COst related concepts in micro economics.

UNIT I DEMAND & SUPPLY ANALYSIS 9

Managerial Economics - Relationship with other disciplines - Firms: Types, objectives and goals - Managerial decisions - Decision analysis.Demand - Types of demand - Determinants of demand - Demand function – Demand elasticity - Demand forecasting - Supply - Determinants of supply - Supply function -Supply elasticity.

UNIT II PRODUCTION AND COST ANALYSIS 9

Production function - Returns to scale - Production optimization - Least COst input - Isoquants - Managerial uses of production function.
COst Concepts - COst function - Determinants of COst - Short run and Long run COst curves - COst Output Decision - Estimation of COst.

UNIT III PRICING 9

Determinants of Price - Pricing under different objectives and different market structures - Price discrimination - Pricing methods in practice.

UNIT IV FINANCIAL ACCOUNTING (ELEMENTARY TREATMENT) 9

Balance sheet and related concepts - Profit & Loss Statement and related concepts - - Financial Ratio Analysis - Cash flow analysis - Funds flow analysis - Comparative financial statements - Analysis & Interpretation of financial statements.

UNIT V CAPITAL BUDGETING (ELEMENTARY TREATMENT) 9

Investments - Risks and return evaluation of investment decision - Average rate of return - Payback Period - Net Present Value - Internal rate of return.

TOTAL: 45 PERIODS

COURSE OUTCOMES: Students able to

CO1: Upon successful completion of this course, students will acquire the skills to apply the basics of economics and COst analysis to engineering and take economically sound decisions
CO2: Evaluate the economic theories, COst concepts and pricing policies
CO3: Understand the market structures and integration concepts
CO4: Understand the measures of national income, the functions of banks and concepts of globalization
CO5: Apply the concepts of financial management for project appraisal

TEXT BOOKS:

1. Panneer Selvam, R, “Engineering Economics”, Prentice Hall of India Ltd, New Delhi,2001.

2. Managerial Economics: Analysis, Problems and Cases - P. L. Mehta, Edition, 13. Publisher, Sultan Chand, 2007.

REFERENCES:

1. Chan S.Park, “Contemporary Engineering Economics”, Prentice Hall of India, 2011.
2. Donald.G. Newman, Jerome.P.Lavelle, “Engineering Economics and analysis” Engg. Press, Texas, 2010.
3. Degarmo, E.P., Sullivan, W.G and Canada, J.R, “Engineering Economy”, Macmillan, New York, 2011.
4. Zahid A khan: Engineering Economy, "Engineering Economy", Dorling Kindersley, 2012
5. Dr. S. N. Maheswari and Dr. S.K. Maheshwari: Financial Accounting, Vikas, 2009

MAPPING OF COS AND POS:

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1		3								2			1	3	
2		3												2	2
3		2													
4	2	3	3		2								2	3	
5	3	3	3		2								2		2
AVg.	2.5	2.4	3		2					2			1.8	2.6	2

TIGE3804 HUMAN RESOURCE MANAGEMENT L T P C
3 0 0 3

OBJECTIVE:

- To provide knowledge about management issues related to staffing,
- To provide knowledge about management issues related to training,
- To provide knowledge about management issues related to performance
- To provide knowledge about management issues related to compensation
- To provide knowledge about management issues related to human factors consideration and compliance with human resource requirements.

UNIT I INTRODUCTION TO HUMAN RESOURCE MANAGEMENT 9

The importance of human resources – Objective of Human Resource Management - Human resource policies - Role of human resource manager.

UNIT II HUMAN RESOURCE PLANNING 9

Importance of Human Resource Planning – Internal and External sources of Human Resources - Recruitment - Selection – Socialization.

UNIT III TRAINING AND EXECUTIVE DEVELOPMENT 9

Types of training and Executive development methods – purpose – benefits.

UNIT IV EMPLOYEE COMPENSATION 9

Compensation plan – Reward – Motivation – Career Development - Mentor – Protege relationships.

UNIT V PERFORMANCE EVALUATION AND CONTROL 9

Performance evaluation – Feedback - The control process – Importance – Methods – grievances – Causes – Redressal methods.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

CO1: Students would have gained knowledge on the various aspects of HRM
CO2: Students will gain knowledge needed for success as a human resources professional.
CO3: Students will develop the skills needed for a successful HR manager.
CO4: Students would be prepared to implement the concepts learned in the workplace.
CO5: Students would be aware of the emerging concepts in the field of HRM

TEXT BOOKS:

1. Decenzo and Robbins, "Human Resource Management", 8th Edition, Wiley, 2007.
2. John Bernardin. H., "Human Resource Management – An Experimental Approach", 5th Edition, Tata McGraw Hill, 2013, New Delhi.

REFERENCES:

1. Luis R,. Gomez-Mejia, DavidB. Balkin and Robert L. Cardy, “Managing Human Resources", 7th Edition, PHI, 2012.
2. Dessler, "Human Resource Management", Pearson Education Limited, 2007.

COs- POs & PSOs MAPPING

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	2	2	1	2	2	2	1	1	2	1	1	1	1	1	1
2	3	3	2	3	2	2	2	2	3	1	2	1	1	2	1
3	3	3	3	3	3	3	2	2	3	1	2	1	1	2	1
4	3	3	2	3	3	2	2	2	2	1	1	1	1	1	1
5	3	3	1	2	2	2	2	2	2	1	1	1	1	1	1
AVg.	2.8	2.8	1.8	2.6	2.6	2.2	1.8	1.8	2.4	1	1.4	1	1	1.4	1

TIGE3805 KNOWLEDGE MANAGEMENT L T P C
3 0 0 3

COURSE OBJECTIVES:

The student should be made to:

- Learn the Evolution of Knowledge management.
- Be familiar with tools.
- Be exposed to Applications.
- Be familiar with some case studies.

UNIT I INTRODUCTION 9

Introduction: An Introduction to Knowledge Management - The foundations of knowledge management- including cultural issues- technology applications organizational concepts and processes- management aspects- and decision support systems. The Evolution of Knowledge management: From Information Management to Knowledge Management - Key Challenges Facing the Evolution of

Knowledge Management - Ethics for Knowledge Management.

UNIT II CREATING THE CULTURE OF LEARNING AND KNOWLEDGE SHARING 9

Organization and Knowledge Management - Building the Learning Organization. Knowledge Markets: Cooperation among Distributed Technical Specialists – Tacit Knowledge and Quality Assurance.

UNIT III KNOWLEDGE MANAGEMENT-THE TOOLS 9

Telecommunications and Networks in Knowledge Management - Internet Search Engines and Knowledge Management - Information Technology in Support of Knowledge Management - Knowledge Management and Vocabulary Control - Information Mapping in Information Retrieval - Information Coding in the Internet Environment - Repackaging Information.

UNIT IV KNOWLEDGE MANAGEMENT APPLICATION 9

Components of a Knowledge Strategy - Case Studies (From Library to Knowledge Center, Knowledge Management in the Health Sciences, Knowledge Management in Developing Countries).

UNIT V FUTURE TRENDS AND CASE STUDIES 9

Advanced topics and case studies in knowledge management - Development of a knowledge management map/plan that is integrated with an organization's strategic and business plan - A case study on Corporate Memories for supporting various aspects in the process life -cycles of an organization.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon completion of the course, the student should be able to:

CO1: Understand the process of acquiry knowledge from experts
CO2: Understand the learning organization.
CO3: Use the knowledge management tools.
CO4: Develop knowledge management Applications.
CO5: Design and develop enterprise applications.

COs- POs & PSOs MAPPING

COs	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1					1										
2					2								1		
3					2									2	
4				1	1				1					1	
5				1	1				1					1	
AVg.				1	1.4				1				1	1.33	

TEXT BOOK:

1. Srikantaiah, T.K., Koenig, M., “Knowledge Management for the Information Professional” Information Today, Inc., 2000.

REFERENCE:

1. Nonaka, I., Takeuchi, H., “The Knowledge-Creating Company: How Japanese Companies Create the Dynamics of Innovation”, Oxford University Press, 1995.

TIGE3806	INDUSTRIAL MANAGEMENT	L	T	P	C
		3	0	0	3

COURSE OBJECTIVES

1. To study the basic concepts of management; approaches to management; contributors to management studies; various forms of business organization and trade unions function in professional organizations.
2. To study the planning; organizing and staffing functions of management in professional organization.
3. To study the leading; controlling and decision making functions of management in professional organization.
4. To learn the organizational theory in professional organization.
5. To learn the principles of productivity and modern concepts in management in professional organization.

UNIT – I INTRODUCTION TO MANAGEMENT **9**

Management: Introduction; Definition and Functions – Approaches to the study of Management – Mintzberg's Ten Managerial Roles – Principles of Taylor; Fayol; Weber; Parker – Forms of Organization: Sole Proprietorship; Partnership; Company (Private and Public); Cooperative – Public Sector Vs Private Sector Organization – Business Environment: Economic; Social; Political; Legal – Trade Union: Definition; Functions; Merits & Demerits.

UNIT – II FUNCTIONS OF MANAGEMENT - I **9**

Planning: Characteristics; Nature; Importance; Steps; Limitation; Planning Premises; Strategic Planning; Vision & Mission statement in Planning– Organizing: Organizing Theory; Principles; Types; Departmentalization; Centralization and Decentralization; Authority & Responsibility – Staffing: Systems Approach; Recruiting and Selection Process; Human Resource Development (HRD) Concept and Design.

UNIT – III FUNCTIONS OF MANAGEMENT - II **9**

Directing (Leading): Leadership Traits; Style; Morale; Managerial Grids (Blake-Mounton, Reddin) – Communication: Purpose; Model; Barriers – Controlling: Process; Types; Levels; Guidelines; Audit (External, Internal, Merits); Preventive Control – Decision Making: Elements; Characteristics; Nature; Process; Classifications.

UNIT – IV ORGANIZATION THEORY **9**

Organizational Conflict: Positive Aspects; Individual; Role; Interpersonal; Intra Group; Inter Group; Conflict Management – Maslow's hierarchy of needs theory; Herzberg's motivation-hygiene theory; McClelland's three needs motivation theory; Vroom's valence-expectancy theory – Change Management: Concept of Change; Lewin's Process of Change Model; Sources of Resistance; Overcoming Resistance; Guidelines to managing Conflict.

UNIT – V PRODUCTIVITY AND MODERN TOPICS **9**

Productivity: Concept; Measurements; Affecting Factors; Methods to Improve – Modern Topics (concept, feature/characteristics, procedure, merits and demerits): Business Process Reengineering (BPR); Benchmarking; SWOT/SWOC Analysis; Total Productive Maintenance; Enterprise Resource Planning (ERP); Management of Information Systems (MIS).

TOTAL: 45 PERIODS

COURSE OUTCOMES:

At the end of the course the students would be able to

CO1 Explain basic concepts of management; approaches to management; contributors to management studies; various forms of business organization and trade unions function in

professional organizations.

CO2 Discuss the planning; organizing and staffing functions of management in professional organization.

CO3 Apply the leading; controlling and decision making functions of management in professional organization.

CO4 Discuss the organizational theory in professional organization.

CO5 Apply principles of productivity and modern concepts in management in professional organization.

TEXTBOOKS:

1. M. Govindarajan and S. Natarajan, "Principles of Management", Prentice Hall of India, New Delhi, 2009.
2. Koontz. H. and Weihrich. H., "Essentials of Management: An International Perspective", 8th Edition, Tata McGrawhill, New Delhi, 2010.

REFERENCES:

1. Joseph J, Massie, "Essentials of Management", 4th Edition, Pearson Education, 1987.
2. Saxena, P. K., "Principles of Management: A Modern Approach", Global India Publications, 2009.
3. S.Chandran, "Organizational Behaviours", Vikas Publishing House Pvt. Ltd., 1994.
4. Richard L. Daft, "Organization Theory and Design", South Western College Publishing, 11th Edition, 2012.
5. S. TrevisCerto, "Modern Management Concepts and Skills", Pearson Education, 2018.

MAPPING OF COS AND POS:

CO	PO												PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
1	1	1	1	1	1	3	2	3	2	3	1	3	1	1	1
2	1	1	1	1	1	3	2	3	2	3	1	3	1	1	1
3	1	1	1	1	1	3	2	3	2	3	1	3	1	1	1
4	1	1	1	1	1	3	2	3	2	3	1	3	1	1	1
5	1	1	1	1	1	3	2	3	2	3	1	3	1	1	1